

EnOcean Equipment Profiles (EEP)

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 - D2-01-03: Type 0x03 (description: see table)
 - D2-01-04: Type 0x04 (description: see table)
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 - D2-01-06: Type 0x06 (description: see table)
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 - D2-04-04: Type 0x04 (description: see table)
 - D2-04-05: Type 0x05 (description: see table)
 - D2-04-06: Type 0x06 (description: see table)
 - D2-04-07: Type 0x07 (description: see table)
 - D2-04-08: Type 0x08 (description: see table)
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 - D2-04-1B: Type 0x1B (description: see table)
 - D2-04-1C: Type 0x1C (description: see table)
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 - D2-20-00: Type 0x00
 - D2-20-01: Type 0x01
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 - D2-30-00: Type 0x00
 - D2-30-01: Type 0x01 (description: see table)
 - D2-30-02: Type 0x02 (description: see table)
 - D2-30-03: Type 0x03 (description: see table) D2-30-04: Type 0x04 (description: see table)

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- 1) Introduction

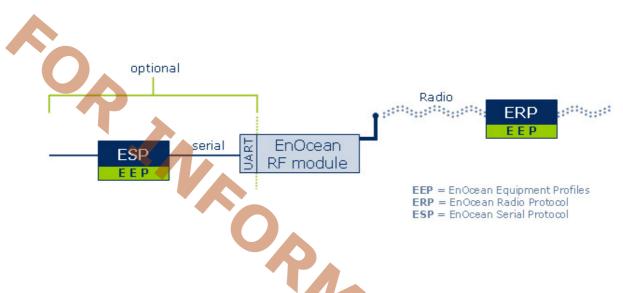
1.1) Terms, Abbreviations

1) Intro	oduction
1.1) Te	rms, Abbreviations
1BS	EnOcean 1 Byte Communication
4BS	EnOcean 4 Byte Communication
BAS	Building Automation System
Choice	Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG
Client	Bidirectional Smart Ack Device
Data	Payload of ERP telegrams or ESP packets
EEP	EnOcean Equipment Profiles
ERP	EnOcean Radio Protocol
ESP	EnOcean Serial Protocol
HTML	Hyper Text Markup Language; HTML can be displayed using a internet browser
MSC	Manufacturer Specific Communication
N/A	Not applicable
ORG	Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface)
RORG	Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice'
RMCC	Remote Management Control Commands
RPC	Remote Procedure Calls
RPS	EnOcean telegram type for Repeated Switch Communication
Smart Ack	Smart Acknowledge EnOcean standard for energy-optimized bidirectional transmission
UART	Universal Asynchronous Receiver Transmitter
VLD	EnOcean Variable Length Data telegram
XML	Extensible Markup Language; designed to transport and store data
XSL	Extensible Stylesheet Language; XML based language to visualize XML (data)

1.2) General

The EnOcean radio protocol (ERP) is optimized to transmit information with utmost reliability using extremely little power while ensuring that the products of customers applying EnOcean technology are compatible with each other. Only the very shortest transmission period (< 1ms) for an EnOcean telegram allows the design of, for example, a battery-free radio switch, which can produce a full radio command with just approx. 50 μ Ws (50 μ J) of energy. At the same time, the reliability of the system increases, as the possibility of data collision is strongly reduced. Every data bit in the radio telegram is essential. For each '0' or '1' state, content descriptions are definied, which must be followed by the sender and the receiver likewise. Depending on the telegram type and the function of the device the user data (payload) is defined in:

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The ERP specification defines the structure of the entire radio telegram. The user data embedded in this structure is defined by the EEP.

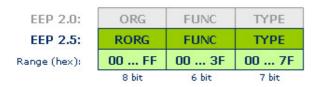
The objective of interoperability is easier to reach with as less profiles as required. Therefore, it is EnOcean Alliance's goal to configure each profile as universally as possible, to target a spectrum of devices in the building automation sector for all manufacturers.

It is of high interest to the EnOcean Alliance that Alliance members verify new devices or newly joined companies verify their products against the existing EEP Profiles and adopt these during testing. Every newly defined EEP would increase diversity and therefore decrease interoperability.

The technical characteristics of a device define three profile elements, which make up the organizational description of all profiles: ONLE

- 1. The ERP radio telegram type (RORG)
- 2. Basic functionality of the data content (FUNC)
- 3. Type of device in its individual characteristics (TYPE)

Therefore, every EEP profile has a number, reflecting these three components:



Every field is represented by a hexadecimal number, where the maximum value is limited by the available bits.

Before the definition of a new profile existing profiles should be checked first for suitability. A new profile is to be defined only if the existing profiles would not be adequate.

Once a new profile is to be developed it should be submitted to the TWG of the EnOcean Alliance. The information to be provided is

- the XML-data, plus
- the profile as text in a pdf-file (the .pdf-data is to be generated from the XML-data)

The TWG will review and ratify the profile. Following the recommendation by the TWG the BoD will disapprove or approve the profile.

When defining a new profile rules, abbreviations and terms as per this document have to be applied.

To maintain the XML-data and the linked pdf-document in a proper way a document maintenance process is defined. For details refer to appendix 3.14 Data + document maintenance process.

1.3) What's new in EEP 2.6?

New RDS profiles:

- F6-02-04 Light and Blind Control ERP2
- F6-04-02 Key Card Activated Switch ERP2
- F6-05-01 Liquid Sensor (mechanic harvester)
- F6-10-01 Window Handle ERP2

New 4BS profiles:

- A5-09-08 Pure CO2 Sensor
- A5-10-20 ROP with Temperature and Set Point with Special Heating States
- A5-10-21 ROP with Temperature, Humidity and Set Point with Special Heating States
- A5-30-03 4 Digital Inputs, Wake and Temperature
- A5-30-04 3 Digital Inputs, 1 Digital Input 8 bits

New VLD profiles:

- D2-01-0A Type 0x0A
- D2-03-10 Mechanical Handle
- D2-04-xx - CO2, humidity, temperature, day/night and autonomy
- D2-30-xx Floor Heating Controls and Automated Meter Reading
- D2-31-xx Automated Meter Reading Gateway
- D2-A0-01 Valve Control

1.4) Telegram types (RORG)

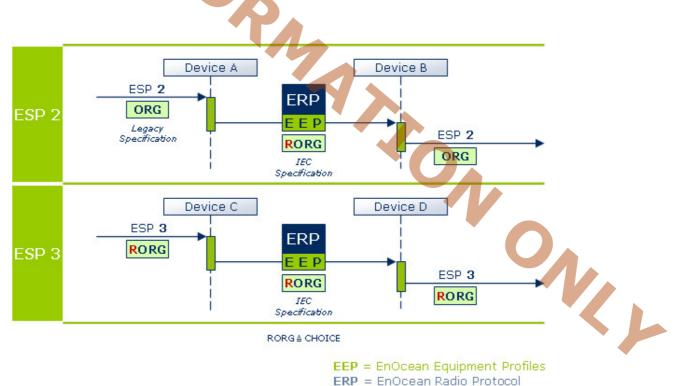
The various **R**adio-Telegram types are grouped **org**anizationally.

The specifications of ERP (EnOcean Radio Protocol) and of ESP (EnOcean Serial Protocol) group telegram types by 'CHOICE' number. 'RORG' at EEP 2.1(2.5) corresponds to 'CHOICE'.

The following RORG are used in EEP 2.5:

Telegram	RORG	ORG	
RPS	F6	05	Repeated Switch Communication
1BS	D5	06	1 Byte Communication
4BS	A5	07	4 Byte Communication
VLD	D2	=RORG	Variable Length Data
MSC	D1	=RORG	Manufacturer Specific Communication
ADT	A6	=RORG	Adressing Destination Telegram
SM_LRN_REQ	C6	=RORG	Smart Ack Learn Request
SM_LRN_ANS	C7	=RORG	Smart Ack Learn Answer
SM_REC	A7	=RORG	Smart Ack Reclaim
SYS_EX	C5	=RORG	Remote Management
SEC	30 🛛	=RORG	Secure telegram
SEC_ENCAPS	31	=RORG	Secure telegram with R-ORG encapsulation

For compatibility reasons, the old ORG values on the serial ESP2 interfaces remain valid. However, on the air interface, each ESP2 telegram is transported with the appropriate RORG (= CHOICE).

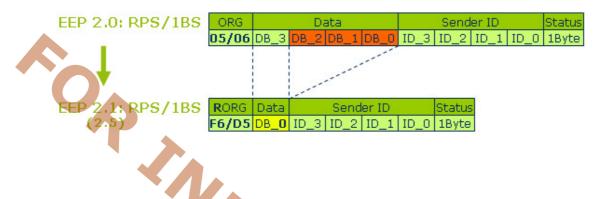


ESP = EnOcean Serial Protocol

1.5) EEP modifications at RPS and 1BS data telegram

Both telegram types carry a one byte payload (DB_0) on the wireless interface (ERP).

EEP 2.0 follows the specification of the serial interface / ESP2, which defines the payload to be carried in DB_3 (see succeeding figure). The trailing bytes, DB_2, DB_1 and DB_0 are marked as `unused'.



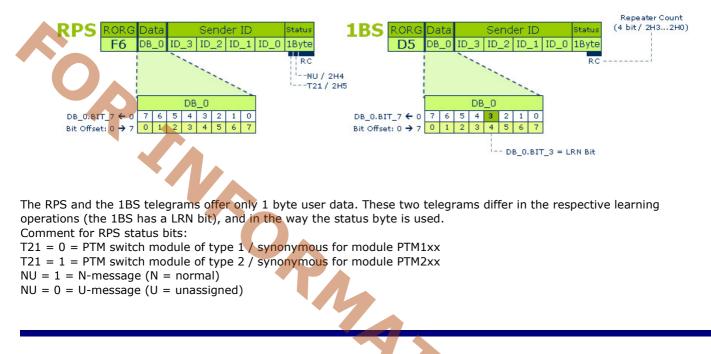
For orthogonal data structural reasons, this deviation will be avoided with EPP 2.1, 2.5 and future versions. The new ESP3 serial interface already respects this.

For reasons of compatibility of end devices, the ESP2 interface remains unaltered, i.e. the DB_0 byte (radio) will continue to be transferred as a DB_3 byte (serial) (including the 3 unused bytes). The conversation has to happen on the application layer as the XML-data structure of EEP 2.1 / 2.5 only refers to the DB_0 byte.

As a consequence of this modification the LRN bit is now described in a row for the 1BS and 4BS telegram types as standardized with the DB_0.BIT_3 position.

1.6) Structure and addressing of the telegram types

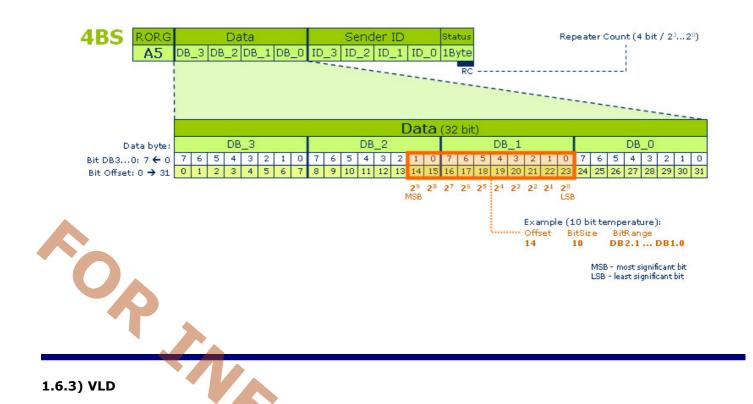
1.6.1) RPS / 1BS



1.6.2) 4BS

A 4BS telegram carries a payload of 4 bytes. The sequence of the 4 data bytes is historically reversed, so that DB_3 appears first and DB_0 last on the radio interface. The bits are addressed in the sequence of the data flow, however (offset). Hence, DB_3.BIT_7 has the offset position 0 and DB_0.BIT_3 (LRN bit) has the offset position 28. The actual content-bits in a byte are not affected by this, i.e., they are described from right (2H0) to left (2H7) in the ascending order.

The example of a 10-bit temperature profile (see below) illustrates the binary valuation of the individual bits, so that a number range from 0 ... 1023 can be addressed.



VLD telegrams carry a variable payload between one and 14 bytes, depending on their design. The teach-in process applies the Smart Ack procedure (see appendices 3.4 and 3.5).

The example following displays a VLD telegram with 6 bytes user data. DB_5.BIT_7 is the first transmitted bit with offset 0.

VLD	RORG	Variable length da	ta Sei	nder ID	Status 🔌	CRC8			
	D2	1 14 bytes	ID_3 ID_	2 ID_1 ID_0	1 byte :	1 byte			
		6 byte example :							
		DB_5	DB_4	DB_3		DB_2	2	DB_1	DB_0
DB_5.BIT_7 ← 0 Bit Offset: 0 → 47	765		5 4 3 2 1 0 10 11 12 13 14 15			7 6 5 4 3		6 5 4 3 2 1 0	7 6 5 4 3 2 1 0 40 41 42 43 44 45 46 47
DICOISEG 0 9 47	0112	3 4 5 6 7 8 9	10111121314	1011101320	21 22 23	2423202712	0/27/30/31/32		

1.7) Teach-in procedures

The 'Teach-in' defines the mutual communication between wireless devices in an 868 (315) MHz radio network. The 'Teach-in' defines to which transmitter(s) a receiver needs to listen to.

For this purpose of a determined relationship between transmitter and receiver each transmitting device has a unique Sender-ID which is part of each radio telegram. The receiving device detects from the Sender-ID whether the device is known, i.e., was already learned, or unknown.

A telegram with unknown Sender-ID is disregarded.

The 'teach-in' process is different for each telegram type (RPS, 1BS, 4BS, Smart Ack), but the following points are valid for all telegrams:

• First, the receiver must be switched into learning mode. Now, the Sender-ID of an arriving telegram is interpreted as an authorized information source and will be stored at the receiver. The further steps of 'teach-in' are defined by the device type or the telegram type. Thus, normal data telegrams or special teach-in telegrams can be used. Frequently, a learn button triggers the teach-in process.

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- The telegram of the respective transmitter should be triggered at least once (by pressing the desired switch rocker or triggering a sensor).
- The bits of the payload (data bytes) can have multiple functions depending on the interpretation set by identification or status bits. Only in the 1BS and 4BS telegram the 'LRN BIT' DB_0.BIT_3 is reserved exclusively and must not be used elsewhere.

The following issues are relevant for a number of application but not mandatory for specification perspective:

- To prevent unwanted devices from being learned the input sensitivity of the receiver is often restricted, and thus an IN-ROOM operation is created. Typically, the device to be learned is placed close by the receiver.
- Dolphin-based transmitters (e.g. TCM 300 or TCM 2x with Dolphin library) can also be switched into the learn-mode via a remote management command. This remote 'teach-in' mode can only be activated within the first 30 min after receiver power-up. To avoid inadvertent learning the transmitter telegrams have to be triggered 3 times within 2 seconds.

For further details on the 'Teach-in' processes refer to appendices 3.1 to 3.6.

1.8) Viewing XML-data

- The XML-file and all the associated files (CSS, DTD, XSL) and the 'graphics' folder must be stored in the same directory.
- The XML-file is best opened using an Internet browser, generating an HTML-view which displays the describing chapters, graphics and data tables.
- Mozilla Firefox V3.6 or upwards is recommended for optimum screen and print view.

The following example illustrates the HTML-view of the XML-data of a 4BS telegram (= payload of 32 bits).

			 		Size = bit Bitrange Data = co	ntent name	description (specially for 4BS)
				1	ShortCut	= logical queries and	dependencies in XML
					Descriptio	on of data field	
					beschipte		/alid Range of data value
	1						Scale of device value
							Jnit of scale value
							Juit of scale value
Offset				ShortCut	Description	Valid Range Scale Unit	
)		DB3.7DB3.0					
3	-	DB2.7DB2.0		the last of the local division of the local	Rel. Humidity (linear)	0250 0100 %	
16	-	DB1.7DB1.0			Temperature (linear)	0250 040 °C	
24		DB0.7DB0.4					ScaleMax
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Ehum:	ScaleMax
						0: Teach-in telegram	
29	1	DB0.2	Not Used (= I	2)		1: Data telegram	RangeMax
30		DB0.2 DB0.1			Availability of the Temperature Sensor		RangeMin
50	1	060.1	1-Sensor	1 SIN	Availability of the reliperature sensor	0: not available	
						1: available	
21	1	080.0	Not Used (=)	2)			1

Data ranges unused are displayed in the table as white rows.

The 'Bit range' column displays the starting-point and the end-point of the respective data.

The 'Valid range', 'Scale' and 'Unit' columns are displayed separately only for measurement values. However, these 3 columns are merged into one if the data comes from an enumeration (enum).

Assuming a linear conversion between the value to be measured and the 'valid range' of data the resolution can be calculated as follows:

Conversion:	Valid Range> Scale
Multiplier =	Scale _{MAX} - Scale _{MIN} Range _{MAX} - Range _{MIN}
Device value	= Multiplier * (rawValue - Range $_{MIN}$) + Scale $_{MIN}$

F6: RPS Telegram

Repeated Switch Communication

F6-ALL: RPS EEP usage on ERP 2

RORG 🧹	F6	RPS Telegram
FUNC	ALL	RPS EEP usage on ERP 2
ТҮРЕ	ALL	ALL

Submitter: EnOcean

ERP 2 (EnOcean Radio Protocol 2) is the radio protocol with FSK encoding. It is compatible on the application level with ERP 1. With ERP 2 all EPPs, Protocols (Security / Smart Acknowledge) can be used as it was before. Only difference are the RPS profiles. The ERP 2 (EnOcean Radio Protocol 2) – does not use the RPS telegrams as ERP 1 did. The biggest difference is the usage of the Status Field. The Status field in ERP 2 is defined as a repeater count field (also other position in the telegram). Other functionalities and fields T21 and NU are not present any more. Therefore a new encoding was developed.

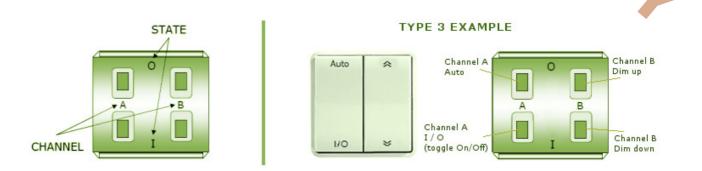
EEP describe an equipment – device - application. The meaning of the data did not change only the coding. The logic and semantic of the application is still the same. So it is defined that RPS profiles on ERP 2 have different coding of the actual telegram data, but the logic is same on ERP 1 and ERP 2.

The new coding is published as new profiles. This is required to keep the same interfaces on the EEP processing (e.g. existing gateways / IP gateways - we do not want have additional information which radio protocol was used – ERP1/ERP2). The exact details are listed below.

The profiles are defined in way that a seamless translation between ERP 1 and ERP 2 vice versa is possible without contextual information, what profile it is in particular.

F6-02: Rocker Switch, 2 Rocker

For clarification reasons the following picture shows a PTM200 transmitter module from EnOcean GmbH which transmits RPS telegrams and is one possibility to be used in applications that require an EEP F6-02-xx. Please note that PTM200 does not support transmission of teach-in telegrams.



The button naming used below is referring to CHANNEL and STATE of the PTM200. Thus "Button AI" means STATE "I" on CHANNEL "A".

There are two different message types, the N-message and the U-message, which need to be identified from the Status Field of an EnOcean RPS telegram. For that reason not only the data bytes are given for each EEP but the T21 and NU bits of the Status Field are listed as well.

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value	
2	1	T21	1	
3	1	NU	1	

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
Dffset)	Size	Bitrange DB0.7DB0.5		R1	Description	Enum: 0: Button AI: "Switch light on" or "Dim light down" or "Move blind closed " 1: Button A0: "Switch light off" or "Dim light up" or "Move blind open " 2: Button BI: "Switch light on" or "Dim light down" or "Move blind closed" 3: Button B0: "Switch light off" or "Dim light up" or "Move
3	1	DB0.4	Energy Bow	EB		blind open" Enum: 0: released 1: pressed
4	3	DB0.3DB0.1	Rocker 2nd action	R2		Enum: 0: Button AI: "Switch light on" or "Dim light down" or "Move blind closed " 1: Button A0: "Switch light off" or "Dim light up" or "Move blind open " 2: Button BI: "Switch light on" or "Dim light down" or "Move blind closed" 3: Button B0: "Switch light off" or "Dim light up" or "Move blind open"
7	1	DB0.0	2nd Action	SA		Enum: 0: No 2nd action 1: 2nd action valid

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Jnit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		Enum: 0: no	button	

					3: 3 or 4 buttons
3	1	DB0.4	Energy Bow	EB	 Enum: 0: released 1: pressed
4	4	DB0.3DB0.0	Not Used (= 0)		

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
ТҮРЕ	02	Light and Blind Control - Application Style 2

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in an I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusf	ield:			_
Offset	Size	Data	Value	
2	1	T21	1	
3	1	NU	1	
Data				

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
D	3	DB0.7DB0.5	Rocker 1st action			Enum: 0: 1: 2: 3:	Button AI: "Switch light on" or blind open " Button A0: "switch light off" or "Move blind closed " Button BI: "Switch light on" or blind open" Button B0: "Switch light off" or	"Dim light down	n" or or "Move
3	1	DB0.4	Energy Bow	EB		Enum: 0: 1:	"Move blind closed" : released pressed	•	
4	3	DB0.3DB0.1	Rocker 2nd action	R2		Enum: 0: 1: 2: 3:	: Button AI: "Switch light on" or blind open " Button A0: "switch light off" or "Move blind closed " Button BI: "Switch light on" or blind open" Button B0: "Switch light off" or "Move blind closed"	"Dim light down	n" or or "Move
7	1	DB0.0	2nd Action	SA		Enum: 0: 1:			

Statusfield:						
Offset	Size	Data	Value			
2	1	T21	1			
3	1	NU	0			

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	IScale	Unit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		Enum:		<u></u>
							no butto 3 or 4	n
						-	outtons	
3	1	DB0.4	Energy Bow	EB		Enum:		
						n :0	eleased	
						1: p	oressed	
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
ТҮРЕ	03	Light Control - Application Style 1

Submitter: Servodan

Definition of Auto, I/O for Rocker switch, Dim control (PTM200)

Statusf	ield:			
Offset	Size	Data	Value	
2	1	T21	1	
3	1	NU	1	

Statusf Offset 2 3 Datafie	Size 1 1	Data Value T21 1 NU 1	Vx	Ò,					
Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	8	DB0.7DB0.0		RA		Enum:			
			action			0x30:	Button A0: Set the controller in a	automatic mod	e
						0x10:	Button A1: Set the controller in r	manually mode	and
						0,10.	toggles between		
							switch light on and su	witch light off	
						0,70,	Button B0:		
						0x70:	Dim light up Button B1:		
						0x50:	Dim light down		

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
ТҮРЕ	04	Light and blind control ERP2

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range Scale Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum	:
						0:	released
						1:	pressed
1	1	DB0.6	Button coding	BC	Signalize button coding	Enum	:
						0:	button
2	2	DB0.5DB0.4	Not Used (= 0))			
4	1	DB0.3	BI	RBI	State I of the rocker B	Enum	:
						0:	not pressed
						1:	pressed

5	1	DB0.2	B0	RB0	State 0 of the rocker B	Enum	:
						0:	not pressed
						1:	pressed
6	1	DB0.1	AI	RAI	State I of the rocker A	Enum	:
						0:	not pressed
						1:	pressed
7	1	DB0.0	A0	RA0	State 0 of the rocker A	Enum	:
						0:	not pressed
						1:	pressed

F6-03: Rocker Switch, 4 Rocker

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
Түре	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusf	ield:			
Offset	Size	Data	Value	
2	1	T21	0	
3	1	NU	1	

Datafield:	

Арриса	tion S	style I is widely	used in EU bu	ut may be	found in othe	r marke	ets as well.		
Statusf Offset 2 3		Data Value T21 0 NU 1	VA						
Datafie									
Offset			Data		Description		Valid Range	Scale	Unit
0	3	DB0.7DB0.5	Rocker 1st action	R1		1: 2: 3: 4: 5: 6: 7:	Button AI: "Switch light on" or " "Move blind closed " Button A0: "Switch light off" or ' blind open " Button BI: "Switch light on" or " "Move blind closed" Button B0: "Switch light off" or ' blind open" Button CI: "Switch light on" or " "Move blind closed " Button C0: "Switch light off" or ' blind open " Button DI: "Switch light on" or " "Move blind closed" Button DI: "Switch light on" or " "Move blind closed" Button DI: "Switch light on" or "	"Dim light up" "Dim light dow "Dim light up" "Dim light dow	or "Move or "Move or "Move or "Move or "Move
3	1	DB0.4	Energy Bow	EB		Enum: 0: 1:			
4	3	DB0.3DB0.1	Rocker 2nd action	R2		Enum: 0:	•		

1

1

			2: 3: 4: 5: 6: 7:	Button BI: "Switch light on" o "Move blind closed Button B0: "Switch light off" o blind open" Button CI: "Switch light on" o "Move blind closed Button C0: "Switch light off" o blind open " Button DI: "Switch light on" o "Move blind closed Button D0:	" r "Dim light up r "Dim light do " r "Dim light up r "Dim light do	″ or "Move wn" or " or "Move
7 1 DB0.0	2nd Action SA		Enum 0: 1:	"Switch light off" o blind open" : No 2nd action 2nd action valid	r "Dim light up	″ or "Move
Statusfield: Offset Size Data Value 2 1 T21 0 3 1 NU 0						
Datafield: Offset Size Bitrange		Data	Sho	ortCut Description	Valid Range	Scale Unit

Statusfield:

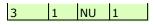
Offset	Size	Data	Value	
2	1	T21	0	1
3	1	NU	0	

Datafie	ld:									
Offset	Size	Bitrange	Da	ita	ShortCut	Description	Valid	Range	Scale L	Jnit
0	3	DB0.7DB0.5	Number of buttons p simultaneously	pressed	R1	0,	Enum: 0: 1: 2: 3: 4: 5: 6: 7:	no Butt pressed 2 butto pressed 3 butto pressed 5 butto pressed 6 butto pressed 7 butto pressed 8 butto	1 ns 1 ns 1 ns 1 ns 1 ns 1 ns 1 ns	
3	1	DB0.4	Energy Bow		EB		Enum: 0: 1:	release pressed		
4	4	DB0.3DB0.0	Not Used (= 0)		•					

-		
RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
ТҮРЕ	02	Light and Blind Control - Application Style 2

A This EEP definition is based on the assumption that a RPS switch module is installed in a I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusf	ield:		
Offset	Size	Data	Value
2	1	T21	0



Offse	t Size	Bitrange	Data	ShortCut	Description		Valid Range Scale Unit
0	3	DB0.7DB0.5	Rocker 1st	R1		Enum:	
			action				Button AI: "Switch light on" or "Dim light up" or "Move
						1:	blind open" Button A0: "Switch light off" or "Dim light down" or "Move blind closed"
						2:	Button BI: "Switch light on" or "Dim light up" or "Move blind open"
K							Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
							Button CI: "Switch light on" or "Dim light up" or "Move blind open"
		17)					Button C0: "Switch light off" or "Dim light down" or "Move blind closed"
			V				Button DI: "Switch light on" or "Dim light up" or "Move blind open"
				D .		7:	Button D0: "Switch light off" or "Dim light down" or "Move blind closed"
3	1	DB0.4	Energy Bow	EB		Enum:	
				1		0:	released
4	-		Deelver 2md	D2			pressed
4	3	DB0.3DB0.1	Rocker 2nd action	R2		Enum:	Button AI:
							"Switch light on" or "Dim light up" or "Move blind open"
							Button A0: "Switch light off" or "Dim light down" or "Move blind closed"
							Button BI: "Switch light on" or "Dim light up" or "Move blind open"
						3:	Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
						4:	Button CI: "Switch light on" or "Dim light up" or "Move blind open"
						5:	Button CO: "Switch light off" or "Dim light down" or "Move blind closed"
						6:	Button DI: "Switch light on" or "Dim light up" or "Move blind open"
						7:	Button D0: "Switch light off" or "Dim light down" or "Move blind closed"
7	1	DB0.0	2nd Action	SA		Enum:	
							No 2nd action

Statusf	ield:		
Offset	Size	Data	Value
2	1	T21	0
3	1	NU	0

Datafie	eld:					
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	3			R1		Enum:
			simultaneously			0: no button pressed
						1: 2 buttons pressed
						2: 3 buttons pressed
						3: 4 buttons pressed
						4: 5 buttons pressed
						5: 6 buttons pressed
						6: 7 buttons pressed
						7: 8 buttons pressed
3	1	DB0.4	Energy Bow	EB		Enum:
						0: released
						1: pressed
4	4	DB0.3DB0.0	Not Used (= 0)			

F6-04: Position Switch, Home and Office Application

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	01	Key Card Activated Switch

Statusfield:						
Offset	Size	Data	Value			
2	1	T21	1			
3	1	NU	1			

Datafield:

IY	PE	01		Key Card /	Activated Swi	Itch	
Insertio	on of l	Key Card gene	rates an N	I-Message,	, take-out a U	J-Message	
Statusf	ield:						
		Data Value					
2	1	T21 1					
3	1	NU 1					
Datafie	١d٠						
Offset		Bitrange	Data	ShortCut	Description	Valid Range Scale Unit	
		DB0.7DB0.0	-			Enum:	
						112: inserted (0x70)	
						Valid Range Scale Unit Enum: 112: inserted (0x70)	
Statusf	ialdu						
		Data Value					F.
2		T21 1					
3		NU 0					

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafie	ld:					
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB0.7DB0.0	Key Card	KC		Enum:
						0: taken out

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
ТҮРЕ	02	Key Card Activated Switch ERP2

Submitter: EnOcean GmbH

When card is inserted field EBO and SOC are both having value 1. When take out, both are having value 0. This coding is required to have a context less translation of RPS profiles between ERP 1 and ERP 2.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range Scale Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum	:
						0:	taken out
						1:	card inserted
1	1	DB0.6	Button coding	BC	Signalize button coding	Enum	:
						0:	button
2	3	DB0.5DB0.3	Not Used (= 0))			
5	1	DB0.2	State of card	SOC	State of the card	Enum	:
						0:	taken out
						1:	card inserted
6	2	DB0.1DB0.0	Not Used (= 0))			

F6-05: Detectors

RORG	F6	RPS Telegram
FUNC	05	Detectors
ТҮРЕ	01	Liquid Leakage Sensor (mechanic harvester)

Submitter: Afriso / EnOcean

Description:

This profile is used for devices detecting leakage. It is commonly placed on ground where a leakage causes damage. The principle is that "paper rings" swell in water and trigger an ECO 200 (generator) based transmitter.

Data exchange

Statusfield:						
Offset	Size	Data	Value			
2	1	T21	1			
3	1	NU	1			

Data ex Directio Address Commu Commu Trigger Teach-i	xchan on: ur sing: unicat unicat even in me		ent-triggered A ction)		nd trigger an ECO 200 (generator) based tr	ansmitter.	
Statusf Offset 2 3 Datafie	Size 1 1	Data Value T21 1 NU 1				0	V,
Offset		Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB0.7DB0.0	Water sensor		Alert signal that the sensor detected water leakage	Wa	ater

F6-10: Mechanical Handle

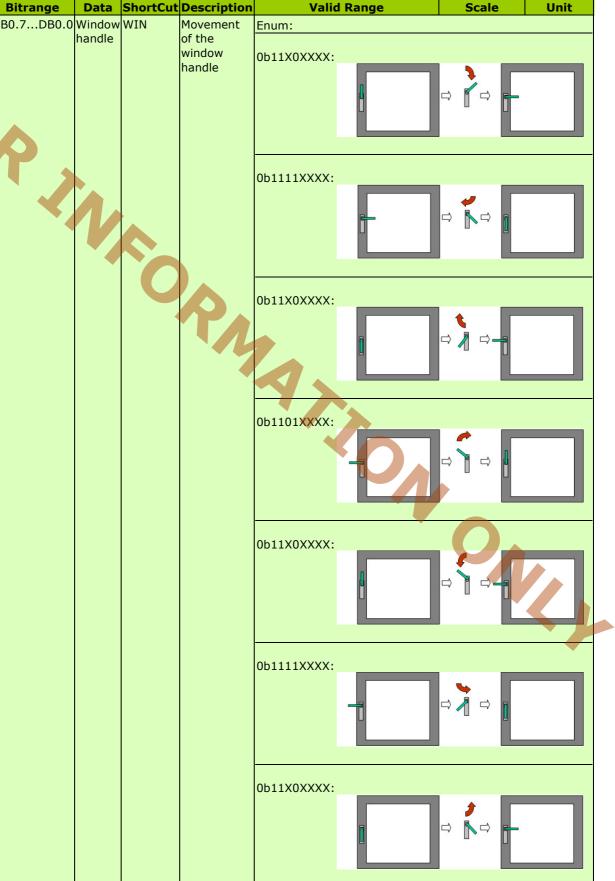
RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
ΤΥΡΕ	00	Window Handle

Submitter: HOPPE AG

The bits marked with 'X' in DB_0 should not be checked. These bits can be '1' or '0' and should not be assumed to be a defined value, because both of them are allowed and not predictable!

Statusfield:						
Offset	Size	Data	Value			
2	1	T21	1			
3	1	NU	0			

Datafield: **Offset** Size Bitrange Data ShortCut Description DB0.7...DB0.0 Window WIN Movement 0 8 of the handle window handle

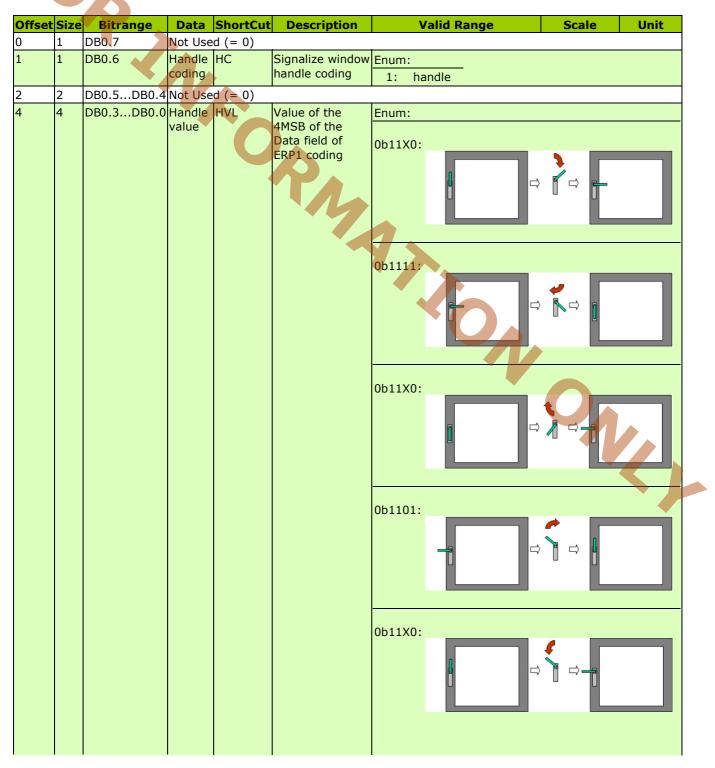


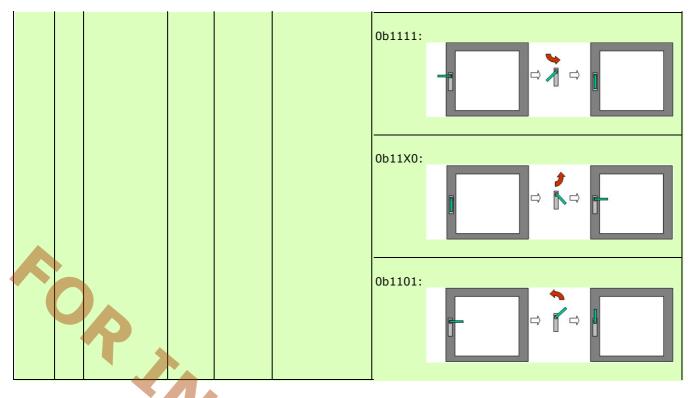
Dec 17, 2013

RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
ТҮРЕ	01	Window Handle ERP2

Submitter: HOPPE AG

DB0.6 - needs to show that RPS/ERP2 has a different coding as RPS/ERP1.





D5: 1BS Telegram

D5-00: Contacts and Switches

RORG	D5	1BS Telegram	
FUNC	00	Contacts and Switches	
ТҮРЕ	01	Single Input Contact	

FU	RG NC PE	D5 00 01	Contact	Telegran s and Swit Input Cont	ches	
fset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
	1	DB0.3	Learn Button	LRN		Enum: 0: pressed 1: not pressed
	1	DB0.0	Contact	со		Enum: 0: open 1: closed
		Telegra	am ure Sensor:	_		0: open 1: closed

A5: 4BS Telegram

A5-02: Temperature Sensors

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	01	Temperature Sensor Range -40°C to 0°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	-400	°C
24	4	DB0.7DB0.4	Not Used (=	0)				

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	02	Temperature Sensor Range -30°C to +10°C

			-	-				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	-30+10	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	m
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

Offeet Size	Ditrongo	Data ChartCut Description
		· · ·
ТҮРЕ	03	Temperature Sensor Range -20°C to +20°C
FUNC	02	Temperature Sensors
RORG	A5	4BS Telegram

						•			
Offset	Size	Bitrange	Data	ShortCut	Description	Valid R	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linea	ir) 2550	-	-20+20)°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit			in telegra elegram	am
29	3	DB0.2DB0.0	Not Used (=	0)					
									0
RO	RG	A5		4BS Tel	egram	7			•
FUI	NC	02	Te	emperatur	e Sensors				
	PE	04	Temperature	Sensor Ra	ange -10°C to +30°	'C			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	04	Temperature Sensor Range -10°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	16	DB3.7DB2.0	Not Used (=	0)			
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	-10+30 °C
24	4	DB0.7DB0.4	Not Used (=	0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-	in telegram
						1: Data te	elegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ΤΥΡΕ	05	Temperature Sensor Range 0°C to +40°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	06	Temperature Sensor Range +10°C to +50°C
Offset Size	Bitrange	Data ShortCut Description

Offset	Size	Bitrange	Data	ShortCu	t Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	+10+50	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram	
FUNC	02	Temperature Sensors	
ТҮРЕ	07	Temperature Sensor Range +20°C to +60°C	

RO FUI TY	NC	A5 02 07			egram re Sensors ange +20°C to +60°C		0	V		
Offset		Bitrange DB3.7DB2.0		<mark>ShortCut</mark> 0)	Description	Valid	Range	Scale	Unit	1.
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	255)	+20+60	°C	
24		DB0.7DB0.4			,			I		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	Teach-	in telegram elegram	<u>1</u>	
29	3	DB0.2DB0.0	Not Used (=	0)						

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	08	Temperature Sensor Range +30°C to +70°C

Offset Size Bitrange ShortCut Description Valid Range Scale Unit Data

0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear) 255()	+30+70 °C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0:	Teach	-in telegram
						1:	Data t	elegram
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	09	Temperature Sensor Range +40°C to +80°C



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	+40+80	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	n
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	0A	Temperature Sensor Range +50°C to +90°C

	<u></u>								
Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	255	.0	+50+90)°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	n:		
						0:	Teach	-in telegrai	m
						1:	Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	0B	Temperature Sensor Range +60°C to +100°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	+60+100	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	-in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ΤΥΡΕ	10	Temperature Sensor Range -60°C to +20°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	-60+20	0°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	m
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	
		4BS Telegram
FUNC	02	Temperature Sensors
TYPE	11	Temperature Sensor Range -50°C to +30°C
o		

Offset	Size	Bitrange	Data	ShortCut		Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	ТМР	Tem	perature (linear)	2550	-50+30	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN	Bit		in telegra elegram	<u>m</u>
29	3	DB0.2DB0.0	Not Used (=	0)		•			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	12	Temperature Sensor Range -40°C to +40°C

	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)	•			
RO	RG	A5		4BS Tel	egram			
FU	NC	02	Те	emperatur	e Sensors			
ТҮ	ΈΕ	12	Temperature	Sensor Ra	ange -40°C to +40°C			
								V.
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit	K.
<mark>Offset</mark> 0		Bitrange DB3.7DB2.0			Description	Valid Range	Scale Unit	N/
			Not Used (=	0)	Description Temperature (linear)		Scale Unit -40+40 °C	K p
0	16	DB3.7DB2.0	Not Used (= <mark>Temperature</mark>	0) TMP	-			
0 16	16 8	DB3.7DB2.0 DB1.7DB1.0	Not Used (= <mark>Temperature</mark> Not Used (=	0) TMP	-			
0 <mark>16</mark> 24	16 8	DB3.7DB2.0 DB1.7DB1.0 DB0.7DB0.4	Not Used (= <mark>Temperature</mark> Not Used (=	0) TMP 0)	Temperature (linear)	2550 Enum:		
0 <mark>16</mark> 24	16 8	DB3.7DB2.0 DB1.7DB1.0 DB0.7DB0.4	Not Used (= <mark>Temperature</mark> Not Used (=	0) TMP 0)	Temperature (linear)	2550 Enum: 0: Teach-	-40+40 °C	

RORG	A5	4BS Telegram			
FUNC	02	Temperature Sensors			
ТҮРЕ	13	Temperature Sensor Range -30°C to +50°C			

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+50	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	m
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG		A5						
FUNC		02		Т	emperature			
ТҮРЕ		14		Temperature	e Sensor Ra	nge -20°C to +60°C	1	
Offset Si	ze B	itrang	e	Data	ShortCut	Description	ľ	Valid Range
0 16	DB3		12 0	Not Used (-	0)			

0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	-20+60 °	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram	
FUNC	02	Temperature Sensors	
ТҮРЕ	15	Temperature Sensor Range -10°C to +70°C	

		110								
FU	NC	02	Temperature Sensors							
TY	PE	15	Temperature	Temperature Sensor Range -10°C to +70°C						
				-			0			
Offset	Size	Bitrange	Data	ShortCut	Description	Valid F	Range	Scale	Unit	
0	16	DB3.7DB2.0	Not Used (=	0)						
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550) .	-10+70	°C	
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0:	Teach-	in telegra	m	
						1:	Data te	elegram		
29	3	DB0.2DB0.0	Not Used (=	0)		•				
	-	•								

5

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	16	Temperature Sensor Range 0°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+80	°C
24	4	DB0.7DB0.4	Not Used (=	0)		_		

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	17	Temperature Sensor Range +10°C to +90°C

									. <u> </u>
Of	fset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		16	DB3.7DB2.0	Not Used (=	0)				
16		8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	+10+90	°C
24		4	DB0.7DB0.4	Not Used (=	0)				
28	;	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							0: Teach-	in telegrar	n
							1: Data t	elegram	
29)	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	18	Temperature Sensor Range +20°C to +100°C

TY	PE	18	Temperature	e Sensor Ra	inge +20°C to +100°	°C		
					17			
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+100	°C
24	4	DB0.7DB0.4	Not Used (=	0)	•			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		-in telegram elegram	_
29	3	DB0.2DB0.0	Not Used (=	0)		•		
RO	RG	A5		4BS Tel	legram			
FUI	NC	02	-	Temperatu	re Sensors			
	PE	19	Temperature	Sensor Ra	ange +30°C to +110°	°C		

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	19	Temperature Sensor Range +30°C to +110°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	+30+110	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	1A	Temperature Sensor Range +40°C to +120°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	16	DB3.7DB2.0	Not Used (=	lot Used (= 0)						
16	8	DB1.7DB1.0	Temperature TMP		Temperature (linear) 2550 +40+1					
24	4	DB0.7DB0.4	Not Used (=	ot Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-	in telegram			
						1: Data t	elegram			
29	3	B DB0.2DB0.0 Not Used (= 0)								

RORG	A5	4BS Telegram						
FUNC	Temperature Sensors							
ТҮРЕ	TYPE 1B Temperature Sensor Range +50°C to +13							
Offset Size	Bitrange	Data ShortCut Description V						

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	16	DB3.7DB2.0	Not Used (=	0)						
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	+50+130)°C		
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram	<u> </u>		
29	3	DB0.2DB0.0	Not Used (=	0)						

RORG	A5	4BS Telegram		
FUNC	02	Temperature Sensors		
ТҮРЕ	20	10 Bit Temperature Sensor Range -10°C to +41.2°C	7	

TY	PE	20	10 Bit Tempe	erature Ser	nsor Range -10°C to -	+41.2°C				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rar	nge	Scale	Unit	
0	14	DB3.7DB2.2	Not Used (=	0)						
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	10230	-1	.0+41.	.2 °C	
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Tea	ach-in	telegrar	n	
						1: Da	ita tele	egram		
29	3	DB0.2DB0.0	Not Used (=	0)						

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
ТҮРЕ	30	10 Bit Temperature Sensor Range -40°C to +62.3°C

Offset Size Bitrange Data ShortCut Description Valid Range Scale Unit

		,								
0	14	DB3.7DB2.2	B3.7DB2.2 Not Used (= 0)							
14	10	DB2.1DB1.0	Temperature	emperature TMP Temperature (linear) 10230 -40+62.3 °C						
24	4	DB0.7DB0.4	B0.7DB0.4 Not Used (= 0)							
28	1	DB0.3	LRN Bit LRNB LRN Bit Enum:							
						0: Teach	-in telegram			
						1: Data t	elegram			
29	3	DB0.2DB0.0	DB0.2DB0.0 Not Used (= 0)							

A5-04: Temperature and Humidity Sensor

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
ТҮРЕ	01	Range 0°C to +40°C and 0% to 100%
Č		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit	
0	8	DB3.7DB3.0	Not Used (=	0)						
8	8	DB2.7DB2.0	Humidity	ним	Rel. Humidity (linear)	0250)	0100	%	
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0250)	0+40	°C	
24	4	DB0.7DB0.4	Not Used (=	ot Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0:	Teach-	in telegr	am	
						1:	Data te	elegram		
29	1	DB0.2	Not Used (=	0)						
30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum:				
						0:	not ava	ailable		
						1:	availab	le		
31	1	DB0.0	Not Used (=	0)						

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A5-06: Light Sensor

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
ТҮРЕ	01	Range 300lx to 60.000lx

A5-0	6: Li	ght Sensor							
RC	RG	A5	4BS Tele	gram					
FU	INC	06	Light Ser	nsor					
T۱	Έ	01	Range 300lx to	60.000lx					
							9		
Offse	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale 🔍	Unit	
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V	
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	30030000	lx	
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	60060000	lx	
24	4	DB0.7DB0.4	Not Used $(= 0)$						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-ir	n telegram		
						1: Data tel	egram		
29	2	DB0.2DB0.1	Not Used (= 0)						
31	1	DB0.0	Range select	RS	Range Enum:				
						0: Range acc. to DB_1 (ILL1)			
							cc. to DB_2 (II	-	

RORG A5 **4BS Telegram**

FUNC	06	Light Sensor
ΤΥΡΕ	02	Range 0lx to 1.020lx

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
3	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
3	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	0510	lx
3	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	01020	lx
ŀ	DB0.7DB0.4	Not Used (= 0)					
-	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-in te	elegram	
					1: Data teleg	ram	
2	DB0.2DB0.1	Not Used $(= 0)$			•		
	DB0.0	Range select	RS	Range	Enum:		
					0: Range acc.	to DB_1 (I	LL1)
					1: Range acc.	to DB_2 (I	LL2)
3		DB3.7DB3.0 DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4 DB0.3 DB0.2DB0.1	DB3.7DB3.0 Supply voltage DB2.7DB2.0 Illumination DB1.7DB1.0 Illumination DB0.7DB0.4 Not Used (= 0) DB0.3 LRN Bit DB0.2DB0.1 Not Used (= 0)	DB3.7DB3.0 Supply voltage SVC DB2.7DB2.0 Illumination ILL2 DB1.7DB1.0 Illumination ILL1 DB0.7DB0.4 Not Used (= 0) DB0.3 LRN Bit LRNB DB0.2DB0.1 Not Used (= 0)	DB3.7DB3.0 Supply voltage SVC Supply voltage (linear) DB2.7DB2.0 Illumination ILL2 Illumination (linear) DB1.7DB1.0 Illumination ILL1 Illumination (linear) DB0.7DB0.4 Not Used (= 0) Used (= 0) DB0.3 LRN Bit LRNB LRN Bit DB0.2DB0.1 Not Used (= 0) Used (= 0) Used (= 0)	DB3.7DB3.0 Supply voltage SVC Supply voltage (linear) 0255 DB2.7DB2.0 Illumination ILL2 Illumination (linear) 0255 DB1.7DB1.0 Illumination ILL1 Illumination (linear) 0255 DB0.7DB0.4 Not Used (= 0) 0 0 0 DB0.3 LRN Bit LRNB LRN Bit Enum: 0: Teach-in teach DB0.2DB0.1 Not Used (= 0) 0 0 0 DB0.0 Range select RS Range Enum: 0: Range acc.	DB3.7DB3.0 Supply voltage SVC Supply voltage (linear) 0255 05.1 DB2.7DB2.0 Illumination ILL2 Illumination (linear) 0255 0510 DB1.7DB1.0 Illumination ILL1 Illumination (linear) 0255 01020 DB0.7DB0.4 Not Used (= 0) Used (= 0)<

RORG	AS		4BS Telegram
FUNC	06		Light Sensor
ТҮРЕ	03	10-t	it measurement (1-Lux resolution) with range 0lx to 1000lx

Offset	Size	Bitrange	Data S	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply S voltage		Supply voltage (linear) 251255: reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6			Illumination (linear) DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx
18	10	DB1.5DB0.4	Not Used $(= 0)$					
28	1	DB0.3	LRN Bit L	.RNB	LRN Bit	Enum: 0: Teach telegr 1: Data		
29	3	DB0.2DB0.0	Not Used $(= 0)$					

A5-07: Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
ТҮРЕ	01	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Supply voltage (OPTIONAL)		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Not Used (= 0)					

16	8	DB1.7DB1.0	PIR Status	PIRS	PIR Status	Enum: 0127: PIR off 128255: PIR on
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0)			
31	1	DB0.0	Supply voltage availability	SVA	Supply voltage availability at DB_3	Enum: 0: Supply voltage is not supported 1: Supply voltage is supported



RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
ТҮРЕ 🧹	02	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8		Supply voltage (REQUIRED)	5	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V		
8	16	DB2.7DB1.0	Not Used (= 0)							
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum:				
						0: Uncertain of occupancy status				
						1: Motion of	detected			
25	3	DB0.6DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-ir	n telegran	n		
						1: Data tel	egram			
29	3	DB0.2DB0.0	Not Used (= 0)							
					•					

RORG	A5	4BS Telegram		
FUNC	07	Occupancy Sensor		
TYPE	03	Occupancy with Supply voltage monitor and 10-bit illumination measurement		

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Supply voltage (REQUIRED)		Supply voltage (linear); 251 – 255 reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear); DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx
18	6	DB1.5DB1.0	Not Used (= 0)	•			•	

24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum: 1: Motion detected 0: Uncertain of occupancy status
25	3	DB0.6DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

A5-08: Light, Temperature and Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
ТҮРЕ	01	Range 0Ix to 510Ix, 0°C to +51°C and Occupancy Button

E.g. for ceiling suspended sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used $(= 0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on		
						1: PIR off		
31	1	DB0.0	Occupancy Button	OCC		Enum:		
						0: Button	pressed	
						1: Button	released	1
				-				

RORG	A5	4BS Telegram	
FUNC	08	Light, Temperature and Occupancy Sensor	
TYPE	02	Range 0Ix to 1020Ix, 0°C to +51°C and Occupancy Button	

							n pressed	
						1: Butto	n released	
						N		
RO	RG	A5		4BS T	elegram			
FU	NC	08	Light, Tem		and Occupancy Sensor			
ТҮ	PE	02			+51°C and Occupancy	Button		
E.g. for Offset		mounted sense	or. Data	ShortCut	Description	Valid Range	Scale Unit	KL
0	8			SVC	Supply voltage (linear)	_	05.1 V	
8	8	DB3.7DB3.0 DB2.7DB2.0		ILL		0255	01020 lx	Ť
o 16	o 8	DB2.7DB2.0 DB1.7DB1.0		TMP		0255	0+51 °C	
24	4		Not Used (= 0)	TIME	Temperature (linear)	0255	0+51 C	
24	1	DB0.7DD0.4	LRN Bit	LRNB	LRN Bit	Enum:		
20	T	00.5				-	in tologram	
							i-in telegram telegram	
20	1	DB0.2	Not Used (- 0)			I. Dala	telegram	
29 30	1 1	DB0.2 DB0.1	Not Used (= 0) PIR Status	PIRS	PIR Status	Enum:		
50	T	DD0.1	PIR Status	PIRS	PIR Status			
						0: PIR o		
24		DD 0 0	.	0.00		1: PIR o	Π	
31	1	DB0.0	Occupancy Button			Enum:		
							n pressed	
						1: Butto	n released	

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
ТҮРЕ	03	Range 0lx to 1530lx, -30°C to +50°C and Occupancy Button

E.g. for outdoor sensor.

Off	set Si	ize	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8		DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01530	lx
16	8		DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0255	-30+50	°C
24	4		DB0.7DB0.4	Not Used (= 0)					
28	1		DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							0: Teach	in telegra	m
							1: Data t	elegram	
29	1		DB0.2	Not Used (= 0)					
30	1		DB0.1	PIR Status	PIRS	PIR Status	Enum:		
							0: PIR on		
							1: PIR of	F	
31	1		DB0.0	Occupancy Button	000		Enum:		
							0: Buttor	pressed	_
							1: Buttor	released	_

A5-09: Gas Sensor

RORG	A5	4BS Telegram		
FUNC	09	Gas Sensor		
ТҮРЕ	01	CO Sensor (not in use)		

							0: Button 1: Button	pressed released	
A5-09): Ga	ıs Sensor		2					1
RO	RG	A5	4BS Tele	gram					
FUI	NC	09	Gas Sen	isor					
ТҮ	PE	01	CO Sensor (no	ot in use)					
Offset			Data	ShortCut	Description		d Range	Scale	Unit
-	8		O I I I		o			0 0 0 0 0	
<u>~</u>	0		Concentration		Concentration	0255		0255	ppm
		DB2.7DB2.0	Concentration	Conc	Concentration (tbd!)				
16	8	DB2.7DB2.0 DB1.7DB1.0	Concentration Temperature	Conc TMP					
<mark>16</mark> 24	<mark>8</mark> 4	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4	Concentration Temperature Not Used (= 0	Conc TMP	Concentration (tbd!) Temperature (linear)	0255			
16 24	<mark>8</mark> 4	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4	Concentration Temperature Not Used (= 0	Conc TMP	Concentration (tbd!)	0255 Enum:		 0,+255	
16 24	<mark>8</mark> 4	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4	Concentration Temperature Not Used (= 0	Conc TMP	Concentration (tbd!) Temperature (linear)	0255 Enum: 0: T	each-in telec	 0+255 gram	
16 24 28	8 4 1	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4 DB0.3	Concentration Temperature Not Used (= C LRN Bit	Conc TMP)) LRNB	Concentration (tbd!) Temperature (linear)	0255 Enum: 0: T	Teach-in teleg Data telegram	 0+255 gram	
16 24 28 29	8 4 1 1 1	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4 DB0.3 DB0.2	Concentration Temperature Not Used (= C LRN Bit Not Used (= C	Conc TMP) LRNB	Concentration (tbd!) Temperature (linear)	0255 Enum: 0: T 1: [0+255 gram	
16 24 28 29	8 4 1 1 1	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4 DB0.3	Concentration Temperature Not Used (= C LRN Bit	Conc TMP)) LRNB	Concentration (tbd!) Temperature (linear)	0255 Enum: 0: T 1: C Enum:	Data telegram	 0+255 gram	• •C
16	8 4 1 1 1	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4 DB0.3 DB0.2	Concentration Temperature Not Used (= C LRN Bit Not Used (= C	Conc TMP) LRNB	Concentration (tbd!) Temperature (linear) LRN Bit	0255 Enum: 0: T 1: C Enum: 0: T	Data telegram	o+255	· °C
16 24 28 29	8 4 1 1 1	DB2.7DB2.0 DB1.7DB1.0 DB0.7DB0.4 DB0.3 DB0.2	Concentration Temperature Not Used (= C LRN Bit Not Used (= C	Conc TMP) LRNB	Concentration (tbd!) Temperature (linear) LRN Bit	0255 Enum: 0: T 1: C Enum: 0: T	Data telegram	 0+255 gram	· °C

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
ТҮРЕ	02	CO-Sensor 0 ppm to 1020 ppm

Submitter: Unitronic AG

Off	set Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
••••		Dialange	Dutu	onorcout	Desemption	tunu nunge	Joane	•••••

0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Concentration	Conc	Gas concentration	0255	01020	ppm
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		
29	1	DB0.2	Not Used $(= 0)$)				
30	1	DB0.1	T-Sensor	TSN		Enum: 0: Temperature available 1: Temperature	Sensor not Sensor availa	ble
31	1	DB0.0	Not Used $(= 0)$)				

-					/
RO	RG	A5		4BS Teleg	Iram
FU	NC 🧃	09		Gas Sen	sor
ТҮ	PE	04		CO2 Sen	sor
				1	
Offset	Size	Bitrang	е	Data	Sh

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear), 0.5 % = 1 bit	0200	0100	%
8	8	DB2.7DB2.0	Concentration	Conc	Concentration (linear), increment = 10 ppm	0255	02550	ppm
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear), increment = 0.2 °C	0255	0+51.0	°C
24	4	DB0.7DB0.4	Not Used (= C))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegram	
						1: Data te	legram	
29	1	DB0.2	H-Sensor	HSN		Enum:		
						0: Humidit availabl	ty Sensor not le	:
						1: Humidit availabl	ty Sensor le	
30	1	DB0.1	T-Sensor	TSN		Enum:		
						0: Temper availabl	ature Sensor le	not
						1: Temper availabl	ature Sensor le	
31	1	DB0.0	Not Used (= 0))				
31	1	080.0	Not Used (= U	<u>, , , , , , , , , , , , , , , , , , , </u>				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
ТҮРЕ	05	VOC Sensor

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	VOC	Conc	VOC Concentration	065535	065535	ppb
16	8	DB1.7DB1.0	VOC ID	VOC_ID	VOC identification	Enum:		
						0: VOCT (to	tal)	
						1: Formalde	ehyde	
						2: Benzene		

	1	1		1		ı ———	
						3:	Styrene
						4:	Toluene
						5:	Tetrachloroethylene
						6:	Xylene
						7:	n-Hexane
						8:	n-Octane
						9:	Cyclopentane
						10:	Methanol
						11:	Ethanol
						12:	1-Pentanol
						13:	Acetone
						14:	ethylene Oxide
						15:	Acetaldehyde ue
						16:	Acetic Acid
						17:	Propionice Acid
						18:	Valeric Acid
						19:	Butyric Acid
						20:	Ammoniac
						22:	Hydrogen Sulfide
		1				23:	Dimethylsulfide
						24:	2-Butanol (butyl Alcohol)
						25:	2-Methylpropanol
							Diethyl ether
						255:	ozone
24	4		Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Not Used (= 0)				
30	2	DB0.1DB0.0	Scale Multiplier	SCM	Scale Multiplier	Enum:	
						0:	0.01
					1:	0.1	
						2:	1
						3:	10

RORG	A5	4BS Telegram	
FUNC	09	Gas Sensor	
ТҮРЕ	06	Radon	

Submitter: NanoSense

					2: 1 3: 10			
RO	RG	A5	4BS Te	elegram				
FU	NC	09	Gas s	Sensor				
ТҮ	PE	06	Ra	idon				
<u>Submit</u> Offset		NanoSense Bitrange	Data	ShortCut	: Description	Valid Range	Scale	Unit
Offset	Size						Scale 01023	
Offset	Size	Bitrange	Radon	Act	Radon activity (regulation is an average of	Range		
Offset 0	Size 10 18	Bitrange DB3.7DB2.6 DB2.5DB0.4 DB0.3	Radon Not Use	Act	Radon activity (regulation is an average of	Range 01023 Enum: 0: Teac		Bq/m3

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
ТҮРЕ	07	Particles

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	9	DB3.7DB2.7	Particles_10	PM10	Dust less than 10 µm (PM10)	0511	0511	µg/m3
9	9	DB2.6DB1.6	Particles_2.5	PM2.5	Dust less than 2.5 µm (PM2.5)	0511	0511	µg/m3
18	9	DB1.5DB0.5	Particles_1	PM1	Dust less than 1 µm (PM1)	0511	0511	µg/m3
27	1	DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in teleg	ram
						1: Data t	elegram	
29	1	DB0.2	PM10 active	PM10a		Enum:		
						0: PM10	not activ	/e
						1: PM10	active	
30	1	DB0.1	PM2.5 active	PM2.5a		Enum:		
						0: PM2.5	not acti	ve
						1: PM2.5	active	
31	1	DB0.0	PM1 active	PM1a		Enum:		
						0: PM1 n	ot active	9
						1: PM1 a	ctive	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
ΤΥΡΕ	08	Pure CO2 Sensor

Submitter: Afriso / EnOcean

Description: Pure CO2 sensor with 8 bit resolution and 0 – 2000ppm.

Address Commu Trigger	on: ur sing: unicat even	nge nidirectional broadcast tion trigger: evo nt: change of va thod: 4BS teac	alue ove					
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rang	je Scale Unit	
0	16	DB3.7DB2.0	Not Use	ed (= 0)				
16	8	DB1.7DB1.0	CO2	CO2	CO2 measurement	t 0255	02000 ppm	
24	4	DB0.7DB0.4	Not Use	ed (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teac	ch-in telegram	
						1: Data	a telegram	
29	3	DB0.2DB0.0	Not Use	ed (= 0)				
A5-10): Ro	oom Operati	ng Par	el				

A5-10: Room Operating Panel

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	01	Temperature Sensor, Set Point, Fan Speed and Occupancy Control

Submitter: Kieback + Peter GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8		Turn-switch for fan speed	FAN		<u>Enum:</u> 210255:	Stage Auto

						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teacl teleg		
						1: Data	telegram	
29	2	DB0.2DB0.1	Not Used (= 0)	_		<u> </u>		
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
						1: Butto	on release	ed
						0: Butto	on pressed	d
	•	7,						

RORG	A5		4BS Telegram					
FUNC	10							
ТҮРЕ	PE 02 Temperature Sensor, Set Point, Fan Speed and Day/Night Control							
				1				

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:		
			speed			210255:	Stage Au	to
						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)		·			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegr	am
						1: Data	telegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum:		
					Day/Night	0: Positio Off	on I / Nig	ht /
						1: Positio On	on O / Da	y 1

RORG	A5	4BS Telegram			
FUNC	10	Room Operating Panel			
TYPE	03	Temperature Sensor, Set Point Control			

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A

16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	0+40 °C		
24	4	DB0.7DB0.4	Not Used (=	Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Tea	ch-in telegram		
						1: Dat	a telegram		
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	04	Temperature Sensor, Set Point and Fan Speed Control

							1	
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Turn-switch for fan	FAN		Enum:		
			speed			210255:	Stage Auto	
			A .			190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					Y X	0: Teacl teleg		
						1: Data	telegram	
29	3	DB0.2DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	05	Temperature Sensor, Set Point and Occupancy Control

						1: Button 0: Button	released	
29 31		DB0.2DB0.1 DB0.0			Occupancy button	Enum:		
20	2			0)		1: Data te	elegram	-
							in telegram	
28		DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		1
24	-	DB0.7DB0.4						1
16		DB1.7DB1.0			Temperature (linear)		0+40 °C	1
8		DB2.7DB2.0		SP	Set point (linear) Min Max+	0255	0255 N/A	
0		DB3.7DB3.0			Description	rana nange	June June	
Offset	_			ShortCut		Valid Range	Scale Unit	
ТҮ	ΈΕ	05	Temperature		Set Point and Occupancy Control			
	NC	10			Operating Panel			
RO	RG	A5		4BS	S Telegram			
29	3	DD0.2DD0.0	Not Used (=	0)	×C			
29	3	DB0.2DB0.0	Not Ucod (-	0)		1.		
						1:	telegram Data telegra	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	06	Temperature Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)					
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Slide switch	SLSW	Slide switch or Slide switch	Enum:		
			0/I		Day/Night	0: Position Off	I / Night	: /
		γ .				1: Position On	O / Day	/
			1.	·				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	07	Temperature Sensor, Fan Speed Control
		PL
A (1) A (1)		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN	.	Enum:	
						210255:	Stage Auto
						190209:	Stage 0
						165189:	Stage 1
						145164:	Stage 2
						0144:	Stage 3
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear) 2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach	in telegram
						1: Data t	elegram
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	08	Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:		
						210255: S	Stage Au	to
						190209: S	Stage 0	
						165189: 5	Stage 1	
						145164: S	Stage 2	
						0144: 5	Stage 3	

		,	1					
8	8	DB2.7DB2.0	Not Used (= 0)			-		
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255	0	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:	
						0:	Teach	-in telegram
						1:	Data t	elegram
29	2	DB0.2DB0.1	Not Used $(= 0)$					
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum	:	
						1:	Buttor	n released
						0:	Buttor	n pressed

	RG	A5		BS Telegi					
	NC	10		n Operatin	-				
TY	PE	09	Temperature Sensor,	Fan Speed	d and Day/Night Control				
		P.							
Offset	Size	Bitrange	Data	ShortCut	Description	Vali Ran		Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN		Enum:			
			speed			-		Stage Au	ito
								Stage 0	
						-		Stage 1	
						-		Stage 2	
						014	14:	Stage 3	
8	8		Not Used (= 0)						
16	8	DB1.7DB1.0		ТМР	Temperature (linear)	2550		0+40	°C
24	4		Not Used (= 0)			_			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						-		-in telegr	am
						1: 1	Data t	telegram	
29	2		Not Used (= 0)						
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum:			
					Day/Night	(Off	on I / Nig	
							Positio On	on O / Da	y /
)		
RO	RG	A5		4BS Te	legram				
	NC	10			ating Panel			K	
ту	ΈΕ	0A	Temperature Sensor.	Set Point	Adjust and Single Input Conta	act			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	0A	Temperature Sensor, Set Point Adjust and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0))				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	2	DB0.2DB0.1	Not Used (= 0))				

31	1	DB0.0	Contact State	CTST	Contact state	Enum:	
						0: closed	
						1: open	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0B	Temperature Sensor and Single Input Contact

Offse	et Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0))				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Contact State	CTST	Contact state	Enum:		
						0: closed		
						1: open		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	0C	Temperature Sensor and Occupancy Control

101		10	INC	Join Opera	ting raner				
TYI	PE	0C	Temperature	Sensor an	nd Occupancy Control				
					4				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2550	0+40	°C	
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	-in telegr elegram		
29	2	DB0.2DB0.1	Not Used (=	0)		•			
31	1	DB0.0	Occupancy	OCC	Occupancy button		n released		K.

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	0D	Temperature Sensor and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)	_	_	_	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				

			,								
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:				
						0:	Teach-in telegram				
						1:	Data telegram				
29	2	DB0.2DB0.1	Not Used (=	Used (= 0)							
31	1	DB0.0	Slide switch	SLSW		Enum	:				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch Day/Night	Enum 0:	: Position I / Night /				
31	1	DB0.0	Slide switch	SLSW							
31	1	DB0.0	Slide switch	SLSW			Position I / Night /				

RORG	A5	4	BS Telegram	
FUNC	10	Roor	n Operating Panel	
TYPE	10	Temperature and Humidity	Sensor, Set Point and Oc	cupancy Control
Ó				
George Cine	Bitrange	Data ShortCut	Description	Valid Range

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A		
8	8	DB2.7DB2.0	Humidity	ним	Rel. Humidity (linear)	0250	0100	%		
16	8	DB1.7DB1.0	Temperature	тмр	Temperature (linear)	0250	0+40	°C		
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-	in telegr	am		
						1: Data te	elegram			
29	2	DB0.2DB0.1	Not Used (=	0)						
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:				
						1: Button	released	1		
						0: Button	pressed			

RORG A5 4BS Telegram FUNC 10 Room Operating Panel TYPE 11 Temperature and Humidity Sensor, Set Point and Day/Night Control			
	RORG	A5	4BS Telegram
TYPE 11 Temperature and Humidity Sensor, Set Point and Day/Night Control	FUNC	10	Room Operating Panel
	ТҮРЕ	11	Temperature and Humidity Sensor, Set Point and Day/Night Control

								1		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit	
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	025	5	0255	N/A	
8	8	DB2.7DB2.0	Humidity	ним	Rel. Humidity (linear)	025	0	0100	%	
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	025	0	0+40	°C	
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:			
						0: Teach-in telegra		m		
								1: Data telegram		
29	2	DB0.2DB0.1	Not Used (=	0)						
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:				
					Day/Night	0:	Positior	n I / Night	t /	
		Off								
						1:	Position	n O / Day	/	
							On			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	12	Temperature and Humidity Sensor and Set Point

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	13	Temperature and Humidity Sensor, Occupancy Control

		15	remperature		uity Sensor, Occupant	Ly Control		
							-	
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data te	elegram	
29	2	DB0.2DB0.1	Not Used (=	0)		•		
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
					72	1: Button	released	<u>1</u>
						0: Button	pressed	
						6		

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
ТҮРЕ	14	Temperature and Humidity Sensor, Day/Night Control	

10		10		ROOTI	Sperating Faller			
TY	PE	14 Temperatu		and Humi	idity Sensor, Day/Night Control			
							1	
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rang	ge Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	ним	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teac	h-in telegra	m
							telegram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:		
		Day/Night		Day/Night	0: Posit Off	ion I / Nigh	t /	
						1: Posit On	ion O / Day	/

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	15	10 Bit Temperature Sensor, 6 bit Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	6	DB2.7DB2.2	Set point		Set point (6 bit, linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	ТМР	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	-in telegram elegram	
29	3	DB0.2DB0.0	Not Used (=	0)	L			

RORG	A5. 4BS Telegram	
FUNC	10 Room Operating Panel	
ТҮРЕ	16 10 Bit Temperature Sensor, 6 bit Set Point Control; Occupancy	y Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	6	DB2.7DB2.2	Set point	SP	Set point (linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	ТМР	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram	<u> </u>
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	OCC	Occupancy button		released	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	17	10 Bit Temperature Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				-	
14	10	DB2.1DB1.0	Temperature	ТМР	Temperature 10 bit (linear)	1023	.0	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:			
						1:	Data t	elegram	
29	2	DB0.2DB0.1	Not Used (=	0)					
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:			
						1:	Buttor	released	
						0:	Buttor	pressed	

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RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	18	Illumination, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8	DB2.7DB2.0	Temp Setpoint	TMPSP	Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan Speed	FAN	Fan Speed	1: S 2: S 3: S 4: S 5: S 6: S	uto peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	te	each-in elegram eata telegra	am
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED	Occupancy enable/disable; if occupancy is disabled ignore DB0.0 (occu. button)	e 1: C	occupancy nabled occupancy isabled	
31	1	DB0.0	Occupancy button	OB		р 1: В	utton ressed utton eleased	
					•	0		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	19	Humidity, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	ним	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Temp Setpoint		Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 2: Speed 3: Speed	1	

	4						
						4:	Speed 3
						5:	Speed 4
						6:	Speed 5
						7:	Off
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Not Used (= 0)	_	-		
30	1	DB0.1	Occupancy button	ОВ		Enum	:
						0:	Button pressed
						1:	Button released
31	1	DB0.0	Occupancy	OED		Enum	:
			enable/disable			0:	Occupancy enabled
\wedge						1:	Occupancy disabled
	0						

RORG	A5 4BS Telegram
FUNC	10 Room Operating Panel
ТҮРЕ	1A Supply voltage monitor, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valie Rang	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage		0 5.0 V linear (super cap); 251-255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set Point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2500	0+40	°C
24	-	DB0.7	Not Used (= 0)					
25 28		DB0.6DB0.4	Fan speed LRN Bit	FAN LRNB	Fan Speed	Enum: 0: Auto 1: Speed 0 2: Speed 1 3: Speed 2 4: Speed 3 5: Speed 4 6: Speed 5 7: Off Enum: 0: Teach-in		
							telegram Data telegra	am
29	1	DB0.2	Not Used (= 0)					
30	1		Occupancy enable/disable	OED		1:	Occupancy enabled Occupancy disabled	•
31	1	DB0.0	Occupancy button	ОВ		1:	Button pressed Button released	

RORG

FUNC	10	Room Operating Panel
ТҮРЕ	1B	Supply Voltage Monitor, Illumination, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	SV	(super cap) 251 – 255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	1: S 2: S 3: S 4: S 5: S 6: S	uto peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	te	each-in elegram ata telegrai	 m
29	1	DB0.2	Not Used (= 0)					
30		DB0.1	Occupancy enable/disable	OED		e 1: C	Occupancy nabled Occupancy isabled	
31	1	DB0.0	Occupancy button	OB		1: B	utton press utton eleased	ed
			<u>.</u>					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	1C	Illumination, Illumination Set Point, Temperature Sensor, Fan Speed and Occupancy Control
		Valid Valid

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination		Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8		Illumination Set Point	ILLSP		0250	01000	lx
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN		Enum:		
						0: Au	ito	
						1: Sp	eed 0	
						2: Sp	eed 1	
						3: Sp	eed 2	
						4: Sp	eed 3	
						5: Sp	eed 4	

						6: Speed 5 7: Off
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Not Used (= 0)			
30	1	DB0.1	Occupancy enable/disable	OED		Enum: 0: Occupancy enabled 1: Occupancy disabled
31	1	DB0.0	Occupancy button	ОВ		Enum: 0: Button pressed 1: Button released

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	1D	Humidity, Humidity Set Point, Temperature Sensor, Fan Speed and Occupancy Control

TYPE 1D			Humidity, Humidity Set F	oint, Tem	perature Sensor, Fan Spee	d and Occupar	ncy Contr	ol
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	ним	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Humidity Set Point	HUMSP	Humidity Set Point (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25 28	3	DB0.6DB0.4 DB0.3	Fan speed LRN Bit	FAN	Fan Speed		1 2 3 4	am
29	1	DB0.2	Not Used (= 0)			1. Data te	elegian	
30	1	DB0.1	Occupancy enable/disable	OED		Enum: 0: Occupa enable 1: Occupa disable	d ancy	
31	1	DB0.0	Occupancy button	ОВ			pressed released	_

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ΤΥΡΕ	1E	see A5-10-1B

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	1F	Temperature Sensor, Set Point, Fan Speed, Occupancy and Unoccupancy Control

Submitter: Distech Controls

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed Enum:				
			speed			210255: Stage auto			
						190209:	Stage 0		
						165189:	Stage 1		
						145164:	Stage 2		
						0144:	Stage 3	_	
8	8	DB2.7DB2.0	Set Point	SP	Set point (linear) Min Max+	0255	0255	N/A	
16	8	DB1.7DB1.0		ТМР	Temperature (linear)	2550	0+40	°C	
24	1	DB <mark>0.7</mark>	Not Used (= 0)			•			
25	1	DB0.6	5 Temperature flag	TMP_F	Temperature flag	Enum:			
						1: Tempe			
					preser				
					0: Tempe				
26	1	DB0.5			Cabussiust flags	absent			
26	6 1 DB0.5 Set point flag	Set point flag	SP_F	Set point flag	Enum:				
					1:Set point present0:Set point absent				
						-	int absen	It	
27	27 1 DB0.4	DB0.4	Fan speed flag	FAN_F	Fan speed flag	Enum:			
						1:Fan speed present0:Fan speed absent			
						0: Fan sp	eed abse	nt	
28	1	DB0.3	LRN Bit	LRNB	LRN Bİt	Enum:			
						0: Teach-in telegram			
							1: Data telegram		
29	1	DB0.2	Not Used (= 0)						
30	1	DB0.1	Unoccupancy	UNOCC	Unoccupancy button	Enum:			
						0: Buttor	pressed		
						1: Button released			
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:			
						0: Button pressed			
						1: Buttor	released	1	
						0	1		
RO	RG	A5	48	S Telegra	m				
		10	Room						

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	20	Temperature and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, User Activity.

This EEP defines a Room Operating Panel that contains a sensor for temperature measurement. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange Direction: unidirectional Addressing: broadcast Communication trigger: event- & time-triggered Communication intervall: 1200 s Trigger event: change of any input signal

Tx delay: n/a Rx timeout: 0 ms (minimum time between two received messages) Teach-in method: 4BS teach-in 2 / Universal teach-in Security Encryption required: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set Point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0250	0+40	°C
24	1	DB0.7	Not Used (= 0)				
25	2	DB0.6DB0.5	mode	SPM BATT	Selection of heating mode Battery change needed	Enum: 0: Room tempe SP 1: Frost protect 2: Automatic co by time prog 3: Reserved Enum: 0: Battery ok 1: Battery low	tion ontrol (e.g. d	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in tele 1: Data telegra		
29	2	DB0.2DB0.1	Not Used (= 0					
31	1	DB0.0	User activity	АСТ	User intervention action	Enum:		
					on device	0: No user action	on	
						1: User interact	tion	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
ТҮРЕ	21	Temperature, Humidity and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, Humidity, User Activity.

This EEP defines a Room Operating Panel that contains sensors for temperature and humidity. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange
Direction: unidirectional
Addressing: broadcast

Data exchange Direction: unidirectional Addressing: broadcast Communication trigger: event- & time-triggered Communication intervall: 1200 s Trigger event: change of any input signal Tx delay: n/a Rx timeout: 0 ms (minimum time between two received messages) Teach-in method: 4BS teach-in 2 / Universal teach-in Security Encryption required: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set Point		Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	ним	Rel. humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	1	DB0.7	Not Used $(= 0)$)				

25	2	DB0.6DB0.5	Set point	SPM	Selection of heating mode	Enum:
			mode			0: Room temperature defined by SP
						1: Frost protection
						 Automatic control (e.g. defined by time program)
						3: Reserved
27	1	DB0.4	Battery state	BATT	Battery change needed	Enum:
						0: Battery ok
						1: Battery low
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0)		
31	1	DB0.0	User activity	ACT	User intervention action on	Enum:
					device	0: No user action
						1: User interaction

A5-11: Controller Status

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	01	Lighting Controller

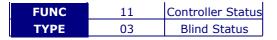
TY	PE	01	Lighting Controller					
				P				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
8	8		Illumination Set Point	ISP	Illumination Set Point (Min Max.) (linear)	0255	0255	N/A
16	8		Dimming Output Level	DIM	Dimming Output Level (Min Max.) (linear)	0255	0255	N/A
24	1	DB0.7	Repeater	REP	Repeater	Enum: 0: disabled 1: enabled		
25	1	DB0.6	Power Relay Timer	PRT	Power Relay Timer	Enum: 0: disabled 1: enabled		
26	1		Daylight Harvesting	DHV	Daylight Harvesting	Enum: 0: disabled 1: enabled		
27	1	DB0.4	Dimming	EDIM	Dimming		ching loa	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: dimming load Enum: 0: Teach-in telegram 1: Data telegram		
29	1	DB0.2	Magnet Contact	MGC	Magnet Contact	Enum: 0: open 1: closed		
30	1	DB0.1	Occupancy	OCC	Occupancy	Enum: 0: unoc 1: occu	cupied pied	_
31	1	DB0.0	Power Relay	PWR	Power Relay	Enum: 0: off	-	

1: on

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	02	Temperature Controller Output

Submitter: Thermokon Sensortechnik GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Control Variable	CVAR	Actual value of controller	0255	0100	%
8	8	DB2.7DB2.0		FAN	Actual value of fan	1: Stag 2: Stag 3: Stag 16: Stag 17: Stag 18: Stag	e 0 Manual e 1 Manual e 2 Manual e 3 Manual e 0 Automa e 1 Automa e 2 Automa e 3 Automa	tic tic
16	8	DB1.7DB1.0	Actual Setpoint	ASP	Occupied: Basic setpoint occupied + Setpoint shift + Sensor offset StandBy: Basic setpoint standBy + Setpoint shift Unoccupied: Basic setpoint unoccupied + setpoint shift	0255	0+51.2	°C
24	1	DB0.7	Alarm	ALR	In case of internal error alarm is set	Enum: 0: No a 1: Alarr		<u> </u>
25	2	DB0.6DB0.5	Controller mode	СТМ	Actual state of controller	Enum: 1: Heat 2: Cooli 3: Off		
27	1		Controller state	CST	Automatic control, or is controlled from another device	Enum: 0: Auto 1: Over	matic ride	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teac	h-in telegra telegram	m
29	1	DB0.2	Energy hold-off	ERH	Stop control if window is opened		nal gy hold-off/ point	
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum: 0: Occu 1: Unoc 2: Stan 3: Frost	cupied dBy	



<u>Submitter: PEHA / infratec</u>

This controller status is specific for blinds, awning and shutter modules. All modules can use this 4BS telegram to send all information about the status, the position and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Blind/shutter	BSP		0100	0100	%	
			pos.						
8	1	DB2.7	Angle sign	AS		Enum:			
						0: Positive sigr	<u>ו</u>		
						1: Negative sig	jn		
9	7	DB2.6DB2.0	Angle	AN	Angle in 2° steps (e.g. 0 = 0^{\circ}, 90 = 180^{\circ})	0180	0360	0	
16	1	DB1.7	Position value	PVF	0 0 7 50 100 7	Enum:			
10	()		flag			0: No Position		hle	
						1: Position valu			
17	1	DB1.6	Angle value	AVF					
17	1		flag	AVI		Enum:			
			lug			0: No Angle va		<u> </u>	
						1: Angle value	avallable		
18	2	DB1.5DB1.4	Error state	ES		Enum:			
						0: No error pre			
						1: End-position	ns are not		
						configured			
						2: Internal faile	ure		
	-					3: Not used			
20	2	DB1.3DB1.2 End-position	nd-position EP		Enum:				
			0: No End-position available						
						1: No End-position reached			
			12.		2: Blind fully o	-			
						3: Blind fully cl	losed		
22	2	DB1.1DB1.0	Status	ST		Enum:			
						0: No Status a	vailable		
						1: Blind is stop	ped		
						2: Blind opens			
						3: Blind closes			
24	1	DB0.7	Service Mode	SM		Enum:			
						0: Normal mod	le		
						1: Service mod		ed (For	
						example for			
25	1	DB0.6	Mode of the	МОТР		Enum:			
			position			0: Normal mod	le:		
						0% Blind fu		0%	
						Blind fully cl	lose		
						1: Inverse mod			
						100% Blind		0%	
						Blind fully cl	lose		
26	2		Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in tel			
						1: Data telegra	am		
29	3	DB0.2DB0.0	Not Used $(= 0)$						

RORG	A5	4BS Telegram
FUNC	11	Controller Status
ТҮРЕ	04	Extended Lighting Status

Submitter: PEHA / infratec

This status is an extended answer of new lighting-controllers. All modules can use this 4BS telegram to send all information about the status and errors of the module, if these data are available.

Offse			Data		Description	Valid Range Scale Unit
)	8	DB3.7DB3.0	Parameter 1	P1		Enum:
						Mode 0: Dimm-Value (0 255)
						Mode 1: R - Red (0 255)
						Mode 2: Energy metering value (MSB
						158) Mada 2: Naturad
	-			D D		Mode 3: Not used
3	8	DB2.7DB2.0	Parameter 2	P2		Enum:
						Mode 0: Lamp operating hours (MSB
						15 8) Mode 1: G - Green (0 255)
						Mode 2: Energy metering value (7 0
						LSB)
						Mode 3: Not used
16	8	DB1.7DB1.0	Parameter 3	P3		Enum:
						Mode 0: Lamp operating hours (7 0
						LSB)
						Mode 1: B - Blue (0 255)
						Mode 2: Unit for energy values:
						Enum: 0 = mW
						0 = MW 1 = W
						2 = kW
						3 = MW
						4 = Wh
						5 = kWh
						6 = MWh
						7 = GWh
						8 = mA
						9 = 1/10 A 10 = mV
						10 - 10 11 = 1/10 V
						12 15 Not used
						Mode 3: Not used
24	1	DB0.7	Service Mode	SM		Enum:
						0: Normal mode
						1: Service mode is activated.
						(For example for maintenance)
25	1	DB0.6	Operating hours	OHF	For Mode 0	Enum:
			flag			0: No lamp operating hours available
						1: Lamp operating hours available
26	2	DB0.5DB0.4	Error state	ES		Enum:
						0: No error present
						1: Lamp-failure
						2: Internal failure
20	1	DD0 0				3: Failure on the external periphery
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
				D 14		1: Data telegram
29	2	DB0.2DB0.1	Parameter Mode	PM		Enum:
						0: 8 Bit Dimmer Value and Lamp
						operating hours
						1: RGB Value
						2: Energy metering value
2.1	1		Chalters	CT		3: Not used
31	1	DB0.0	Status	ST		Enum:
						0: Lighting off
						1: Lighting on

A5-12: Automated meter reading (AMR)

The meter reading is represented by 3 data bytes, a divisor and a flag that indicates it as a cumulative or a current value. A 4 bit info field gives additional information and is TYPE specific.

RORG	A5	4BS Telegram
FUNC	12	Automated meter reading (AMR)
TYPE	00	Counter

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortC	ut Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading	MR	Current value or cumulative counter value	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Measurement channel	СН		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	_
						1: Data t	elegram	
29	1	DB0.2	Data type (unit	:) DT	Current value or	Enum:		
					cumulative counter value	0: Cumul	ative value	L
					value	1: Curren	nt value 1	l/s
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for counter	Enum:		
					value	0: x/1		
						1: x/10		
						2: x/100		
						3: x/1000)	
					1			
	RG	A5		elegram				
FUNC 12 Automated meter reading (AMR)								
ΤY	ΈΕ	01	Ele	ctricity				
<u>Submit</u>	tter: E	EnOcean GmbH						
Offset	Size	Bitrange	Data Sh	ortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter MR	cu	rrent value in W or	016777215 a	according to	according to



RORG	A5	4BS Telegram	
FUNC	12	Automated meter reading (AMR)	
ТҮРЕ	01	Electricity	

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Ra	nge	Scale	Unit
0	24	DB3.7DB1.0				016777		5	according to
			reading		cumulative value in kWh			VIV	DT
24	4	DB0.7DB0.4	Tariff info	TI		015	0	15	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Te	ach-ir	n telegram	
						1: Da	ita tel	egram	
29	1		/	DT	Current value or cumulative	Enum:			
			(unit)		value	0: Cu	mulat	ive value k	Wh
						1: Cu	rrent	value V	v
30	2	DB0.1DB0.0		DIV	Divisor for value	Enum:		_	
			(scale)				1		
							10	_	
						2: x/3	100	_	
						3: x/3	1000		

RORG	A5	4BS Telegram
FUNC	12	Automated meter reading (AMR)
ТҮРЕ	02	Gas

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	24	DB3.7DB1.0	meter reading		Cumulative value in m ³ or Current value in liter/s	0167		according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015		015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	Teach-	in telegram elegram	_
29	1		data type (unit)		Current value or cumulative value	Enum: 0: 1:	Cumula	ative value t value	m³ iter/s
30	2	DB0.1DB0.0	divisor (scale)	DIV	Divisor for value	1: 2:	x/1 x/10 x/100 x/1000		
)	

RORG	A5	4BS Telegram
FUNC	12	Automated meter reading (AMR)
ТҮРЕ	03	Water

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading		Cumulative value in m ³ or Current value in liter/s	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	-
29	1	DB0.2	Data type (unit)		Current value or cumulative value	0: Cumul	ative value n It value L	n³ iter/s
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	Enum: 0: x/1 1: x/10 2: x/100 3: x/100		
A5-13	: Er	ivironmenta	l Applicat	ions				2

A5-13: Environmental Applications

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	01	Weather Station

A receiver that accepts EEP A5-13-01 at teach-in automatically needs to accept telegrams from the same ID that comply to the definitions of EEP A5-13-02 thru EEP A5-13-06. Different telegrams received from that ID need to be distinguished by their 4 bit identifiers.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Dawn sensor	DWS	Dawn sensor	0255	0999	lx
8	8	DB2.7DB2.0	Temperature	ТМР	Outdoor Temp	0255	-40+80	°C
16	8	DB1.7DB1.0	Wind speed	WND	Wind speed	0255	070	m/s
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x1:		

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Day / Night	D/N	Day / Night	Enum:
						0: Day
						1: Night
30	1	DB0.1	Rain Indication	RAN	Rain Indication	Enum:
						0: No Rain
						1: Rain
31	1	DB0.0	Not Used $(= 0)$			

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
ТҮРЕ	02	Sun Intensity
		•

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Sun – West	SNW	Sun - West,linear	0255	0150	klx
8	8	DB2.7DB2.0	Sun – South	SNS	Sun - South,linear	0255	0150	klx
	8	DB1.7DB1.0	Sun – East	SNE	Sun - East,linear	0255	0150	klx
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x2:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					14		ach-in egram	
						1: Da tel	ita egram	
29	1	DB0.2	Hemisphere		0 = north / 1 = south, then swith Sun	Enum:		
					south to Sun North when in southern	0: No	rth	
					hemisphere	1: So	uth	
30	2	DB0.1DB0.0	Not Used (=	0)				
RO	RG	A5		elegram				
FU	NC	13	Environmen	tal Applica	tions			
TY	PE	03	Date I	Exchange				
<u>Submit</u>	ter: E	Elsner electroni	<u>cs</u>			0,	V	
					Description Valid Denne	C l -		
Offset	Size	Bitrange	Data Sh	ortCut	Description Valid Range	Scale	Ur	ΠΟ

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
ΤΥΡΕ	03	Date Exchange

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Not Used	(= 0)				
3	5	DB3.4DB3.0	Day	DY	Day	131	131	N/A
8	4	DB2.7DB2.4	Not Used	(= 0)				
12	4	DB2.3DB2.0	Month	MTH	Month (1->January)	112	112	N/A
16	1	DB1.7	Not Used	(= 0)				
17	7	DB1.6DB1.0	Year	YR	Year (0->Year 2000)	099	20002099	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x3:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in tele	gram	
						1: Data telegrar	n	
29	2	DB0.2DB0.1	Not Used	(= 0)				

31	1	DB0.0	Source	SRC	Source	Enum:	
						0:	Real Time Clock
						1:	GPS or equivalent (e.g. DCF77, WWV)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
ТҮРЕ	04	Time and Day Exchange

Submitter: Elsner electronics

Recommendation: always transmit time in 24 hrs format

Uttse	t Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
)	3	DB3.7DB3.5	Weekday	WDY	Weekday (1 ->	Enum:		
					Monday)	1: Monday		
						2: Tuesday		
	4					3: Wednesday		
						4: Thursday		
						5: Friday		
						6: Saturday		
						7: Sunday		
3	5	DB3.4DB3.0	Hour	HR	Hour	023	023	N/A
3	2	DB2.7DB2.6			t	+		-
10	6	DB2.5DB2.0		MIN	Minute	059	059	N/A
16	2	DB1.7DB1.6						
18	6	DB1.5DB1.0		SEC	Second	059	059	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x4:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegr	am	
						1: Data telegram		
29	1	DB0.2	Time	TMF	Time Format	Enum:		
			Format			0: 24 hours		
						1: 12 hours		
30	1	DB0.1	AM/PM	A/PM	AM or PM	Enum:		
						0: AM		
						1: PM		
31	1	DB0.0	Source	SRC	Source	Enum:		
						0: Real Time Cloc	<	
						1: GPS or equivale	ent (e.g. DC	F77,
						WWV)		

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	05	Direction Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Elevation	ELV	Elevation ("0° -> horizon")	0180	-90+90	0
8	7	DB2.7DB2.1	Not Used	(= 0)				
15	9	DB2.0DB1.0	Azimut		Azimuth ("0° -> True north"; "clockwise")	0359	0359	0
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x5:		

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used	(= 0)			

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	06	Geographic Position Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	DB3.7DB3.4	Latitude(MSB)	LAT(MSB)	Latitude MSB	-	according to LAT(LSB)	according to LAT(LSB)
4	4	DB3.3DB3.0	Longitude(MSB)	· · ·	Longitude MSB	0	according to LOT(LSB)	according to LOT(LSB)
8	8	DB2.7DB2.0	Latitude(LSB)	LAT(LSB)	Latitude LSB	04095	-90+90	0
16	8	DB1.7DB1.0	Longitude(LSB)		Longitude LSB	04095	-180+180	o
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x6:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram gram	
29	3	DB0.2DB0.0	Not Used $(= 0)$					

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
ТҮРЕ	10	Sun position and radiation

Submitter: NanoSense

29	3	DB0.2DB0.0	Not used $(= t$,,				
					1			
RC	RG	A5	4BS Te	legram				
FU	NC	13	Environmenta	-	ons			
T	ΈΕ	10	Sun position	and radiati	on			
		<u>VanoSense</u>				6		
Offse	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	DB3.7DB3.1	Sun Elevation	SNE	Sun Elevation (linear); 91 - 127: reserved	090	090	0
7	1	DB3.0	Day / Night	D/N	Day / Night	Enum: 0: Day 1: Night		1.
8	8	DB2.7DB2.0	Sun Azimuth	SNA	Sun Azimuth 181 - 255: reserved	0180	-90+90	0
16	8	DB1.7DB1.0	Solar Radiation (MSB)	SRA (MSB)	Solar Radiation (MSB)	according to SRA (LSB)	according to SRA (LSB)	according to SRA (LSB)
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x7:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegram legram	
29	3	DB0.2DB0.0	Solar Radiation (LSB)	SRA (LSB)	Solar Radiation (LSB) (Linear); 20012048: reserved	02000	02000	W/m2

A5-14: Multi-Func Sensor

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
ТҮРЕ	01	Single Input Contact (Window/Door), Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	20	DB2.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	in telegra	am
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used $(= 0)$)				
31	1	DB0.0	Contact	СТ		Enum:		
						0b0: Contac	t closed	
						0b1: Contac	t open	

RORG	A5			4BS Telegram
FUNC	14			Multi-Func Sensor
ТҮРЕ	02	Single Input	Conta	ect (Window/Door), Supply voltage monitor and Illumination

Submitter: Lutuo Technology

TY	PE	02	Single Input C	ontact (Wi	ndow/Door), Supply voltage monitor a	and Illuminatio	on	
		<u>utuo Technoloc</u>): Ventilation, L			M			
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telegra 1: Data t		
29	2	DB0.2DB0.1	Not Used $(= 0)$)		•		
31	1	DB0.0	Contact	СТ		Enum: 0b0: Conta 0b1: Conta		

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
ТҮРЕ	03	Single Input Contact (Window/Door), Supply voltage monitor and Vibration

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm , Intrusion (breakage of glass), Calling system

0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	025	0	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	: Teach-in Data tele		n
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Vibration	VIB		Enum: 0b0: 0b1:	No vibra detected Vibration	1	ed
31	1	DB0.0	Contact	СТ			: Contact : Contact		-

A5	4BS Telegram
14	Multi-Func Sensor
04	Single Input Contact (Window/Door), Supply voltage monitor, Vibration and Illumination
	11

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm, Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data te	legram	
29	1	DB0.2	Not Used $(= 0)$)				
30	1	DB0.1	Vibration	VIB		Enum:		
						No vibr 0b0: detecte		
							on detecte	d
						0b1:	on detecte	u
31	1	DB0.0	Contact	СТ		Enum:		
						0b0: Contac	t closed	
						0b1: Contac	t open	

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
ТҮРЕ	05	Vibration/Tilt, Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear);	0250	05.0	V
			voltage		251 – 255 reserved for error code			

8	20	DB2.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Not Used $(= 0$)			
30	1	DB0.1	Vibration	VIB		Enum	:
						0b0:	No vibration detected
							Vibration detected
						0b1:	
31	1	DB0.0	Not Used $(= 0)$)			

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
ТҮРЕ	06	Vibration/Tilt, Illumination and Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegrar elegram	<u>n</u>
29	1	DB0.2	Not Used $(= 0)$)				
30	1	DB0.1	Vibration	VIB		Enum: No vibr 0b0: detecte Vibratio 0b1:		d
31	1	DB0.0	Not Used $(= 0)$)				

A5-20: HVAC Components

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
ТҮРЕ	01	Battery Powered Actuator (BI-DIR)

<u>Submitter: Kieback + Peter GmbH</u>

DIRECTION-1 = Transmit mode: Message from the actuator to the controller DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Current Value	CV	Current value	0100	0100	%
8	1	DB2.7	Service On	SO	Service On	Enum: 1: on	_	

ONC L

9	1	DB2.6	Energy input enabled	ENIE	Energy input enabled	Enum:
						1: true
10	1	DB2.5	Energy Storage	ES	Energy storage sufficiently	Enum:
					charged	1: true
11	1	DB2.4	Battery capacity	BCAP	Battery capacity; change	Enum:
					battery next days	0: true
12	1	DB2.3	Contact, cover open	ссо	Contact, cover open	Enum:
						1: true
13	1	DB2.2	Failure temperature	FTS	Failure Temperature	Enum:
			sensor, out off range		sensor, out off range	1: true
14	1	DB2.1	Detection, window open	DWO	Detection, window open	Enum:
						1: true
15	1	DB2.0	Actuator obstructed	ACO	Actuator obstructed	Enum:
						1: true
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255 0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in
						telegram
						1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			
DIREC	TION	-7				
		2				

DIRECTION-2

DIRECT	TON-	2						
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		or Temperature Setpoint	SP	Valve position 0100% in combination with compatible classic controllers the actuator used DB_3; Temperature set point: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).		0100 or +40	°C
8	8	DB2.7DB2.0	Temperature from RCU	ТМР	Temperature actual from RCU = 000 (Room controller-unit), see DB1.0 Maintenance mode ("service on"): DB_2.BIT_5: energy memory sufficiently charged =1 DB_2.BIT_4: battery capacity changing battery in the next days, need changing batteries = 0 Status feedback signal (service on, DB_2.BIT_7	2550	0+40	°C
16	1		Run init sequence	RIN	The limit switching measures the travel and signals when an end position has been reached. This end position (valve zero point) in the actuator is stored.	Enum: 1: tru	le	
17	1	DB1.6	Lift set	LFS	Initialization, adjustment to the valve stroke. The Initialization is switched after receiving the command. The valve is completely opened and closed during initialization.	Enum: 1: tru	le	

		1	1	1		
18	1	DB1.5	Valve open / maintenance	VO	After receiving an operation command, the actuator moves the valve in direction open or close. when reaching the end position, an automatic switch-off procedure is started. In service mode the valve can be set to open or closed always.	Enum: 1: true
19	1	DB1.4	Valve closed	VC	valve closed	Enum: 1: true
20	1	DB1.3	Summer bit, Reduction of energy consumption	SB	The radio communication between the actuator and the controller is restricted, sleep mode is extended. This functionality can be used for battery powered actuators.	Enum: 1: true
21	1	DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	Enum: 0: Valve position (0-100%). Unit respond to controller.
		P)				1: Temperature set point 040°C. Unit respond to room sensor and use internal PI loop.
22	1	DB1.1	Set point inverse	SPN	Valve set point can be sent to the actuator normal or inverted. The selection is done by DB_1.Bit1. The implementation is done and is controlled in the actuator with DB_3. This function is used in dependence on the type of valve.	Enum: 1: true
23	1	DB1.0	Select function	RCU	RCU or "Service on": After transmitting the command to the actuator, it can be send from the controller or a service device, the actuator sends a status feedback signal (service on, DB_2.BIT_7).	Enum: 0: RCU 1: service on
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	02	Basic Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

Basic Actuator can be used by any manufacturer for linear or rotary actuator.

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator. To use with a BAS/Gateway system; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual Value		Actual value (linear); can be a linear or rotation motion.	0100	0100	%
8	14	DB2.7DB1.2	Not Used	(= 0)				

N.

22	1		Set point inverse		Set point inverse (Needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer	Enum: 1:	true
24	4	DB0.7DB0.4	Not Used	(= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used	(= 0)			

DIRECTION-2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Valve Set point	VSP	Valve set Point (linear)	0100	0100	%
8	8	DB2.7DB2.0	Not Used	d (= 0)				
16	6	DB1.7DB1.2	Not Used	d (= 0)				
22	1	DB1.1	Set point inverse		"Set point inverse " needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer. It can send a command to invert functionality of the unit. In some instance some equipment might need 100% to represent fully extracted, in other fully retracted.	Enum: 1: 1	true	
23	5	DB1.0DB0.4	Not Used	d (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1:	Teach-in telegram Data telegram	<u> </u>
29	3	DB0.2DB0.0	Not Used	d (= 0)		•		

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
ТҮРЕ	03	Line powered Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

DIRECTION-1 = Transmit mode: Message from the actuator to the controller. DIRECTION-1 = Transmit mode: Message from the actuator to the controller. DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECT	TON-	1						
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Uni
0	8	DB3.7DB3.0	Actual valve	AV	Actual valve	0100	0100	%
8	8	DB2.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	ТМР	Temperature (linear)	0255	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

DIRECTION-2

Offset Size Bitrange Data ShortCut	Description	Valid Range	Scale	Unit
------------------------------------	-------------	----------------	-------	------

1

hit

0	8	DB3.7DB3.0	Actuator or Temperature Setpoint	ATS	Actuator Setpoint: in combination with BAS/Gateway controllers. Temperature Setpoint: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).	255	r 0100 or +40	°C
	8		from RCU	TMPRC	Temperature actual from RCU = 0b0 (Room controller-unit)	2550	0+40	°C
16	5	DB1.7DB1.3	Not Used $(= 0)$)				
21	1	DB1.2	Set Point Selection Set Point Inverse	SPS	Set Point Selection for DB3 Valve set point can be sent to the actuator normal or inverted through BAS/Gateway controller. The selection is done by DB_1.Bit1. in the actuator with DB_3. This function is used in dependence on	(0 re 1: Te Se 0. re se	ctuator Setp -100%); Ur spond to introller. emperature etpoint +40°C; Ur spond to ro insor and us ternal PI loc	nit nit om se
					the type of valve.			
23	5	DB1.0DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	ach-in teleg ata telegran	
29	3	DB0.2DB0.0	Not Used $(= 0)$)				
			,					

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
ТҮРЕ	10	Generic HVAC Interface (BI-DIR)

Submitter: Intesis Software SL

Functions: Mode, Vane Position, Fan Speed, Sensors and On/Off: With this EEP plus the already existing EEP A5-10-03 and A5-20-11 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Ra	ange	Scale	Unit
0	8	DB3.7DB3.0	Mode	MD	The modes are the same as in KNX	Enum:			
					and LON allowing a more transparent integration with this protocols and it has plenty of free positions for future	0:	Auto		
						1:	Heat		
					expansion	2:	Morni	ng Warn	nup
						3:	Cool		
						4:	Night	Purge	
						5:	Preco	ol	
						6:	Off		
						7:	Test		
						8:	Emerg	gency He	eat

						9: Fan only
						10: Free cool
						11: Ice
						12: Max heat
						13: Economic
						heat/cool
						14: Dehumidification
						(dry) 15: Calibration
						16: Emergency cool 17: Emergency
						17: Emergency steam
						18: max cool
						19: Hvc load
						20: no load
						reserved
						2130:
						31: Auto Heat
						32: Auto Cool
						reserved
						33254:
						255: N/A
8	4	DB2.7DB2.4		VPS		Enum:
			position			0: Auto
						1: Horizontal
						2: Pos2
						3: Pos3
						4: Pos4
						5: Vertical
						6: Swing
						Reserved
						710:
						11: Vertical swing
						12: Horizontal swing
						13: Horizontal and
						vertical swing
						14: Stop swing
10				FANGE		15: N/A
12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14, 1 is the lowest fan speed allowed by the	Enum:
						0: Auto
					AC and from there it increments with the value of this variable. Typically AC	Up to 14 fan
					AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any	Up to 14 fan 114: speeds being 1 the
					AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the	Up to 14 fan 114: speeds being 1 the lowest
					AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher	Up to 14 fan 114: speeds being 1 the
16	8	DB1 7 DB1 0	Control	CVAP	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A	Up to 14 fan 114: speeds being 1 the lowest 15: N/A
16	8	DB1.7DB1.0		CVAR	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher	Up to 14 fan 114: speeds being 1 the lowest
			variable		AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A	Up to 14 fan 114: speeds being 1 the lowest 15: N/A
24	4	DB0.7DB0.4	variable Not Used (= 0)	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 %
24			variable		AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum:
24	4	DB0.7DB0.4	variable Not Used (= 0)	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram
16 24 28 29	4	DB0.7DB0.4	variable Not Used (LRN Bit Room	= 0)	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum:
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit Room	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto LRN Bit The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit Room	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action)
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit Room	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto LRN Bit The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action) 2: Unoccupied (action
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit Room	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto LRN Bit The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action) 2: Unoccupied (action performed)
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit Room	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto LRN Bit The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action) 2: Unoccupied (action performed)
24 28	4	DB0.7DB0.4 DB0.3	variable Not Used (LRN Bit Room	= 0) LRNB	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto LRN Bit The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action) 2: Unoccupied (action performed) 3: Off (no occupancy
24 28 29	4 1 2	DB0.7DB0.4 DB0.3 DB0.2DB0.1	variable Not Used (LRN Bit Room occupancy	= 0) LRNB RO	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action) 2: Unoccupied (action performed) 3: Off (no occupancy and no action)
24 28 29	4 1 2	DB0.7DB0.4 DB0.3 DB0.2DB0.1	variable Not Used (LRN Bit Room occupancy	= 0) LRNB RO	AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A Control variable; value 255 = auto	Up to 14 fan 114: speeds being 1 the lowest 15: N/A 0100, 255 0100 % Enum: 0: Teach-in telegram 1: Data telegram Enum: 0: Occupied 1: StandBy (waiting to perform action) 2: Unoccupied (action performed) 3: Off (no occupancy and no action) Enum:

DIRECT						
Offset			Data	ShortCut		Valid Range Scale Unit
)	8	DB3.7DB3.0	Mode	MD	The modes are the same as in KNX	Enum:
					and LON allowing a more transparent integration with this protocols and it	0: Auto
					has plenty of free positions for future	1: Heat
					expansion	2: Morning Warmup
						3: Cool
						4: Night Purge
						5: Precool
						6: Off
						7: Test
						8: Emergency Heat
						9: Fan only
						10: Free cool
						11: Ice
						12: Max heat
						13: Economic
						heat/cool
	4					14: Dehumidification
						(dry)
						15: Calibration
						16: Emergency cool
						17: Emergency steam
						18: max cool
						19: Hvc load
						20: no load
						reserved 2130:
				· · · · · ·	NA.	31: Auto Heat
						32: Auto Cool
						reserved
						33254:
						255: N/A
	4	DB2.7DB2.4	Vane	VPS		Enum:
	•	002.7002.1	position	VI S		0: Auto
						1: Horizontal
						2: Pos2
						3: Pos3
						4: Pos4
						5: Vertical
						6: Swing
						Reserved
						710:
						11: Vertical swing
						12: Horizontal swing
						13: Horizontal and
						vertical swing
						14: Stop swing
						15: N/A
.2	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1	Enum:
					is the lowest fan speed allowed by the	
					AC and from there it increments with	Up to 14 fan speeds
					the value of this variable. Typically	114: being 1 the lowest
					AC units have up to 5-6 speeds. Any	15: N/A
					speed higher than the maximum the AC allows would set it to the higher	
					speed. 0 is auto and 15 is N/A	
.6	8	DB1.7DB1.0	Control		Control variable (linear); value 255 =	0100, 255 0100 %
-						
			variable		auto	

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:			
						0:	Teach-in telegram			
						1:	Data telegram			
29	2	DB0.2DB0.1	Room	RO	Room occupancy	Enum	:			
			occupancy			0:	Occupied			
					1:	StandBy (waiting to				
						perform action)				
						2:	Unoccupied (action performed)			
						3:	Off (no occupancy and no action)			
31	1	DB0.0	On/Off	O/I	On/Off	Enum	:			
						0:	off			
						1:	on			
	1: on									

RORG	A5		4BS Telegram
FUNC 🧹	20		HVAC Components
ТҮРЕ	11	•	Generic HVAC Interface – Error Control (BI-DIR)

Submitter: Intesis Software SL

Error Control: AC Error Code, Error States and Disablements. With this EEP plus the already existing EEP A5-10-03 and A5-20-10 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

DIRECT	'ION-	1

Offset	Size	Bitrange	Data	ShortCut	Description	Vali Rang	- S	cale	Unit
0	23	DB3.7DB1.1	Not Used (= 0)						
23	1		External disablement	EXDS	External disablement	Enum: 0: Not disabled 1: Disabled			d
24	4	DB0.7DB0.4	Not Used (= 0)	-	· · · · · · · · · · · · · · · · · · ·				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Teach- telegra Data te	am	am
29	1		Disable remote controller	DRC	Disable remote controller (When in receive mode it controls if the interface overwrites the remote controller commands.)	1:	Enable contro Disable Remot contro	ller e .e	iote
30	1	DB0.1	Window contact	wc	Window contact	1:	Windo openeo Windo closed	d ws	
31	1	DB0.0	Not Used (= 0)						

DIRECTION-2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Error Code		Error Code (DB3 HI,DB2 LO); generated by A.C.	065535	065535	N/A
16	4	DB1.7DB1.4	Reserved	RES	Reserved (0b0000)	Enum: : Reserved		

2	0	1	DB1.3	Other disablement	OD	Manufacturer defined. It is just to provide an extra "disablement signal" that could be used for other devices. People would not have to change anything then as this is already an established "signal"	Enum: 0: 1:	: Not disabled Disabled
2	1	1	DB1.2	Window contact disablement	WCD	Window contact disablement	Enum: 0: 1:	: Not disabled Disabled
2	2	1	DB1.1	Key card disablement	KCD	Key carddisablement	Enum: 0: 1:	: Not disabled Disabled
2	3	1	DB1.0	External disablement	ED	External disablement	Enum: 0: 1:	: Not disabled Disabled
2	4	4	DB0.7DB0.4	Not Used $(= 0)$)			
2	8	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
							0:	Teach-in telegram
							1:	Data telegram
2	9	1	DB0.2	Remote	RCD	Remote controller Disablement	Enum	:
				controller Disablement		(In transmit it sends the status of this parameter. If the manufacturer doesn't support this option, it will	0:	Remote controller enabled
						send allways 0, no matter what it receives.)	1:	Remote controller disabled
3	0	1	DB0.1	Window	wc	Window contact	Enum	
				contact			0:	Windows opened
							1:	Windows closed
3	1	1	DB0.0	Alarm State	AS	Alarm State	Enum	:
							0:	Ok
							1:	Error

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
ТҮРЕ	12	Temperature Controller Input

31	1	DB0.0	Alarm State	AS	Alarm	State		Ok Error	
					<				
RO	RG	A5	4BS Te	elegram					
FU	NC	20	HVAC Co	mponent	ts				
ТҮ	Έ	12	Temperature (Controlle	r Input				
Submi	tter: [:]	Thermokon Sen	sortechnik Gm	bH			V		
Offset	Size	Bitrange	Data	9	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Control Variab override	le (CV	Actual value for controller	0255	0100	%
8	8	DB2.7DB2.0	FanStage over	ride F	ANOR	FanStage override	Enum:		
							0: Stage	0	
							1: Stage		
							2: Stage 2		
							3: Stage 3	3	
							31: auto		
10	0		<u> </u>				255: not ava		
16	8	DB1.7DB1.0	Setpoint shift		SPS	Actual set point could be shifted	0255	-10+10	°К
24	1	DB0.7	Fan override	F	ANOR		Enum:		_
							0: Automa		_
							1: Overric	le Fan DB2	
25	2	DB0.6DB0.5	Controller mod	de O	СТМ		Enum:		
							0: Auto m		
							1: Heating		
							2: Cooling]	
							3: Off		

27	1	DB0.4	Controller state	CST	Controller state	Enum:
						0: Automatic
						1: Override control variable DB3
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Energy hold-off / Dew point		Energy hold-off / Dew	Enum:
					point	0: Normal
						1: Energy hold-off/ Dew point
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum:
						0: Occupied
						1: Unoccupied
						2: StandBy
						3: Frost
	0					

A5-30: Digital Input

RORG	A5	4BS Telegram
FUNC	30	Digital Input
ТҮРЕ	01 Sing	le Input Contact, Battery Monitor

-								
Offse	t Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale U	Init
0	8	DB3.7DB3.0	Not Used $(= 0)$					
8	8	DB2.7DB2.0	Supply voltage	SVC	Supply voltage (linear)	Enum:		
						0120: Ba	ttery LOW	
						121255: Ba	ttery OK	
16	8	DB1.7DB1.0	Input State	IPS	Input State	Enum:		
						0195: Co	ntact close	ed
						196255: Co	ntact open	ı
24	4	DB0.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegram	
						1: Data tele	egram	
29	3	DB0.2DB0.0	Not Used $(= 0)$)				
RC	DRG	A5	4BS Telegr	am				
	JNC	30	Digital Inp					
-	PE	02	Single Input C					
	F E	02	Single Input C	JILACL				

RORG	A5	4BS Telegram
FUNC	30	Digital Input
ТҮРЕ	02	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	ot Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-i	n telegr	am
						1:	Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	= 0)	•				
31	1	DB0.0	Input State	IPS	Input State	Enum:			
						0:	Contact	closed	
						1:	Contact	open	

RORG	A5	4BS Telegram
FUNC	30	Digital Input
ТҮРЕ	03	4 Digital Inputs, Wake and Temperature

Submitter: Afriso / EnOcean

Description:

This is used for universal modules with 4 digital inputs and a room temperature. The wake input signal of the device is provided to show the telegram transmission trigger. The application meaning and exact data interpretation of the digital channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional

Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: wake event – application dependent

Teach-in method: 4BS teach-in 2

Appendix:

D1.4 – The Status of Wake signalizes the status of the WAKE PIN which has a special meaning in an ultra low application. Usually, by a status change of this input the module is triggered to perform a predefined operation.

Applications using this profile:

- water sensor conductive Wake Status = 0 (water detected)
- pressure gauge with minimum or maximum (wake signal, configurable if min or max)
- indication and individual switching points (digital channels show different areas)

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)					
8	8	DB2.7DB2.0	Temperature	ТМР	Temperature (linear)	2550	040	°C
16	3	DB1.7DB1.5	Not Used (= 0)					
19	1	DB1.4	Status of Wake	WA0	Value of wake signal	Enum:		
						0: Low		
						1: High		
20	1	DB1.3	Digital Input 3	DI3	Digital Input 3	Enum:		
						0: Low		
						1: High		
21	1	DB1.2	Digital Input 2	DI2	Digital Input 2	Enum:	7	
						0: Low		
						1: High		
22	1	DB1.1	Digital Input 1	DI1	Digital Input 1	Enum:		
						0: Low		
						1: High		
23	1	DB1.0	Digital Input 0	DI0	Digital Input 0	Enum:		
						0: Low		
						1: High		
24	4	DB0.7DB0.4	Not Used (= 0)			·		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegr	am
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	30	Digital Input
ТҮРЕ	04	3 Digital Inputs, 1 Digital Input 8 Bits

Submitter: Afriso / EnOcean

Description:

This profile is used for universal module with 1 analog input (= 8 bits resolution digital) and 3 digital inputs. The application meaning and exact data interpretation of the input channels depends on the end application and is not defined in this profile documentation.

Data exchange Direction: unidirectional Addressing: broadcast Communication trigger: event- & time-triggered Trigger event: values have changed Teach-in method: 4BS teach-in 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid F	Range	Scale Unit		
0	16	DB3.7DB2.0	Not Used (= 0)							
16	8	DB1.7DB1.0	Digital value-input	DV0	Digital value 1 byte	0255		0255 N/A		
24	4	DB0.7DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: .	Teach-i	in telegram		
						1:	Data te	elegram		
29	1	DB0.2	Digital Input 2	DI2	Measured digital Input 2	Enum:				
						0:	Low			
						1:	High			
30	1	DB0.1	Digital Input 1	DI1	Measured digital Input 1	Enum:				
						0:	Low			
						1:	High			
31	1	DB0.0	Digital Input 0	DI0	Measured digital Input 0	Enum:				
						0:	Low			
						1:	High			
A5-37	A5-37: Energy Management									
PO	RG	Α5	4BS Telegram							

A5-37: Energy Management

RORG	A5	4BS Telegram
FUNC	37	Energy Management
ТҮРЕ	01	Demand Response

Submitter: Echoflex Solutions Inc.

Purpose of EEP:

Demand Response is a developing standard to allow utility companies to send requests for reduction in power consumption during peak usage times. It is also used as a means to allow users to reduce overall power consumption as energy prices increase. Having an EEP for this will allow ease of integration with EnOcean products to this standard. The EEP was designed with a very flexible setting for the level (0-15) as well as a default level whereby the transmitter can specify a specific level for all controllers to use (0-100% of either maximum or current power output, depending on the load type). This EEP also includes a timeout setting to indicate how long the DR event should last if the DR transmitting device does not send heartbeats or subsequent new DR levels.

Description:

This EEP is included under a new function of Energy Management. Additional types could be added in future for power, voltage, and current data. The proposed EEP type 01 only deals with demand response activation at this point. Data Byte 3 is the default DR value for devices that implement a control algorithm that uses a set-point. It will be used for any controllers not supporting the current DR Level in the message and having an adjustable set-point.

Data Byte 2 is the default DR Level for any controllers not supporting the current DR Level in the message and having an adjustable control. It can be defined as either a percentage of the maximum power or a percentage of the current power, depending on the value of bit 7 in Data Byte 2. Bits 0 through 6 contain the percentage of power (either relative or absolute) that should be used. A value of 0 corresponds to 0% and a value of 100 corresponds to 100%. Any value higher that n100 should be interpreted as 100%. For example, if the current DR level is not supported by the controller and Data Byte 2 bit 7 is 0 and Data Byte 2 bits 0 through 6 are set to 55, then the controller should try to use 55% of its maximum power usage. In the case of a lighting load with 0-10V dimming, this would correspond to 5.5V on the dimming line. In the case of a heating controller with a maximum set back of 5 degrees C, this would correspond to a set back of 2.75 degrees C (this would most likely be rounded to 3).

Data Byte 1 is the timeout for this DR event. After this command is sent the controller will stay at the DR level for Data Byte 1 multiplied by 15 minutes. Once this time has elapsed the controller will return to normal operation. If

Data Byte 1 is 0 then the controller will remain in the DR event until the next DR command is received. This timeout allows DR devices to leave or turn off after setting controllers into a DR state, thus the DR transmitter is not needed to take the devices out of the DR state and the controllers will automatically recover. For example a DR transmitter that only sends messages when a DR event is active could be used with the timeout to create a successful DR system.

Data Byte 0, Bits 7 through 4 make up a nibble that will be used as the DR level. Levels 0 through 15 will be possible using these bits. Bit 4 will be the lowest bit in this nibble and bit 7 will be the highest. If any level is not supported by a controller then that controller should use the default settings sent in this message or map the level to one that it supports.

Data Byte 0 Bits 2 and 1 indicate whether the power adjustment at start and end of the DR event should be randomized or not. This feature is intended to minimize rapid changes on the power distribution equipment by delaying each controller's response. If random start or end is enabled, each controller will delay starting or ending the DR event by a random time that will vary uniformly over a specific time period (for example, 5 seconds, 60 seconds, or 15 minutes).. The maximum length of these random delays will depend on the implementation in the controller.

Data Byte 0, Bit 0 is the state for loads that are not adjustable for the default DR level. If a controller does not support the current DR level and does not have adjustable control then it should use this bit. The two states of this bit are defined as follows: 1 = maximum power usage by controller, 0 = minimum power usage by the controller. If for example lights are being controlled, then a setting of 1 will mean the lights should be ON, where as a setting of 0 will mean the lights should be OFF. For a thermostat application with non adjustable set back, a setting of 1 will mean that no set back should be applied, whereas a setting of 0 will mean that the full set back should be applied. This setting only applies to the maximum power usage of the controller, if for example the lights are currently off and the controller receives a DR event with this bit set, then the lights should not turn ON as the DR event has only set the maximum power usage for the device.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Temporary default	TMPD	New Temporary default DR set point Min Max. (linear)	0255	0255	N/A
8	1	DB2.7	Absolute/relative power usage	SPWRU		Interpret DB_2.BIT_ percentage power use. 1: Relative po DB_2.BIT_ percentage power use.	wer usage. In 6DB_2.BIT_ of the currer	num nterpret _0 as a nt
9	7	DB2.6DB2.0	Power Usage	PWRU	0% to 100% power usage in 1% increments; 101127 = interpreted as 100%	0100	0100	N/A
16	8	DB1.7DB1.0	Timeout Setting	TMOS	Time in 15 min. intervals; 0 = No time specified; 1255 = increasing 15 min. intervals. Max value: 3825 = 255*15	1255	153825	min
24	4	DB0.7DB0.4	DR Level	DRL	DR Level	015	015	N/A
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in te 1: Data telegr		
29	1	DB0.2	Random start delay	RSD		Enum: 0: False 1: True		
30	1	DB0.1	Randomized end delay	RED		Enum: 0: False 1: True		
31	1	DB0.0	Max/Min Power Usage for Default DR State	MPWRU			ower usage Power usage	_

A5-38: Central Command

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	08	Gateway

Communication between gateway and actuator uses byte DB_3 to identify Commands. Commands 0x01 to 0x7F shall be common to all types belonging to this profile. Commands 0x80 to 0xFE can be defined individually for each device type.

0x01 Switching

			1	•				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x01:	-	
8	16	DB2.7DB1.0	Time	ТІМ	Time in 1/10 seconds. 0 = no time specifed	165535	0.16553.5	S
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ach-in telegra ta telegram	im
29	1	DB0.2	Lock/Unlock	LCK	Lock for duration time if time >0, unlimited time of no time specified. Locking may be cleared with "unlock". During lock phase no other commands will be accepted or executed	Enum: 0: Un 1: Loo	lock ck	
30	1	DB0.1	Delay or duration	DEL	Delay or duration (if Time > 0); 0 = Duration (Execute switching command immediately and switch back after duration) 1 = Delay (Execute switching command after delay)	Enum: 0: Du 1: De	ration lay	
31	1	DB0.0	Switching Command	SW	Switching Command ON/OFF	Enum: 0: Off 1: On	_	

0x02 Dimming

REMARK:

<u>: On</u> Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x02:	-	
8	8	DB2.7DB2.0	Dimming value		Dimming value (absolute [0255] or relative [0100])	0255	0100	%
16	8	DB1.7DB1.0	Ramping time		Ramping time in seconds, 0 = no ramping, 1 255 = seconds to 100%	0255	0255	s
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ach-in egram	

						1:	Data telegram
29	1		5	EDIM R	Dimming Range	Enum	:
			Range			0:	Absolute value
						1:	Relative value
30	1	DB0.1	Store final	STR	Store final value	Enum	:
			value			0:	No
						1:	Yes
31	1		J	SW	Switching Command ON/OFF	Enum	:
			Command			0:	Off
						1:	On

0x03 Setpoint shift

Submitter: Thermokon Sensortechnik GmbH

Used for changing set point, for example summer / winter compensation

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x03:		
8	8	DB2.7DB2.0	Not Used	(= 0)				
16	8	DB1.7DB1.0	Setpoint	SP	Setpoint shift	0255	-12.712.8	К
24	4	DB0.7DB0.4	Not Used ((= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
				-		1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used ((= 0)				

0x04 Basic Setpoint

Submitter: Thermokon Sensortechnik GmbH

						1: Data telegram						
29	3	DB0.2DB0.0	Not Used (=	0)								
0x04 Basic Setpoint Submitter: Thermokon Sensortechnik GmbH												
Send a new basic set point via DDC to an actuator												
Offset	Size	Bitrange	Data	ShortCu	t Description	n Valid Range Scale UI						
0	8	DB3.7DB3.0	Command	COM	Command II	D Enum:						
						0x04:						
8	8	DB2.7DB2.0	Not Used (=	0)								
16	8	DB1.7DB1.0	Basic Setpoir	nt BSP	Basic Setpoi	nt 0255 0+51.2 °C						
24	4	DB0.7DB0.4	Not Used (=	0)								
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:						
						0: Teach-in telegram						
						1: Data telegram						
	3		Not Used (=	<u>.</u>								

0x05 Control variable

Submitter: Thermokon Sensortechnik GmbH

Set occupancy, energy holdoff and control directly actuator

0	ffset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
							0x05:		
8		8	DB2.7DB2.0	Not Used (= 0)					

16	8	DB1.7DB1.0	Control variable override	CVOV	Control variable override	0255	0100	%
24	1	DB0.7	Not Used (= 0)					
25	2	DB0.6DB0.5	Controller mode	СМ	Controller Mode	Enum: 0: Automatic selection 1: Heating 2: Cooling 3: Off	c mode	
27	1	DB0.4	Controller state	CS	Controller state	Enum: 0: Automatio 1: Override	<u> </u>	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in t 1: Data teleg		-
29	1	DB0.2	Energy hold off	ENHO	Energy Hold Off	Enum: 0: Normal 1: Energy ho point	oldoff/ Dew	1
30	2	DB0.1DB0.0	Room occupancy	RMOCC	Room occupancy	Enum: 0: Occupied 1: Unoccupie 2: Standby	ed	

						2.	Standby	
	ter: 1	-	sortechnik GmbH	P				
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit	
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x06:		
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8		FanStage override	FO	FanStage override	Enum: 0: Stage 1: Stage 2: Stage 3: Stage 255: Auto	1 2	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	in telegram elegram	V ,
29	3	DB0.2DB0.0	Not Used (= 0)			•		

0x07 Blind Central Command

<u>Submitter: PEHA / infratec</u>

With this central command all blinds, awnings and shutters can be manipulated.

Remarks for data table:

REMARK 1: The angle is usually available in blinds and awning modules. Normally, in shutter modules the angle value is ignored. The angle value can be set from -180° (e.g. maximum slat angle at the fully SHUT position) to 180° (e.g. maximum slat angle at the fully OPEN position). The byte is set with following rule: Bit7: Sign of the slat angle (0 = positive value, 1 = negative value) Bit6..0: Slat angle value in 2° steps (e.g. 50 = 100°)

REMARK 2:

If this function (Blind drives to position with angle value) is not supported or not configured, use following rule:

Position is 0 to 49% -> The blind opens
Position is 50 to 100% -> The blind closes.

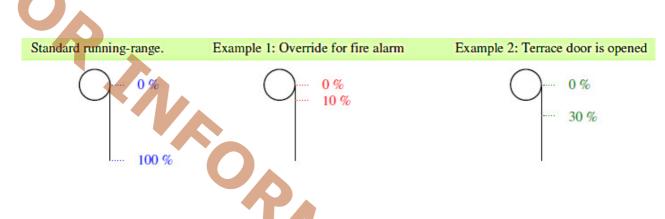
REMARK 3:

Conventional blinds and shutters can be configured with these 3 parameters to calculate the sufficiently accurate position and angle of the blind.

REMARK 4:

With this command you can adjust the minimal and maximal position of the blinds. So it's possible to override the running-range of blinds via a central control unit. Local operations are restricted and increase safety (e.g. to open blinds in case of wind or fire).

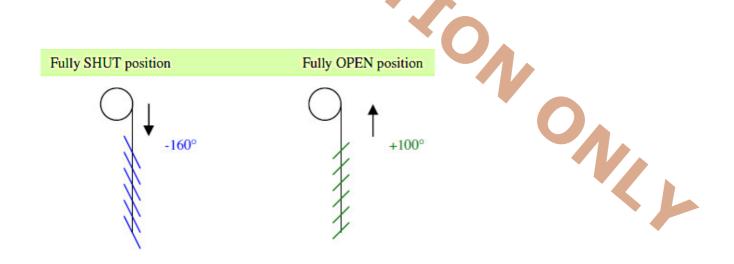
Condition: The Minimal value must be smaller or equal the maximal value.



Example to lock the local functionality: Drive the shutters to a define position and set the minimal and maximal values to this position.

REMARK 5:

These to angle values describe the maximum slat angle at the fully SHUT position and the maximal slat angle at the fully OPEN position. With the time parameter, e.g.:



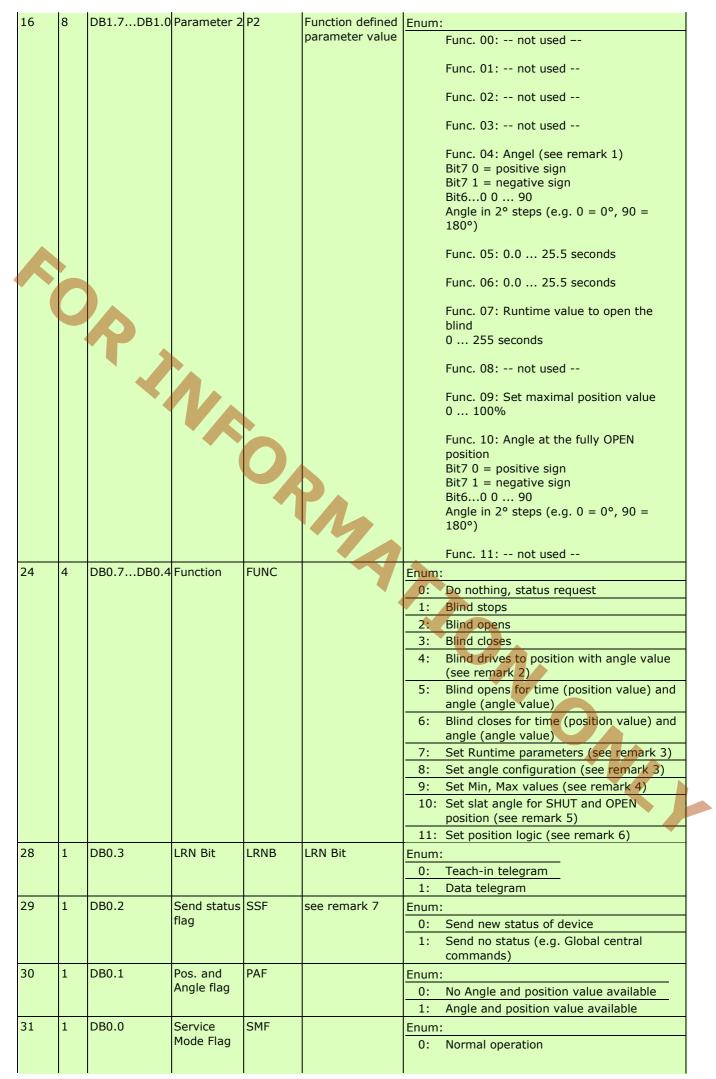
REMARK 6: Set the position logic for the blind control and visualization. Normal mode 0% ... 100% Inverse mode 100% ... 0% 0% 100 % 100 % 0%

Note: If the mode is changed, the minimum and maximal values (function 9) are converted as well!

REMARK 7:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously. Note: Special functionality is in function "Status request (0)", the status is always sent.

t Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
8		Command	СОМ	Command ID	Enum:		
					0x07: Shutters / Blinds		
8	DB2.7DB2.0	Parameter 1	P1	Function defined	Enum:		
				parameter value	Func. 00: not use	d	
					Func. 01: not use	d	
					Func. 02: not use	d	
				17	Func. 03: not use	d	
						ly open / 10	0% =
					Bind fully closed		
					Func. 05: 0 255 s	seconds	
					Func. 06: 0 255 s	seconds	
						alue to close	e the
						alue for the	sunblind
					This is the time to re	evolve the su	unblind
						on to the ot	per end
					position:		
					0.0 25.5 seconds	(0.1s steps)	
					Func. 09: Set minim 0 100%	al position v	alue
					-	he fully SHU	т
						n	
					Bit60 0 90		
					Angle in 2° steps (e 180°)	.g. 0 = 0°, 9	0 =
						= 0% / Low	vest
						= 100% / L	owest
					position = 0%		
	8	8 DB3.7DB3.0	8 DB3.7DB3.0 Command	8DB3.7DB3.0CommandCOM8DB2.7DB2.0Parameter 1P1	8 DB3.7DB3.0 Command COM Command ID 8 DB2.7DB2.0 Parameter 1 P1 Function defined	8 DB3.7DB3.0 Command COM Command ID Enum: 0x07: Shutters / Blinds 8 DB2.7DB2.0 Parameter 1 P1 Function defined parameter value Enum: Func. 00: not use 8 DB2.7DB2.0 Parameter 1 P1 Function defined parameter value Enum: Func. 01: not use 9 Func. 01: not use Func. 02: not use Func. 03: not use 9 Func. 04: 09% 100 e.g: 0% = Blind ful Blind fully closed 9 Func. 05: 0 255 s Func. 06: 0 255 s 9 Func. 07: Runtime v Blind 0 255 seconds 9 Func. 07: Runtime v Blind 0 255 seconds 9 Func. 08: Runtime v Blind 0 255 seconds 9 Func. 09: Set minim 0 100% 9 Func. 09: Set minim 0 100% 9 Func. 10: Angle at t position: 0 90 9 Angle in 2° steps (e 180°) Bit60 0 90 9 Func. 11: Position to 0 = Highest position 0 90 9 Func. 11: Position to 0 = Highest position 0 90	8 DB3.7DB3.0 Command COM Command ID Enum: 0x07: Shutters / Blinds 8 DB2.7DB2.0 Parameter 1P1 Function defined parameter value Enum: Func. 00: not used Func. 01: not used Func. 02: not used Func. 03: not used Func. 04: 0% 100% e.g.: 0% = Blind fully open / 10 Blind fully closed 8 DB2.7DB2.0 Parameter 1P1 Function defined parameter value Func. 00: not used Func. 01: not used Func. 03: not used Func. 04: 0% 100% e.g.: 0% = Blind fully open / 10 Blind fully closed 9 Func. 05: 0 255 seconds Func. 06: 0 255 seconds 9 Func. 07, Runtime value for the reversion time This is the time to revolve the si from one slat angle end position to the oth position: 0.0 25.5 seconds (0.1s steps) 9 Func. 09: Set minimal position v 0 100% Func. 10: Angle at the fully SHU position Bit7 0 = positive sign Bit7.0 = positive sign Bit7.0 = nogative sign Bit7.0 = nogative sign Bit7.1 = negative sign Bit7.0 = 0.90 Angle in 2° steps (e.g. 0 = 0°, 9 180°)



	1: Service mode: The module disables all senders, except this sender, which has set the service mode. (For example for maintenance)
--	--

RORG	A5	4BS Telegram
FUNC	38	Central Command
ТҮРЕ	09	Extended Lighting-Control

Submitter: PEHA / infratec

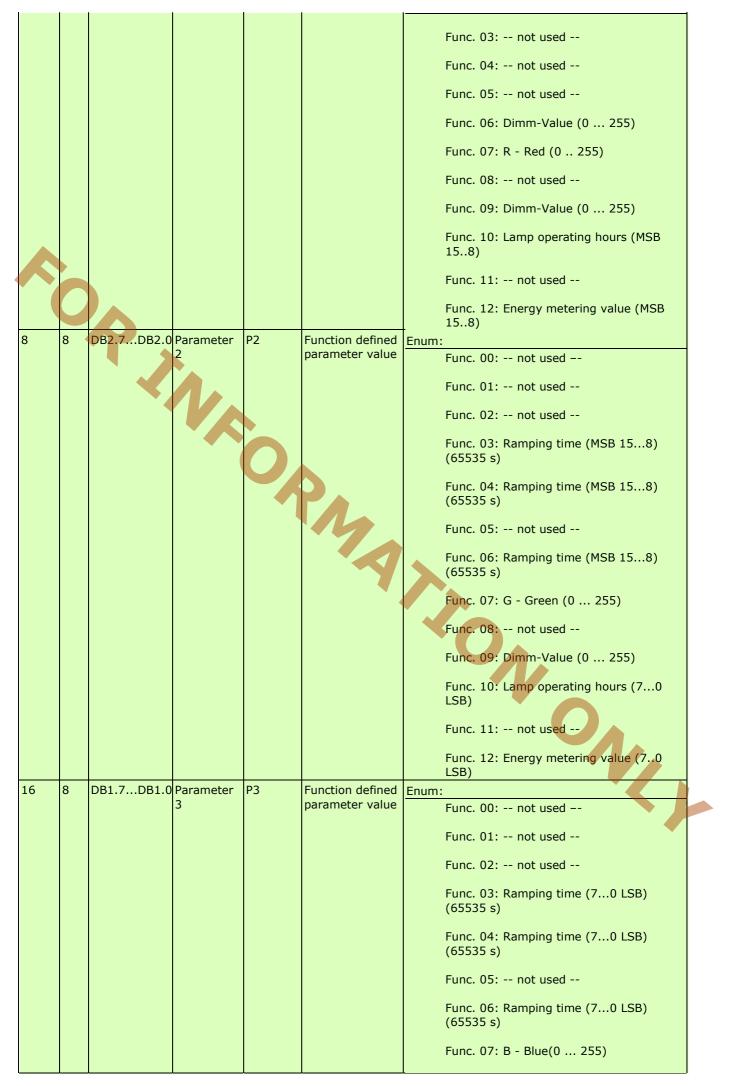
With this central command all lighting actors can be manipulated.

Remarks for data table: REMARK 1: Set the RGB level for corresponding lighting-control. Devices without this feature ignore this command. **REMARK 2:** Up to 16 different scenes can be selected and configured. **REMARK 3:** Change the minimal and maximal dimmer-value. Example: Example 1: Override for fire alarm. Example 2: Corridor lighting at night. Standard dimmer-range. 55 255 255 80 General for switchers: The values 0 .. 127 are defined to "Off". The values 128.. 255 are defined to "On". **REMARK 4:** Example: If the lamp was replaced, the operating hours are reset to 0. **REMARK 5:** This function blocks all other commands from the other taught-in transmitters. The transmitter, which has called this function, must delete the blocking state, before the other transmitters can use the device again. **REMARK 6:** For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously. Note: Special functionality is in function "Status request (0)", the status is always sent.

REMARK 7:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Parameter	P1	Function defined	Enum:		
			1		parameter value	Func. 00: not use	ed	
						Func. 01: not use	ed	
						Func. 02: not use	ed	



Specif	icati	011				© Enocea
						Func. 08: Bit7: 0 = Drive to scene-value Bit7: 1 = Stores actual value in the scene Bit30: Scene number 0 15 Func. 09: not used Func. 10: not used Func. 11: Blocks the local operations Enum: 0 = Unlock local operations 1 = Locking switch on commands 2 = Locking switch off commands 3 = Locking local operations Func. 12: Unit of energy metering value Enum: 0 = mW 1 = W 2 = kW 3 = MW 4 = Wh 5 = kWh 6 = MWh 7 = GWh 8 = mA 9 = 1/10 A 10 = mV 11 = 1/10 V
24	4	DB0.7DB0.4	Function	FUNC		11 = 1/10 V 12 15 Not used Enum: 0: Do nothing, status request 1: Switched off 2: Switched on (Memory value) 3: Dimming up with ramping time 4: Dimming down with ramping time 5: Dimming stops 6: Set dimmer-value and ramping time 7: Set RGB values (see remark 1) 8: Scene function (see remark 2) 9: Set minimal and maximal dimmer-value (see remark 3) 10: Set the operating hours of the lamp (see remark 4) 11: Locking local operations (see remark 5) 12: Set a new value for the energy metering (overwrite the actual value with the selected unit)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Send status flag	SSF	see remark 6	1. Data telegram Enum: 0: Send new status of device 1: Send no status (e.g. Global central commands)
30	1	DB0.1	Store final value	SFV		Enum: 0: No 1: Yes
31	1	DB0.0	Service Mode Flag	SMF		1. res Enum: 0: Normal operation 1: Service mode: The module disables all senders, except this sender, which has set the service mode. (For example for maintenance)

A5-3F: Universal

RORG	A5	4BS Telegram
FUNC	3F	Universal
TYPE	00	Radio Link Test (BI-DIR)

Submitter: PROBARE

Units supporting the EEP Radio Link Test shall offer a functionality that allows for radio link testing between them (Position A to Position B, point-to-point only). Testing shall be possible without the need for prior teach-in and as an option it shall cover two way communications.

Further, testing shall be backward compatible to existing EnOcean installations that support at least 1BS (RORG=0xD5) and 4BS (RORG=0xA5) EnOcean messages.

The main area of RLT application are in-field testing of radio links between portable test equipment placed at different locations as well as between portable test equipment and fixed installation, e.g. an EnOcean Gateway.

Functional description of RLT:

When two units perform radio link testing one unit needs to act in a mode called RLT Master and the other unit needs to act in a mode called RLT Slave. On a RLT enabled unit one or both modes may be supported. The mode(s) supported shall require explicitly activation at run time.

After activation a RLT Master listens for RLT_Query messages. On reception of at least one RLT_Query message a RLT Master responds with an RLT_Response message. Following that it starts transmission of RLT_MasterTest messages within a maximum time frame of 250ms and awaits the response from the RLT Slave for each RLT_MasterTest message sent. A radio link test communication consists of a minimum of 16 and a maximum of 256 RLT MasterTest messages. Timing distance between individual RLT_MasterTest messages shall not exceed 250ms. When the radio link test communication is completed the RLT Master gets deactivated automatically.

After activation a RLT Slave periodically transmits RLT_Query messages (1 message / 2s). It stops transmission of RLT Query messages as soon as it has received at least one RLT Response message. It then waits for RLT MasterTest messages from the same EnOcean ID and replies to them within a maximum delay of 100ms thru RLT_SlaveTest messages. If it does not receive RLT_MasterTest messages from the same EnOcean ID for a time period of 5s, the RLT Slave restarts periodic transmission of RLT_Query messages. The RLT Slave requires explicit deactivation.

RLT_Query Message

This Message is a "4BS Teach-In Query" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process.

RLT_Response Message

This Message is a "4BS Teach-In Response" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process. As a RLT Master does accept teach-in of a RLT Slave only for the time period required by a single RLT communication it shall indicate the EEP to be supported but the EnOcean ID of the RLT Slave not to be stored permanently. Kr

RLT_MasterTest_4BS

This is the 4BS message sent by the RLT Master during a radio link test communication **DIRECTION-1**

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	am
						1: Data te	legram	
29	2	DB0.2DB0.1	MSG_ID	MSGID	Message ID	Enum:		
						2:		
31	1	DB0.0	MSG-Source	MSGS	Message Source	Enum:		
						0: RLT-Ma	ster	

RLT_SlaveTest_4BS

This is the 4BS message sent by the RLT Slave in reply to an RLT_MasterTest_4BS message. DIRECTION- 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Uni
0	2	DB3.7DB3.6			related to RLT_MasterTest_4BS	Enum:		
			Counter		message received Repeater level 2	0: no	t support	ed
						1: 1 9	sub telegi	am
						2: 2 9	sub telegi	am
						3: ≥	3 sub	
						tel	legram	
2	6	DB3.5DB3.0	RSSI Level in dBm	RSLV	related to RLT_MasterTest_4BS	Enum:		
					message received Repeater level 1	no	ot	
						0x00: su	pported	
\sim							-31	dBm
						0x01:		
						-3	2	dBm
						0x02:		
							-93	dBm
	-					0x3F:		
8	8	DB2.7DB2.0			Related to RLT_MasterTest_4BS	Enum:		
			Counter/RSSI Level in dBm		message received Repeater level 1 (for details see DB3)	: Se	e prev	
16	8		Sub-Telegram		Related to RLT MasterTest 4BS	Enum		
10	0	DD1.7DD1.0	Counter/RSSI		message received direct link	Enum:		
			Level in dBm			: Se	e prev	
24	4	DB0.7DB0.4	RSSI Level in dBm	RSLV	Non-EnOcean signal detection since	Enum:		
				last RLT_MasterTest message RSSI	no			
					Level with 6dB quantization steps	0x00: su		
						-	-31	dBm
						0x01:	01	
						-3	237	dBm
						0x02:		
						-3	843	dBm
						0x03:		
							449	dBm
						0x04:		
							055	dBm
						0x05:		
							661	dBm
						0x06:	2 67	10
					· · · · · · · · · · · · · · · · · · ·	-6 0x07:	267	dBm
							873	dBm
						0x08:	075	ubm
							479	dBm
						0x09:		abiii
							085	dBm
						0x0A:		
						≤	-92	dBm
						0x0B:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Te	ach-in	
							legram	
						1: Da	ata telegra	am
29	2	DB0.2DB0.1	MSG_ID	MSGID		Enum:		
						2:		
								_
31	1	DB0.0	MSG-Source	MSGS		Enum:		

RLT_MasterTest_1BS

This is the 1BS message sent by the RLT Master during a radio link test communication.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECT	ION-	1							
Offset	Size	Bitrange	Data	ShortCut	Description	Val Ran	Sc:	ale	Unit
0	4		RLT MSG-Counter MSB		Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :			
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-ir telegran		
						1:	Data telegran	า	
5	2		RLT MSG-Counter LSB		Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :			
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum:			
						0:	RLT Mas	ter	

RLT_SlaveTest_1BS

This is the 1BS message sent by the RLT Slave in reply to an RLT_MasterTest_1BS message.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECT	ION- 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale I	Jnit
0	4		RLT MSG-Counter MSB	MC-MSB	Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :	_	
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	te	each-in elegram ata telegrai	n
5	2		RLT MSG-Counter LSB	MC-LSB	Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum:	-	
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum: 1: R	LT-Slave	
D2: \	/LD	Telegram					K	

D2: VLD Telegram

D2-00: Room Control Panel (RCP)

The Communication is based on the Smart Ack concept. Some basics related hereto are included in this document for convenience but for details please consult the Smart Ack specification.

A Room Control Panel (RCP) compliant to this EEP offers the following features:

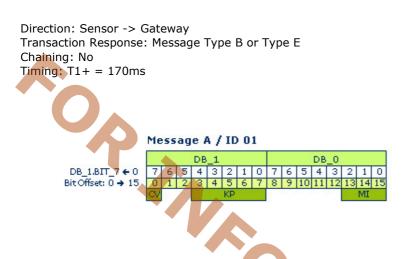
- Multi symbol, multi segment LC display (or equivalent)
- 1 temperature measurement channel, remote configurable
- 1 temperature set point control (e.g. key pad based)
- 1 fan speed control (e.g. key pad based)
- 1 presence control (e.g. key pad based)

Repeater operation shall work in compliance with the Smart Ack specification.

RORG	D2	VLD Telegram
FUNC	00	Room Control Panel (RCP)
TYPE	01	RCP with Temperature Measurement and Display (BI-DIR)

Submitter: PROBARE

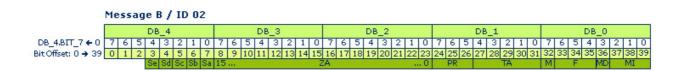
Message type A / ID 01 (First User Action on RCP)



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	ConfigValid	CV	1	Enum: 0: Configuration data not valid (message of type E) 1: Configuration data valid	e.g. never receive	d
1	2	Not Used (=	= 0)				
3		User Action	КР		Enum: 0: not used 1: Presence 2: Temperature Set Poir 3: not used 4: not used 5: Temperature Set Poir 6: Fan 0x070x1F: Not Used		- - - - -
8	5	Not Used (=	= 0)		·		
13	3	MsgId		Message Id; 0x01	Enum: 1: Message Id		
Messa	ige 1	Гуре В / І	D 02 (Di	splay Content)		

Message Type B / ID 02 (Display Content)

Direction: Gateway -> Sensor Reply to Message Type A Response: None Chaining: Up to 2 messages per chain Timing: T2 + = 300 ms



The symbols Sa, Sb, Sc, Sd, Se are optional. One or more of those symbols are available on the display only if the manufacturer of a RCP implements them in a specific design. Thus, they are NOT mandatory for a RCP in order to comply with this EEP.

Offset		Data	ShortCut	Description	Valid	Range	Scale	Unit
0	3	Not Used (= 0)						
3	1	User	Se	optional	Enum:			
		Notification			0x00: Off			
					0x01:On			
4	1	Window	Sd	optional	Enum:			
					0x00: Closed	 t		
					0x01: Opene			
5	1	Dew-Point	Sc	optional	Enum:			
					0x00: Warni	ng		
					0x01: No wa			
6	1	Cooling	Sb	optional	Enum:			
		_			0x00: Off			
					0x01:On			
7	1	Heating	Sa	optional	Enum:			
		_			0x00: Off			
					0x01:On			
8	16	Figure A Value	ZA	Format according to	Enum:			
				TA:	0x010x07	: 0 4000	0.01°	
					0x080x0A	: Time 0000 2	359	
					0x0B0x0C	: Date 0101 3	112	
					0x0D:	0 9999	lx	
					0x0E0x10	: 0 10000	0.01%	
					0x0F:	0 999	ppm	
24	3	Presence	PR		Enum:			
					0x00:	Do not display		
					0x01:	Present		
					0x02:	Not present		
					0x03:	Night time redu	ction	
					0x040x07	: not used		•
27	5	Figure A Type	ТА		Enum:			
					0x00:	Do not display		
					0x01:	Room Temperat		°C
					0x02:	Room Temperat		°F
					0x03:	Nominal Temper		°C °F
					0x04: 0x05:	Nominal Temper		°F °C
					0x05:	Delta Temperatu		°F
					0x00:	Delta Temperatu		
					0,07.	Point(graphic)	lie Set	
					0x08:	Time 00:00 to 2	3:59 [24h]	
					0x09:	Time 00:00 to 1		
					0x0A:	Time 00:00 to 1		
					0x0B:	Date 01.01 to 32	1.12 [DD.MM]	
					0x0C:	Date 01.01 to 12	2.31 [MM.DD]	
					0x0D:	Illumination (line		lx
					0x0E:	Percentage 0 to	100	
					0x0F:	Parts per Million	0 to 9999	ppm

					0x10	:	Relative Humidity 0 to 100) % rH
					0x11	0x1F:	not used	
32	1	Fan manual	М		Enum: 0:	Auto Fan ma	ual	
33	3	Fan	F		Enum: 0: 1: 2: 3: 4:	Do not Speed Speed Speed	t display Level 0 Level 1 Level 2 Level 3	
36	1	MoreData	MD			no more more da	e data ata will follow after T2+	
37	3	MsgId	MI	Message Id;0x02	Enum: 2:	Messag	e Id	

Message Type C / ID 03 (Repeated User Action on RCP)

Direction: Sensor -> Gateway Fire and Forget Response: None Chaining: No Timing: may only be sent within 5s from latest receipt of a Message Type B

Message C / ID 03

DB_3 DB_0 DB DB_1 7654321076 5 4 3 2 1 0 7 6 5 4 3 2 1 0 DB_3.BIT_7 ← 0 7 6 Bit Offset: 0 → 31 0 1 5 4 3 2 1 0 5 9 10 11 12 13 14 15 18 19 2 4 6 16 21/2

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	Set Point A Value	ZA	Format according to TA: 0x05 [0.01°]	-1270+1270	-12.70+12.70 °	
16	3	Presence	PR		Enum:		
					0x00:	no change	
					0x01:	Present	•
					0x02:	Not present	
					0x03:	Night time reduction	
					0x040x07:	not used	
19	5	Set Point A	ТА		Enum:		
		Туре			0x00:	no change	
					0x010x04:	not used	
						Tomporature Cat Daint	
					0x05:	Temperature Set Point [°]	
					0x060x1F:	not used	
24	1	Not Used $(= 0)$					
25	3	Fan	F		Enum:		
					0: no chai	nge	
					1: Speed	Level 0	
					2: Speed	Level 1	
					3: Speed	Level 2	
					4: Speed	Level 3	

					5: Speed Level Auto 67: not used
28	1	Not Used $(= 0)$			
29	3	MsgId	MI	Message Id; 0x03	Enum: 3: Message Id

Message Type D / ID 04 (Measurement Result)

Direction: Sensor -> Gateway Fire and Forget Response: None Chaining: No Timing: None Message D / ID 04 DB_3.BIT 7 + 0 Bit Offset: 0 + 23 Diffset Size Data ShortCut Description Valid Range Scale Unit												
Offset	Size	Data	ShortCut	Description	Valid Ra	nge	Scale	Unit				
0	4	Channel A Type	ТА		Enum:							
					0x00:	Tempe	rature [°C]					
					0x010x0E	E: not use	ed					
					0x0F:	Measur	rement result no	ot valid				
4	12	Channel A Value	VA	Format according to TA:	04000		040.00	0				
16	5	Not Used $(= 0)$										
21	3	MsgId	MI	Message Id;0x04	Enum:							
					4: Messag	ge Id						
4: Message Id Message Type E / ID 05 (Sensor Configuration) Direction: Gateway -> Sensor Reply to Message Type A Response: None Chaining: Up to 2 messages per chain Timing: T2+ = 300ms												



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Significant Temperature Difference		Difference between two subsequent temperature measurements to trigger a Message Type D [0.2°]	0x00xF	0.03.0	o
4	1	Not Used (= 0)					

5	3	Keep Alive Timing	KA	Number of measurements	Enum:
				between two subsequent "Keep Alive messages"	0: Transmission of
				Allve messages	measurement result with each Temperature
					measurement
					measurement *10
					0x10x7:
8	3		PR	Number of Presence Levels	Enum:
				available to user	0: Presence disabled
					0x10x7: Presence avaibles
11	3	Fan	F	Number of Fan Speed Levels	Enum:
				available to user:	0: Fan Speed disabled
					0x10x7: Fan Speeds
14	6	Temperature	Π	Time between two subsequent	Enum:
		Measurement Timing		Temperature measurements	Temperature s 0x010x3C: measurement disableds
20	5	Not Used (= 0)			
25	7	Set PointSteps	SPS	Number of Set Point Steps:	Enum:
					0: Set Point disabled
	•				0x010x7F: Set point
32	1	Not Used (= 0)	r		
33	7	Set Point Range	SPR	Limit of Set Point Range,	Enum:
		Limit		absolute value:	0: Set Point disabled
					0x010x7F: Set point °
40	4	Not Used (= 0)			
44	1	MoreData	MD		Enum:
					0: no more data
					1: more data will follow after 300ms
45	3	MsgId	MI	Message Id; 0x05	Enum:
					5: Message Id

D2-01: Electronic switches and dimmers with Energy Measurement and Local Control

This EEP family shall be used for bidirectional actuators that control electric loads, e.g. for lightning purposes. Switching and dimming is controlled and high-resolution energy measurement is supported. Local Control, either thru a user interface or thru other measures shall be supported on the actuator. This may include other EnOcean enabled devices taught-in to a device belonging to the EEP family, e.g. a simple rocker switch or more sophisticated devices like occupancy sensors with timing control. The proposed EEP family serves up to 30 output channels and allows controlling them either individually or as a bulk. Extension of this EEP family is possible in different ways:

1. A new device with a different feature mix creates a new TYPE within this EEP family -> new column in following table

2. An additional feature is added and a new device with a new TYPE is created $\mathchar`->$ new column and new line in following table

3. Like 2, but EnOcean communication of the EEP family needs to be extended

- -> new column and new line in following table
- -> one or more additional messages need to be defined

For teach-in and teach-out UTE (Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication) shall be used.

Supported function	Type 0x00	Type 0x01				Type 0x05		Type 0x07	Type 0x08		Type 0x0A	Type 0x10	
No. of output channels	1	1	1	1	1	1	1	1	1	1	1	2	2
Switching	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	х	х
Dimming	-	-	Х	Х	Х	Х	-	-	-	Х	-	-	-
Dimming configurable	-	-	-	-	Х	х	-	-	-	х	-	-	-
Local control	Х	Х	Х	Х	Х	Х	-	-	Х	Х	Х	х	Х
Local control enable/disable	-	-	-	-	х	х	-	-	х	-	х	-	-

SNIF

								-					
Taught-in devices enable/disable 2)	-	-	-	-	х	Х	-	-	х	Х	х	-	-
User interface day/night mode	-	-	-	-	-	Х	-	-	х	-	х	-	-
Over current reporting	-	-	-	-	Х	Х	-	-	х	Х	-	-	-
Over current configurable	-	-	-	-	Х	Х	-	-	Х	-	-	-	-
Energy measurement	Х	-	Х	-	Х	Х	Х	-	Х	Х	-	Х	-
Power measurement	-	-	-	-	Х	Х	-	-	х	Х	-	-	-
Measurement Roll Over 1)	х	-	Х	-	-	-	Х	-	-	-	-	Х	-
Measurement Auto Scaling 1)	-	-	-	-	х	Х	-	-	х	Х	-	-	-
Measurement configurable	-	-	-	-	-	Х	-	-	х	Х	-	-	-
Measurement report on query	х	-	Х	-	Х	Х	Х	-	х	Х	-	Х	-
Measurement auto reporting	-	-	-	-	Х	Х	-	-	х	Х	-	-	-
Default state configurable	-		-	-	-	Х	-	-	х	Х	х	-	-
Error level reporting	-		-	-	-	Х	-	-	Х	Х	-	-	-
Power Failure Detection	-	-		-	-	-	-	-	-	-	Х	-	-
Power Failure Detection enable/disable	-	-			-	-	-	-	-	-	Х	-	-

1) A device may either support Measurement Roll Over or Measurement Auto Scaling.

2) Enable / disable only effects devices that are taught-in to a device belonging to this EEP family; it does not effect communication between a device belonging to this EEP family and any other entity where this device has been taught-in by itself.

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	00	Type 0x00
<u>Submitter: Te</u>	am	
CMD 0x1 - /	Actuator So	et Output
This message	is sent to an	actuator. It controls switching / dimming of one or all channels of an actuator.

CMD 0x1 - Actuator Set Output



REMARK:

In case an Actuator Set Output message specifies a parameter that is not supported by the device being addresses, such device shall react as following:

- channel not supported by device -> ignore message
- dimming command to switching device -> no change of status
- dimming command with non supported speed -> dim with regular speed

RECOMMENDATION:

Dimmers should take things like phase shifting into account to provide dimming based on power consumption (results in brightness for lamps) rather than interpreting percentage values as phase angle only.

Offset	Size	Data	ShortCut	Description	Valie	d Range	Scale	Unit			
0	4	Not Used (=	0)		_						
4	4	Command		command	Enum:						
		ID		identifier	0x01:ID 01						
8	3	Dim value	DV		Enum:						
					0x00:	Switch to new out	put value				
					0x01:	Dim to new output	t value – dim tim	er 1			
					0x02:	Dim to new output	t value – dim tim	er 2			
					0x03:	Dim to new output	t value – dim tim	er 3			
					0x04:	Stop dimming					
					0x050x07	not used					
11	5 I/O channel	I/O		Enum:							
						0x000x1D:	Output channel (to load)				
					0x1E:	All output channel device	s supported by tl	he			
					0x1F:	Input channel (fro	m mains supply)				
16	1	Not Used (=	0)								
17	7	Output value	OV		Enum:						
					0x00:	Output value 0% of	or OFF				
					0x010x64	Output value 1% t	o 100% or ON				
					0x650x7E	7E: Not used					
					0x7F:	Output value not v	valid / not applica	ble			

CMD 0x2 - Actuator Set Local

This message is sent to an actuator. It configures one or all channels of an actuator.

Response Timing: None

RECOMMENDATION:

In case the device implements an internal order for dim timers, this order should be from "dim timer 1" (fast) to "dim timer 3" (slow). The configured time shall always be interpreted for a full range (0 to 100%) dimming.



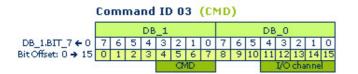
Offset	Size	Data	ShortCut	Description		Valid Range	Scale	Unit
0	1	Taught-in devices	d/e		Enum	:		
					0b0:	Disable taught-in dev EEP)	rices (with diff	ferent
					0b1:	Enable taught-in devi EEP)	ces (with diff	erent
1	3	Not Used (= 0)						

	4	Command ID	CMD	Command identifier	Enum:
0	1		00		0x02: ID 02
8	1	Over current shut down	UC		Enum:
					0b0: Over current shut down: static off
	-		D O		0b1: Over current shut down: automatic restart
9	1	reset over current shut down	RO		Enum:
		down			Reset over current shut down: not active 0b0:
					Reset over current shut down: trigger 0b1: signal
10	1	Local control	LC		Enum:
					0b0: Disable local control
					0b1: Enable local control
11	5	I/O channel	I/O		Enum:
A					Output channel (to load) 0x000x1D:
					0x1E: All output channels supported by the device
					0x1F: Input channel (from mains supply)
16	4	Dim timer 2	DT2		Enum:
					0x00: Not used
		< A .			Dim timer 2 [0,5 7,5s / steps 0x010x0F: 0,5s]
20	4	Dim timer 3	DT3		Enum:
					0x00: Not used
		-			Dim timer 3 [0,5 7,5s / steps 0x010x0F: 0,5s]
24	1	User interface	d/n		Enum:
	-	indication	u/		0b0: User interface indication: day operation
					0b1: User interface indication: night operation
25	1	Power Failure	PF		Enum:
20	-				0b0: Disable Power Failure Detection
					0b1: Enable Power Failure Detection
26	2	Default state	DS		
20	2		55		0b00: Default state: 0% or OFF
					0b01: Default state: 100% or ON
					0b10: Default state: remember previous state
					0b11: Not used
28	4	Dim timer 1	DT1		Enum:
20	-		511		0x00: Not used
					Dim timer 1 [0,5 7,5s / steps
					0x010x0F: 0,5s]
смр ()x3 ·	- Actuator Status Qu	ery		e or all channels of an actuator.

CMD 0x3 - Actuator Status Query

Response Timing:

An Actuator Status Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valio	d Range	Scale	Unit
0	4	Not Used (=	0)					
4		Command ID	-	Command identifier	Enum: 0x03: ID 03	_		
8	3	Not Used (=	0)					
11	5	I/O channel	I/O		Enum: 0x000x1D:	Output channel (t	o load)	
					0x1E:	All output channe device	ls supported by t	he
				0x1F:	Input channel (fro	om mains supply)	

CMD 0x4 - Actuator Status Response

This message is sent by an actuator if one of the following events occurs:

- Status of one channel has been changed locally
- Message Actuator Status Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Status Query message.



REMARK 1:

In case an Actuator Status Query message specifies a parameter that is not supported by the device being addresses, such device shall ignore the message and shall not answer using the Actuator Status Response message. REMARK 2:

In case an Actuator Status Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Power Failure	PF		Enum:		
					Power Failure Detection 0b0: supported	n disabled/not	
					Power Failure Detection 0b1:	n enabled	
1	1	Power Failure	PFD		Enum:		
		Detection			Power Failure not deter 0b0: supported/disabled	cted/not	

					Power Failure Detected
					0b1:
2	2	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04
8	1	Over current switch	ос		Enum:
		off			Over current switch off: ready / not 0b0: supported
					Over current switch off: executed 0b1:
9	2	Error level	EL		Enum:
					0b00: Error level 0: hardware OK
					0b01: Error level 1: hardware warning
					0b10: Error level 2: hardware failure
					0b11: Error level not supported
11	5	I/O channel	I/O		Enum:
					0x000x1D: Output channel (to load)
					0x1E: Not applicable, do not use
					0x1F: Input channel (from mains supply)
16	1	Local control	LC		Enum:
					0b0: Local control disabled / not supported
					0b1: Local control enabled
17	7	Output value	OV		Enum:
					0x00: Output value 0% or OFF
					0x010x64: Output value 1% to 100% or ON
					0x650x7E: Not used
					0x7F: output value not valid / not set

CMD 0x5 - Actuator Set Measurement

This message is sent to an actuator. It configures the energy and power measurement of one or all channels of an actuator.

Response Timing: None



Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)	÷		
4	4	Command ID	CMD	Command identifier	Enum: 0x05: ID 05
8	1	Report measurement	RM		Enum: Report measurement: query 0b0: only Report measurement: query / 0b1: auto reporting
9	1	Reset measurement	RE		Enum: Reset measurement: not 0b0: active Reset measurement: trigger 0b1: signal

- 1

1

10	1	Measurement mode	e/p		Enum:			
					0b0: Energy me	asurement		
					0b1: Power mea	asurement		
11	5	I/O channel	I/O		Enum:			
					Ou 0x000x1D: loa	tput channel (to d)	0	
					sup	output channel oported by the vice	S	
						out channel (fro ins supply)	m	
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A	
20	1	Not Used (= 0)						
21	3	Unit	UN		Enum:			
					0x00: Er	nergy [Ws]		
					0x01: Energy [Wh]			
					0x02: Energy [KWh]			
					0x03: Pc	wer [W]		
	•				0x04: Pc	wer [KW]		
					0x050x07: No	ot used		
24	8	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A	
32	8	Maximum time between two subsequent Actuator	MAT	Measurement Response messages [10s]	0255	102550	S	
40	8	Minimum time between two subsequent Actuator	MIT	Measurement Response messages [s]	0255	0255	s	

CMD 0x6 - Actuator Measurement Query

This message is sent to an actuator. The actuator replies with an Actuator Measurement Response message.

Response Timing:

An Actuator Message Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.

Command ID 06 (CMD)																
				DB	_1							DB	_0			
DB_1.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a	1D			100	qu		I/O	cha	nne	

withou	t resu	ult.	ommand II	D 06 (CMD) 2 1 0 7 6 5 4 5 6 7 8 9 10 11 1		rame the action sha		
06	Size	Data						
UTTSE	JJIZE	Data	ShortCut	Description	Vali	d Range	Scale	Unit
Offset 0	4	Not Used (=		Description	Vali	d Range	Scale	Unit
				Description Command identifier	Enum: 0x06: ID 06	d Range	Scale	Unit
0	4	Not Used (= Command	0) CMD	Command	Enum:	d Range	Scale	Unit
0 4	4 4	Not Used (= Command ID	0) CMD	Command	Enum:	energy	Scale	Unit

CMD 0x7 - Actuator Measurement Response

This message is sent by an actuator if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Measurement Query message.

 Command ID 07 (CMD)

 DB_5
 DB_4
 DB_3
 DB_2
 DB_1
 DB_0

 OMD
 Unit
 UV
 Wet colspan="2"
 DE_1
 DB_2

 DB_1
 <th col

message.

REMARK 2:

In case an Actuator Measurement Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07		
8	3	Unit	UN		Enum: 0x00: Energy [W 0x01: Energy [W 0x02: Energy [KV 0x03: Power [W] 0x04: Power [KW 0x050x07: Not used	h] Wh]	
11	5	I/O channel	I/O		0x000x1D: 0x1E: Not applica	nnel (to load able, do not nel (from m	use
16	32	Measurement value (4 bytes)	MV	DB3 = MSB / DB0 = LSB	04294967295		N/A

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	01	Type 0x01 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control

 TYPE
 02
 Type 0x02 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	03	Type 0x03 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	04	Type 0x04 (description: see table)
See profile: D2	-01-00	
RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	05	Type 0x05 (description: see table)
See profile: D2	-01-00	
RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	06	Type 0x06 (description: see table)
See profile: D2		
RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	07	Type 0x07 (description: see table)
See profile: D2		

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	08	Type 0x08 (description: see table)

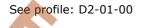
See profile: D2-01-00

EEP 2.6 Specification

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	09	Type 0x09 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
ТҮРЕ	0A	Type 0x0A (description: see table)



RORG 🖌	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	10	Type 0x10 (description: see table)
See profile: D	02-01-00	

RORG	D2	VLD Telegram					
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control					
ΤΥΡΕ	11	Type 0x11 (description: see table)					
See profile: D	2-01-00						

D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke

This EEP family shall be used for bidirectional sensors that measure temperature, illumination, and detect room occupancy and smoke presence.

The EEP may be used in conjunction with the Smart Acknowledge protocol.

For teach-in and teach-out the "Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication" shall be used. Alternatively the Smart Acknowledge Teach-In Procedure is used for those sensors supporting Smart Acknowledge.

Supported function	Type 0x00	Type 0x01	Type 0x02
Temperature Sensor	Х	Х	Х
Illumination Sensor	х	х	-
Occupancy Detector	х	-	-
Smoke Detector	Х	Х	Х

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
ТҮРЕ	00	Type 0x00

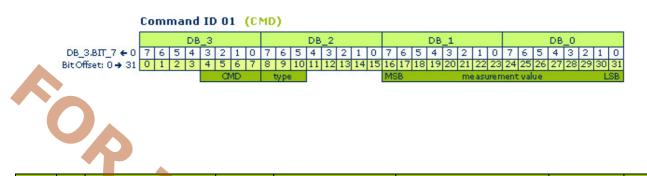
Submitter: MSR-Office

CMD 0x1 - Sensor Measurement

This message is sent by a sensor if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing: None



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	command identifier	Enum: 0x01: ID 01		
8	3		type		Enum: Temperature (06 0x00: +120°C) Illumination (06 0x01: Occupancy (0: not 0x02: detected) Smoke 0x03: The following cont value in DB_0 and 0x00 - No smoke det 0x01 - Smoke det chamber 0x02 - Smoke det chamber 0x03 - Smoke det chambers	5535: 0 to 204 detected; 1: DB_1: detected ected via ioniz ected via optic	the ation
11	5	Not Used (= 0)			*		
16	16	Measurement value (2 bytes)	MV	DB_0 = LSB / DB_1 = MSB	065535		N/A
CMD ()x2 ·	- Sensor Test/Trigg	jer				<

CMD 0x2 - Sensor Test/Trigger

This message is sent to a sensor. It causes the sensor to enter self-test mode or trigger an alarm (if supported).

Response Timing: None

Command ID 02 (CMD)																
	DB_1							DB_0								
DB_1.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a	4D		ST	TA	1					

2 1 0

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used $(= 0)$))		_		
4	4	Command ID	CMD	Command identifier	Enum:		
					0x02: ID 02		
8	1	Self-test	ST		Enum:		
					0b0: Self-tes	st mode	9
					0b1: Normal	operat	ion
9	1	Trigger alarm	TA		Enum:		
					0b0: Trigger	alarm	
					0b1: Normal	operat	ion
10	6	Not Used (= 0))				

CMD 0x3 - Actuator Set Measurement

This message is sent to a sensor. It configures the measurement behaviour of the sensor.

Response Timing: None

Command ID 03 (CMD)

 DB_5.8IT_7 ←0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6
 5
 4
 3
 1
 0
 7
 6
 5
 4
 3
 2
 1
 0
 7
 6

Measurement delta to be reported

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x03: ID 03		
8	1	Report measurement	RM		Enum:		
					Report mea	asurement: qu	ery
					0b0: only		
						asurement: qu	ery /
					0b1: auto rep <mark>ort</mark>	ing	
9	7	Not Used (= 0)	1				
16		Measurement delta to be	MD_LSB		04095	04095	N/A
		reported (LSB)					
20		Not Used (= 0)					
21	3	Unit	UN		Enum:		
						mperature (°C)
						umination (Ix)	
					0x020x07: No	1	
24	-	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32		Maximum time between two	МАТ	Maaguramant Pagnanga	0255	102550	s
52	-	subsequent Actuator		Measurement Response messages [10s]	0255	102350	5
40	8	Minimum time between two	MIT	Measurement Response	0255	0255	s
		subsequent Actuator		messages [s]			

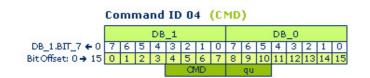
CMD 0x4 - Sensor Measurement Query

This message is sent to a sensor. The sensor replies with an Sensor Measurement message.

Response Timing:

A Sensor Measurement message shall be received within a maximum of 300ms from the time of transmission of this message.

In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (=	0)				
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04		
8	3	Query	qu		0x1: Quer 0x2: Quer	y tempera y illumina y occupar y smoke used	tion
11	5	Not Used (=	0)				

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
ТҮРЕ	01	Type 0x01 (description: see table)

See profile: D2-02-00

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	02	Type 0x02 (description: see table)

See profile: D2-02-00

D2-03: Light, Switching + Blind Control

The EEP family D2-03-xx provides different telegram types for switches, light and blind control. The purpose is to support secure communication and other functional aspects of applications extending the possibilities given by existing profiles (1BS, RPS, 4BS). Transmitting information in the status field of a telegram is not necessary with this EEP family.

In

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
ТҮРЕ	00	Type 0x00

Submitter: EnOcean GmbH

EEP Properties:

ONL

DATA EXCHANGE Direction: unidirectional Addressing: broadcast Communication trigger: event-triggered Communication interval: N/A Trigger event: N/A Tx delay: N/A Rx timeout : N/A

TEACH-IN Teach-in method: Universal teach-in (UTE) + Secure Teach-in (for secure communication)

SECURITY Encryption supported: yes

EEP Family Table:

(Only for VLD EEP families)

Supported function Type 00 Х 2 Rocker Switch

Each TYPE has to support every parameter that is marked in its column!

The encrypted telegram has the R-ORG 0x30. The payload (4 bits) is encrypted. That telegram can be repeated. After decryption and the authentication of the CMAC, the telegram turns into a non-encrypted EnOcean telegram with the R-ORG 0x32. The payload will be expanded to 8 bits (4 MSB set to zero) and can then be interpreted as described in the telegram definition table.

The decrypted telegram may not be repeated as the information is not secure anymore. The following table provides information about the conversion between the profiles D2-03-00 and F6-02-01:

D2-03-00 DATA	F6-02-01 DATA	F6-02-01 STATUS
04	-	-
5	0x17	0x30
6	0x70	0x20
7	0x37	0x30
8	0x10	0x20
9	0x15	0x30
10	0x35	0x30
11	0x50	0x30
12	0x70	0x30
13	0x10	0x30
14	0x30	0x30
15	bxxx0xxxx	0x20

	00 C	DATA	F6-02-01	. DATA	F6-0	02-01 STATUS					
04			-		-						
5			0x17		0x3						
6			0x70		0x2	0					
7			0x37		0x3	0					
8			0x10		0x2	0					
9			0x15		0x3	0					
10			0x35		0x3	0					
11			0x50		0x3	0					
12			0x70		0x3	0					
13			0x10		0x3	0					
14			0x30		0x3	0					
15			bxxx0xxx	x	0x2	0					
Offset S	Size		Data	Short	tCut	De	escription		lid Range		ale
0 4	ŀ	Not U	sed (= 0)	-			escription	Va	lid Range		ale
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	Short RI2		Information abo	escription		lid Range		ale
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0)	-			escription	Enum:	lid Range		ale
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04:	lid Range Reserved	Sc	
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Enum:	lid Range	+ B0 p	ressed,
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04: 5:	lid Range Reserved Button A1 energy box	+ B0 p w press	ressed,
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04:	lid Range	+ B0 p w press	ressed, ed
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04: 5:	lid Range Reserved Button A1 energy box 3 or 4 butt	+ B0 p w press cons pre w press	ressed, eed essed, eed
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04: 5: 6:	lid Range Reserved Button A1 energy boy 3 or 4 butt energy boy	+ B0 p w press ons pre w press + B0 p	ressed, aed essed, aed ressed,
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04: 5: 6:	lid Range Reserved Button A1 energy boy 3 or 4 butt energy boy Button A0	+ B0 p w press cons pre w press + B0 p w press s presse	ressed, eed essed, eed ressed, eed
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Enum: 04: 5: 6: 7:	lid Range Reserved Button A1 energy boy 3 or 4 butt energy boy Button A0 energy boy No buttons	+ B0 p w press cons pre w press + B0 p w press s presse ed	ressed, ied essed, ied ressed, ied ed, ener
0 4	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04: 5: 6: 7: 8:	lid Range Reserved Button A1 energy boy 3 or 4 butt energy boy Button A0 energy boy No buttons bow presse	+ B0 p w press cons press + B0 p w press s presse ed + B1 p	ressed, aed essed, aed ressed, aed ed, ener ressed,
	ŀ ŀ	Not U <mark>Rocke</mark>	sed (= 0) r	-		Information abo	escription	Va Enum: 04: 5: 6: 7: 8: 9:	lid Range Reserved Button A1 energy boy 3 or 4 butt energy boy Button A0 energy boy No buttons bow presse Button A1	+ B0 p w press ons pre w press + B0 p w press s presse ed + B1 p w press + B1 p	ressed, eed ressed, eed ressed, eed, ener ressed, ressed, ressed,

	11:	Button B1 pressed, energy bow pressed
	12:	Button B0 pressed, energy bow pressed
	13:	Button A1 pressed, energy bow pressed
	14:	Button A0 pressed, energy bow pressed
	15:	Energy bow released

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	10	Mechanical Handle
ITPE	10	Mechanical Handle

Submitter: Eltako

This document contains the description of decrypted mechanical handle data. The mechanical handle profile must be redefined because there is no status field in EnOcean security available.

EEP Properties:

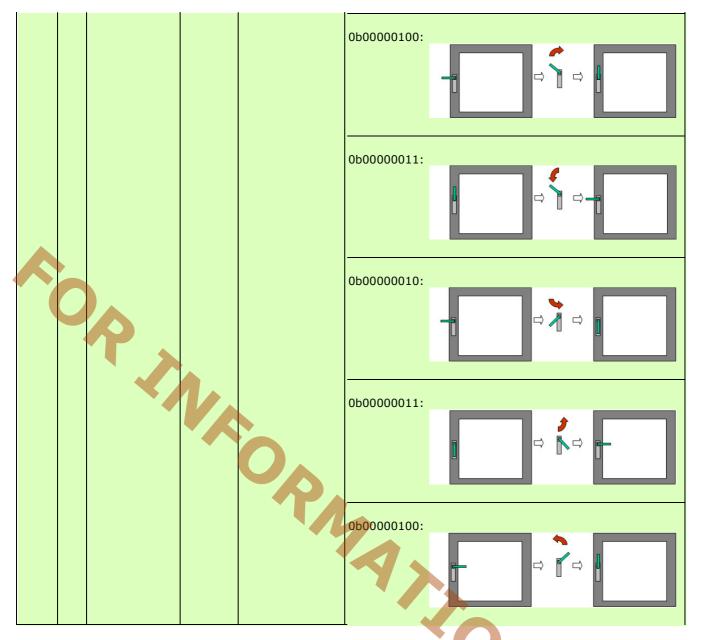
DATA EXCHANGE Direction: unidirectional Addressing: broadcast Communication trigger: event-triggered Communication interval: N/A Trigger event: rotate mechanical handle Tx delay: N/A Rx timeout: N/A

TEACH-IN

Teach-in method: Secure Teach-in, followed by special RPS teach-in sequence: Mechanical handle (closed => opened => closed within 2s) 97

SECURITY Encryption supported: yes Security level format:

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	8	Window handle, decrypted data	WIN	Movement of the window handle	Enum: 0b00000001: 0b00000010:			
					0b00000011:			



D2-04: CO2, Humidity, Temperature, Day/Night and Autonomy

CO2 sensor with 8 bits resolution (0 – 2000ppm or 0-5000ppm range) 8 bits temperature and relative humidity with NIL Day / Night and battery autonomy.

Day / Night is based on illumination not on clock

Data exchange

Direction: unidirectional Addressing: broadcast Communication trigger: time-triggered Communication interval: According to remaining autonomy and day or night Trigger event: heartbeat, ... Teach-in method: Universal teach-in, Smart Ack Encryption required: no Security level format: 0

EEP Family Table

Each TYPE has to support every parameter that is marked in its column!

ТҮРЕ	0x00	0x01	0x02	0x03	0x04	0x05	0x06	0x07	0x08	0x09	0x10	0x1A	0x1B	0x1C	0x1D	0x1E
CO2 Sensor 0-2000	Х	Х	Х	Х	Х	Х	Х	Х	-	-	-	-	-	-	-	-
ppm range																
CO2 Sensor 0-5000	-	-	-	-	-	-	-	-	Х	Х	Х	Х	Х	Х	Х	Х
ppm range																
Humidity Sensor	Х	Х	-	-	-	-	-	-	Х	Х	-	-	-	-	-	-

Temperature Sensor	х	-	х	х	х	х	-	-	х	-	х	х	х	х	-	-
Day/Night Sensor	Х	Х	Х	-	-	Х	Х	Х	Х	Х	Х	-	-	Х	Х	Х
Battery Autonomy	Х	Х	Х	Х	-	-	-	Х	Х	Х	Х	Х	-	-	-	Х

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ΤΥΡΕ	00	Type 0x00

Submitter: NanoSense

The manufacturer will indicate emission rates versus battery autonomy and day night status.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	CO2		Concentration (linear), 1 LSB = 7.84 ppm Or Concentration (linear), 1 LSB = 19.6 ppm	0255	02000 (or 5000)	ppm
8	8	Humidity	ним	Rel. Humidity (linear), 1 LSB = 0.5%	0200	0100	%
16	8	Temperature	ТМР	Temperature (linear), 1 LSB = 0.2 °C	0255	0+51	°C
24	1	Day/Night	DN		Enum: 0: Day 1: Night	_	
25		Battery autonomy	ВА	Battery autonomy	1: 87.5 - 2: 75 - 6 3: 62.5 - 4: 50 - 3 5: 37.5 -	87.5 % - 75 % - 2.5 % - 50 % - 25 % - 2.5 % - 0 %	
28	4	Not Used (= 0)					

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy	
ТҮРЕ	01	Type 0x01 (description: see table)	
See profile: D	2-04-00		

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	02	Type 0x02 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	03	Type 0x03 (description: see table)

See profile: D2-04-00

	20	VI D Tologram	
RORG FUNC	D2	VLD Telegram	
TYPE	04	CO2, Humidity, Temperature, Day/Night and Autonomy Type 0x04 (description: see table)	
ITPE	04	Type 0x04 (description: see table)	
ee profile: D2	2-04-00		
RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy	
ТҮРЕ	05	Type 0x05 (description: see table)	
ee profile: D2	04-00		
RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy	
ТҮРЕ	06	Type 0x06 (description: see table)	
_			
ee profile: D2	2-04-00		
		Ph	
RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy	
ΤΥΡΕ	07	Type 0x07 (description: see table)	
ee profile: D2	-04-00		
ee profile: D2	2-04-00		
ee profile: D2	2-04-00		
		VID Telegram	
RORG	D2	VLD Telegram CO2 Humidity, Temperature, Day/Night and Autonomy	
RORG FUNC	D2 04	CO2, Humidity, Temperature, Day/Night and Autonomy	
RORG	D2		
RORG FUNC TYPE	D2 04 08	CO2, Humidity, Temperature, Day/Night and Autonomy	
FUNC	D2 04 08	CO2, Humidity, Temperature, Day/Night and Autonomy	
RORG FUNC TYPE	D2 04 08	CO2, Humidity, Temperature, Day/Night and Autonomy	
RORG FUNC TYPE	D2 04 08	CO2, Humidity, Temperature, Day/Night and Autonomy	
RORG FUNC TYPE	D2 04 08	CO2, Humidity, Temperature, Day/Night and Autonomy	
RORG FUNC TYPE ee profile: D2	D2 04 08 2-04-00	CO2, Humidity, Temperature, Day/Night and Autonomy Type 0x08 (description: see table)	

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	10	Type 0x10 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1A	Type 0x1A (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	1B	Type 0x1B (description: see table)
See profile: D2	2-04-00	
POPC	D 2	
RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	1C	Type 0x1C (description: see table)
See profile: D2	2-04-00	
RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	1D	Type 0x1D (description: see table)
See profile: D2	2-04-00	
RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
ТҮРЕ	1E	Type 0x1E (description: see table)
		VLD Telegram CO2, Humidity, Temperature, Day/Night and Autonomy Type 0x1E (description: see table)

See profile: D2-04-00

D2-20: Fan Control

The EEP family D2-20-xx provides different telegram types for fan control and fan supervision messages using various parameters and variables. Devices using this EEP family may include a master-slave function (for further description see subheading 'Master-slave function').

EEP Properties:

DATA EXCHANGE Direction: bidirectional Addressing: unicast (ADT) + broadcast Communication trigger: event-triggered Communication interval: N/A Trigger event: query / polling Tx delay: N/A Rx timeout : N/A

TEACH-IN Teach-in method: Universal teach-in (UTE)

SECURITY Encryption supported: no Security level: none

EEP Family Table:

(Only for VLD EEP families)

Supported function	Type 00	Type 01	Type 02
Fan Speed	Х	Х	Х
Fan Speed Status	Х	Х	Х
Humidity	Х	-	-
Humidity Control	Х	-	-
Humidity Control Status	Х	-	Х
Humidity Threshold	Х	-	-
Message Type	X	Х	Х
Operating Mode	X	-	-
Operating Mode Status	X	Х	-
Room Size	Х	X	Х
Room Size Reference	X	X	Х
Room Size Reference Status	Х	X	Х
Room Size Status	Х	X	Х
Service Information	Х		
Temperature Level	Х	-	-

Each TYPE has to support every parameter that is marked in its column!

Master-slave function:

A device using this EEP may be able to work as a master or a slave fan. Master fans control slave fans. Slave fans are controlled by master fans. These roles are defined during the teach-in process. A slave fan will always be taught-in to a master. A master fan will accept teach-in requests from slave fans. A fan that is taught-in to another device will from now on work as a slave. A fan that accepted the teach-in of another device will go on working as a master. Combining master fans is not possible. Not every device is able to work as a master and a slave. Certain fans might only be able to be used as slaves.

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	00	Type 0x00

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition : 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid F	Range	Scale	Unit
0	4	Operating Mode	ОМ	Sets the operating mode	Enum:			
					0:	Disable	ed	
					1:	Standa	ard	
						compli	ant	
						Reserv	ed	
					214:			
					15:	No cha	inge	

NIL

1	1	Not Used (= 0)			
5	2	Temperature Level	TL	Status of the temperature supervision	Enum:
					0: Too low
					1: Normal
					2: Too high
					3: No change
7	1	Message Type	MT	Defines the message type	Enum:
					0: Fan control
8	2	Humidity Control	HC	Activates the humidity control	Enum:
					0: Disabled
					1: Enabled
					2: Default
					3: No change
10	2	Room Size	RSR	Defines if the provided room size has to be	Enum:
		Reference		considered	0: Used
				1: Not used	
					2: Default
					3: No change
12	4	Room Size	RS	Defines the room size	Enum:
					0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
					4: 100125 m ²
		· · · · · · · · · · · · · · · · · · ·			5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
				RMAN	13: 325350 m ²
					14: > 350 m ²
					15: No change
16	8	Humidity	НТ	Sets the humidity threshold	Enum:
		Threshold			0100: 0100%
					101252: Reserved
					253: Auto
					254: Default
					255: No change
24	8	Fan Speed *	FS	Sets the fan speed	Enum:
					0100: 0100%
				101252: Reserved	
					253: Auto
					254: Default
					2JT. Delault

Telegram Definition : 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid F	Range	Scale	Unit
0			OMS	Provides the recent operating mode	Enum:			
		Status			0:	Disable	ed	
					1:	Standa	ard	
						compli	ant	
						Reserv	'ed	
					214:			
					15:	Not su	pported	

4	3	Service Information	SI	Service information	Enum:
					0: Nothing to report
					1: Air filter error
					2: Hardware error
					36: Reserved
					7: Not supported
7	1	Message Type	МТ	Defines the message type	Enum:
,	-	hessage type		bennes the message type	1: Fan status
0	2	Humidity Control	HCS	States if the humidity control is active	· · · · · · · · · · · · · · · · · · ·
8	2	Humidity Control Status	псэ	States if the humidity control is active	Enum:
		Status			0: Disabled
					1: Enabled
					2: Reserved
					3: Not supported
10	2	Room Size	RSR	States if the provided room size has to be	Enum:
		Reference		considered	0: Used
					1: Not used
					2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum:
					0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					<u>10: 250275 m²</u>
				PMAN N	11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
					15: Not supported
16	8	Humidity	НИМ	Humidity measurement	Enum:
					0100: 0100%
					Reserved
					101254:
					255: Not
					supported
24	8	Fan Speed Status	FSS	Fan speed	Enum:
					0100: 0100%
					Reserved
					101254:
					255: Not
					supported

RORG	D2	VLD Telegram
FUNC	20	Fan Control
ΤΥΡΕ	01	Type 0x01

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition : 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid Rang	e Scale Unit		
0	7	Not Used $(= 0)$						
7	1	Message Type	MT	Defines the message type	Enum:			
					0: Fan	control		
8	2	Not Used $(= 0)$						
10	2	Room Size	RSR	Defines if the provided room size has to be	Enum:			
		Reference	Reference		considered	0: Used		
					1: Not u	used		
					2: Defa	ult		
					3: No c	hange		
12	4	Room Size	RS	Defines the room size	Enum:			
					0: < 25	m²		
					1: 25	50 m²		
					2: 50	75 m²		
					3: 75	100 m²		
						125 m²		
						150 m²		
						175 m²		
					-	200 m²		
						225 m²		
						250 m²		
					10: 250.			
					11: 275.			
					12: 300.			
					13: 325.			
					14: > 35			
	-				15: No c	hange		
16	8	Not Used (= 0)	50					
24	8	Fan Speed *	FS	Sets the fan speed	Enum:	0 1000/		
					0100:	0100%		
					101252:	Reserved		
					253:	Auto		
					253:	Default		
					255:	No		
					255.	change		

Telegram Definition : 'Fan Status Message'

Teleg	ram	Definition : `Fa	n Status M	lessage'	0,,,
Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0		Operating Mode Status	OMS	Provides the recent operating mode	Enum: 0: Disabled 1: Standard compliant Reserved 214: 15: Not supported
4	3	Not Used $(= 0)$		-	
7	1	Message Type	MT	Defines the message type	Enum: 1: Fan status
8	2	Not Used $(= 0)$			
10		Room Size Reference	RSR	States if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Reserved 3: Not supported

12	4	Room Size Status	RSS	Room size status	Enum:	
					0: < 25	m²
					1: 25	50 m²
					2: 50	75 m²
					3: 75	100 m²
					4: 100	.125 m²
					5: 125	.150 m²
					6: 150	.175 m²
					7: 175	.200 m²
					8: 200	.225 m²
					9: 225	.250 m²
					10: 250	.275 m²
					11: 275	.300 m²
					12: 300.	
					13: 325	
					14: > 35	
					15: Not s	upported
16	8	Not Used (= 0)	1			
24	8	Fan Speed Status	FSS	Fan speed	Enum:	
					0100:	0100%
						Reserved
					101254:	
					255:	Not
						supported

RORG	D2	VLD Telegram	
FUNC	20	Fan Control	
ТҮРЕ	02	Type 0x02	

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition : 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0 7	7	Not Used (= 0)		•	
7 :	1	Message Type	МТ	Defines the message type	Enum: 0: Fan control
8 2	2	Not Used (= 0)			
10 2		Room Size Reference	RSR	Defines if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Default 3: No change
12 4	4	Room Size	RS	Defines the room size	Enum: 0: < 25 m ² 1: 2550 m ² 2: 5075 m ² 3: 75100 m ² 4: 100125 m ² 5: 125150 m ² 6: 150175 m ² 7: 175200 m ² 8: 200225 m ² 9: 225250 m ² 10: 250275 m ²

					11: 275. 12: 300. 13: 325. 14: > 35 15: No c	325 m ² 350 m ² 0 m ²
16	8	Not Used (= 0)				
24	8	Fan Speed *	FS	Sets the fan speed	Enum: 0100: 101252:	0100% Reserved
					253:	Auto
					254:	Default
					255:	No change

Telegram Definition : 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	Not Used (= 0)					
7	1	Message Type	MT	Defines the message type	Enum:		
					1: Fan sta	tus	
8	2	Humidity Control	HCS	States if the humidity control is active	Enum:		
		Status			0: Disable	d	-
					1: Enabled	ł	_
					2: Reserve	ed	-
					3: Not sup	ported	
10	2	Room Size	RSR	States if the provided room size has to be	Enum:		
		Reference		considered	0: Used		_
					1: Not use	d	_
					2: Reserve	ed	
					3: Not sup	ported	
12	4	Room Size Status	RSS	Room size status	Enum:		
					0: < 25 m	2	-
					1: 2550	m²	_
					2: 5075	m²	-
					3: 7510	0 m²	-
					4: 1001	25 m²	
					5: 1251	50 m²	
					6: 1501	75 m²	
					7: 1752	00 m²	_
					8: 2002	25 m²	
					9: 2252	50 m²	_
					10: 2502		_
					11: 2753		_
					12: 3003		
					13: 3253		_
					14: > 350 r		_
					15: Not sup	ported	
16	8	Not Used (= 0)					
24	8	Fan Speed Status	FSS	Fan speed	Enum:		
					-	100%	
						eserved	
					101254:		
						ot	
					รเ	upported	

D2-30: Floor Heating Controls and Automated Meter Reading

Floor heating controls and automated meter reading gateway may appear combined in one device, but the metering functionality can also be absent.

The floor heating control unit controls a number of valves for separate heating circuits (e.g. for separate heating of single rooms). It measures the common hot water supply temperature as well as the return water temperatures of each single circuit.

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered Communication interval: minimum 1-1000 s, maximum 1000 s Trigger event: heartbeat 1000 s, value change in "Position", "Return Temperature", "Status/Error", "Supply Temperature", "Meter Reading" while respecting the minimum reporting interval Tx delay: 500 ms (maximum response time, first telegram) Rx timeout: 0 ms (minimum time between two received messages) Teach-in method: Universal teach-in (outbound) Encryption required : no Security level format : 0

EEP Family Table (Only for VLD EEP families)

Each TYPE has to support every parameter that is marked in its column!

Supported function	Type 0x00	Туре	0x01	Ту	pe 0x02	Type 0x03	Type 0x04
Number of heating channels/valves	4	8		8	•	8	8
Number of supported MBUS meters	0	0		8		10	10
Number of supported S0 meters	0	0		0		0	1
Number of supported D0 meters	0	0		0		0	0

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

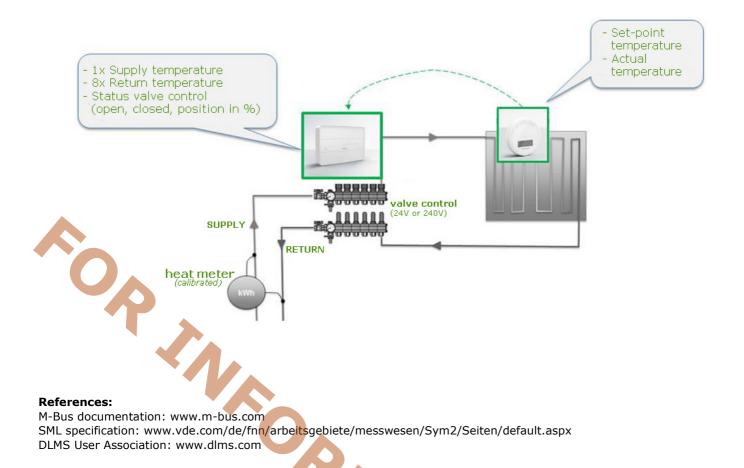
D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

Application example for floor heating controls



RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
ТҮРЕ	00	Type 0x00

Submitter: MSR-Solutions

CMD 0x1 - Set heating controls output

This message is sent to a floor heating actuator. It controls the valve position of one channel or of all channels of the floor heating controls.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0		Valve control period / PWM signal interval		Total on-off time for two-position valve controller (T valve open + T valve closed)	Enum: 0:	chang	default / je	no
					1: 2: 3:	1 s 2 s 5 s		
					4: 5:	10 s 20 s		
					6: 7:	50 s 100 s		
					8: 9:	200 s		
					10: 1115:	1000 Reser	-	
4	4	Command ID	CMD	Command identifier	Enum: 0x01:1	ID 01	_	

1 1

1

8	2	Not Used (= 0)			
10	1	Valve type	VTYP	Type of connected valve	Enum: 0: Valve normally closed (N.C.) 1: Valve normally open (N.O.)
11	5	Heating channel	НСН	The heating channel that should be set	Enum: 015: A valid channel number Reserved 1630: 31: All valid channels
16	1	Run init sequence	RIN	Measure and store the valve zero point	Enum: 0: No action 1: Run init sequence
17	7	Valve position set point	POS	Valve set point 0100% (0=closed, 100=open)	0100 0100 %

CMD 0x2 - Heating controls status query

This message is sent to a floor heating actuator. It requests the status of one channel or the status of the global control unit of an actuator.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut		Description		Valid Rang	e Sc	ale	Unit
0	4	Not Used (= 0)							
4	4	Command ID	CMD	Command	identifier	Enur	n:			
						0x	02: ID 02			
8	3	Not Used (= 0)							
11		Heating	НСН		ng channel that shou	uld Enur	n:			
		channel		be reporte	ed 💦	0	.15: A valid	channel nur	nber	
							Reserve	ed		
						16	*			
						29	: All valio	d channels		
						30		d channels a	nd glo	bal
							device		<u> </u>	
						31	: Global	device statu	s only	
		_		-	oonse / CH = 0			0	1	
		e is sent by a f status query" h		ceived (CN		ing events	occurs:			
- Statu	s of o	one channel or			nged. num send delay 1 s.					

CMD 0x3 - Heating controls status response / CH = 0...15

If the response is for single channel data (CH = 0...15):

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used $(= 0)$					
4	4	Command ID	CMD	Command identifier	Enum: 0x03: ID 03		
8	3	Status / Error		Status / Error indication of given channel	Enum: 0: No fault 1: General err 2: Init sequen 3: Channel no 4: Temperatur	ce running t available	ror

					5: Valve error 6: Temperatu valve error	re sensor a	nd
					7: Reserved		
11	5	Heating channel	HCH	The heating channel that is reported	Enum:		
					015: A valid	channel nur	nber
					1631: Reserve	ed	
16	1	Not Used (= 0)					-
17	7	Valve position		Actual valve position 0100% (0=closed, 100=open)	0100	0100	%
24	-	Return temperature		The current return temperature of the channel	0180	090	°C



If the response is for global floor heating controls unit data (CH = 31):

	-					_		
Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	4	Not Used $(= 0)$						
4	4	Command ID	CMD	Command identifier	Enum:			
					0x03	: ID 03		
8	3	Status / Error	STATUS	Global unit status	Enum:			
					0:	No fault		
					1:	General e	error	
					2:	Supply te	mperatu	re
						error		
					3:	Return te	mperatu	re
					4:	error Error on l	oth sen	sore
					т.			5013
					57:	Reserved		
11	5	Heating channel	НСН	The heating channel that is reported	Enum:			
				(=global unit)	31:	Unit status	s only	
16		Supply temperature	TSUP	The current supply temperature of the unit	0180		090	°C
2.4			TDET		0 100		0 00	20
24	-	Return	TRET	The current common return temperature	0180		090	°C
		temperature						

 24
 8
 Recommendation

 CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

 This message is sent to a metering device gateway to configure the meter settings for one channel.

 This message is sent to a metering device gateway to configure the meter settings for one channel.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report measurement		Minimum auto reporting interval	Enum: 0: No auto repo 1: Min. 1 s inter 2: Min. 3 s inter 3: Min. 10 s inter 4: Min. 30 s inter 5: Min. 100 s in 6: Min. 300 s in 7: Min. 1000 s in 815: Reserved	rval rval erval erval terval terval	
4	4	Command ID	CMD	Command identifier	Enum: 0x06: ID 06		
8	1	Not Used (= 0)					

0	2	Motor bus twee	BUS	The meter bug that should be	E			
9	2	Meter bus type	BUS	The meter bus that should be configured	Enum			
				configured	0:	Reserved		
					1:	MBUS		
					2:	S0		
					3:	D0		
11	5	Meter channel	MCH	The meter bus that should be	030		030	1
		index		configured				
16	2	Not Used $(= 0)$						
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum	:		
				quantity	0:	No reading (ur	configured)	
				(imported value)	1:	Current value value kWh		ed
					2:	Current value	W, accumulat	ed
					3:	Accumulated v	alue kWh onl	у
					4:	Current value value m3	m3/h, accum	ulated
					5:	Current value value dm3	dm3/h, accun	nulated
					6:	Accumulated v	alue m3 only	
					7:	Digital counter	•	
21	3	Meter 2 units	UNIT2	Physical units of second	Enum	-		
	~			measured quantity	0:	No reading (ur	configured)	
				(exported value)	1:	Current value		od
						value kWh		
					2:	Current value Value Value Wh	W, accumulat	ed
					3:	Accumulated v	alue kWh onl	у
					4:	Current value value m3	m3/h, accum	ulated
					5:	Current value value dm3	dm3/h, accun	nulated
					6:	Accumulated v	alue m3 only	
					7:	Digital counter		
24	0	Drimony Address		The primary MDUC address of			1	1
24	8	Primary Address	ADDR	The primary MBUS address of the meter	125	U	1250	1
32	40	Not Used $(= 0)$						

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

32	40	Not Used (= 0)		he meter	
			figuration	/ S0 (BUS = 2)	0
Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
D	4	Report measurement	RM	Minimum auto reporting interval	Enum:0:No auto reporting1:Min. 1 s interval2:Min. 3 s interval3:Min. 10 s interval4:Min. 30 s interval5:Min. 100 s interval6:Min. 300 s interval7:Min. 1000 s interval815: Reserved
4	4	Command ID	CMD	Command identifier	Enum: 0x06: ID 06
8	1	Not Used (= 0)	- -	•	
9		Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0

16 18 21	2 3	Not Used (= 0) Meter 1 units	UNIT1	that should be configured Physical units of first measured quantity (imported value)	Enum: 0: No reading (unconfigured) 1: Current value W, accumulated value kWh 2: Current value W, accumulated value Wh 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h, accumulated value dm2
18			UNIT1	quantity	0:No reading (unconfigured)1:Current value W, accumulated value kWh2:Current value W, accumulated value Wh3:Accumulated value kWh only4:Current value m3/h, accumulated value m35:Current value dm3/h,
21	3				 Current value W, accumulated value kWh Current value W, accumulated value Wh Accumulated value kWh only Current value m3/h, accumulated value m3 Current value dm3/h,
21	3			(imported value)	 Current value W, accumulated value kWh Current value W, accumulated value Wh Accumulated value kWh only Current value m3/h, accumulated value m3 Current value dm3/h,
21	3				 2: Current value W, accumulated value Wh 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h,
21	3				 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h,
21	3				 4: Current value m3/h, accumulated value m3 5: Current value dm3/h,
21	3				5: Current value dm3/h,
21	3				
21	3				accumulated value dm3
21	3				6: Accumulated value m3 only
21	3				7: Digital counter
		Meter 2 units	UNIT2	Physical units of second	Enum:
				measured quantity	0: No reading (unconfigured)
		P		(exported value)	1: Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
					3: Accumulated value kWh only
					4: Current value m3/h,
					accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
24	2	Factor of number of	FACP	The factor for the number of	Enum:
		pulses		pulses	0: 1
				per value in UNIT1	1: 0.1
					2: 0.01
					3: 0.001
26	14	Number of pulses	NOP	The number of pulses per value	Enum:
20	14	Number of pulses	1101	in UNIT1* FACP	
					0: Do not change the current setting of NOP
				×	Number of pulses per unit
40	32	Preset value	RST	Preset the accumulated value to	Enum:
10	52		NOT	this value	
					New preset value 04294967294:
					0xFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
					current value
CMD	0x6	- Set meter confi	guration	n / D0 (BUS = 3)	

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

Offset	Size	Data	ShortCut	Description	Va	lid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:			
		measurement			0:	No auto reporting Min. 1 s interval Min. 3 s interval		
					1:			
					2: Min. 3 s interva			
				3: Min. 1	Min. 10 s interval			
					4:	Min. 30 s inte	erval	
					5:	Min. 100 s in	terval	
					6:	Min. 300 s in	terval	
					7:	Min. 1000 s i	nterval	
					81	5: Reserved		
4	4	Command ID	CMD	Command identifier	Enum:			
					0x06	: ID 06		

5	Meter bus type Meter channel index Not Used (= 0) Meter 1 units Meter 2 units	BUS MCH UNIT1	The meter bus that should be configured The meter number of given bus that should be configured Physical units of first measured quantity (imported value)	1: MI 2: SC 3: DC 030 030 Enum: 0: 0: No 1: Cu 2: Cu 2: Cu 3: Ac 4: Cu 5: Cu 6: Ac			
2	index Not Used (= 0) Meter 1 units	UNIT1	The meter number of given bus that should be configured Physical units of first measured quantity	1: MI 2: SC 3: DC 030 030 Enum: 0: 0: No 1: Cu 2: Cu 2: Cu 3: Ac 4: Cu 5: Cu 6: Ac	BUS D D D D D D D D D D D D D D D D D D D		
2	index Not Used (= 0) Meter 1 units	UNIT1	Physical units of first measured quantity	2: S0 3: D0 030 Enum: 0: No 1: Cu va 2: Cu va 3: Ao 4: Cu ac 5: Cu ac 6: Ao	030 1 030 1 0 reading (unconfigured) urrent value W, accumulated ulue kWh urrent value W, accumulated ulue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
2	index Not Used (= 0) Meter 1 units	UNIT1	Physical units of first measured quantity	3: D0 030 Enum: 0: No 1: Cu va 2: Cu va 3: Ao 4: Cu ac 5: Cu ac 6: Ao	0 reading (unconfigured) urrent value W, accumulated ulue kWh urrent value W, accumulated ulue Wh cumulated value kWh only urrent value m3/h, cumulated value m3 urrent value dm3/h, cumulated value dm3/h, cumulated value dm3		
2	index Not Used (= 0) Meter 1 units	UNIT1	Physical units of first measured quantity	030 Enum: 0: No 1: Cu va 2: Cu va 3: Ac 4: Cu ac 5: Cu ac 6: Ac	030 1 p reading (unconfigured) urrent value W, accumulated ulue kWh urrent value W, accumulated ulue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3/h, ccumulated value dm3		
2	index Not Used (= 0) Meter 1 units	UNIT1	Physical units of first measured quantity	Enum: 0: No 1: Cu va 2: Cu va 3: Ac 4: Cu ac 5: Cu ac 6: Ac	o reading (unconfigured) urrent value W, accumulated ulue kWh urrent value W, accumulated ulue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
3	Meter 1 units		quantity	0: No 1: Cu va 2: Cu va 3: Ac 4: Cu ac 5: Cu ac 6: Ac	urrent value W, accumulated ilue kWh urrent value W, accumulated ilue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
			quantity	0: No 1: Cu va 2: Cu va 3: Ac 4: Cu ac 5: Cu ac 6: Ac	urrent value W, accumulated ilue kWh urrent value W, accumulated ilue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
3	Meter 2 units			1: Cu va 2: Cu va 3: Ac 4: Cu ac 5: Cu ac 6: Ac	urrent value W, accumulated ilue kWh urrent value W, accumulated ilue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
3	Meter 2 units			2: Cu va 3: Ac 4: Cu ac 5: Cu ac 6: Ac	ulue kWh urrent value W, accumulated ulue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
3	Meter 2 units			va 3: Ac 4: Cu 5: Cu 6: Ac	ulue Wh ccumulated value kWh only urrent value m3/h, ccumulated value m3 urrent value dm3/h, ccumulated value dm3		
3	Meter 2 units			4: Cu ac 5: Cu ac 6: Ac	urrent value m3/h, cumulated value m3 urrent value dm3/h, cumulated value dm3		
3	Meter 2 units			4: Cu ac 5: Cu ac 6: Ac	urrent value m3/h, cumulated value m3 urrent value dm3/h, cumulated value dm3		
3	Meter 2 units			25: Cu 30: Ac	cumulated value m3 urrent value dm3/h, cumulated value dm3		
3	Meter 2 units			ac 6: Ac	cumulated value dm3		
3	Meter 2 units			6: Ac			
3	Meter 2 units				cumulated value m3 only		
3	Meter 2 units			7: Di			
3	Meter 2 units				gital counter		
		UNIT2	Physical units of second measured	-			
			quantity (exported value)				
				1: Current value W, accumulated value kWh			
					urrent value W, accumulated lue Wh		
				3: Ac	cumulated value kWh only		
					ırrent value m3/h,		
					cumulated value m3		
					urrent value dm3/h,		
					cumulated value dm3		
					cumulated value m3 only		
2	D0 Droto col	DDOT	The D0 protocol that should be		gital counter		
J		PROT			Auto dotoct		
					Auto detect SML (Smart Message		
					Language)		
					DLMS (Device Language		
					Message Specification)		
					Reserved		
40	Not Used $(= 0)$			0			
		Query			K		
x	0 (7 - sag	0 Not Used (= 0) 7 - Meter Status sage is sent to a met	0 Not Used (= 0) 7 - Meter Status Query sage is sent to a metering devi	0 Not Used (= 0) x7 - Meter Status Query sage is sent to a metering device gateway to query the status of a	2: Cu 3: Ac 4: Cu ac 5: Cu ac 6: Ac 7: Di D0 Protocol PROT The D0 protocol that should be used for that meter 0: 1: 2: 0 Not Used (= 0)		

CMD 0x7 - Meter Status Query

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit			
0	4	Not Used (= 0)						
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07			
8	1	Not Used (= 0)	ot Used (= 0)					
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum: 0: Reserved 1: MBUS 2: S0			
					3: D0			

11	5	Meter channel	MCH	The meter channel of given bus that status is	Enum:	
		index		queried		Meter channel
					030:	
					31:	All valid
						channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message "meter status query" has been received (CMD 0x7)

- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0)		-			
1	3	Meter status / error		Meter channel status	Enum: 0: No faul 1: Genera 2: Bus uno		
			Ņ		4: Bus sho 5: Commu 6: Unknov configu	connected ortcut unication timeout vn protocol or ration mismatch cialization running	
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08	_	
8	1	Not Used (= 0))				
9	2	Meter bus type	BUS	The used bus of the meter status response	Enum: 0: Reserve 1: MBUS 2: \$0 3: D0	ed	
11	5	Meter channel index	МСН	The meter number of given bus that status is reported	030	030	1
16	3	Not Used $(= 0)$)				
19	2	Value selection	VSEL	The selection of the reported value	1: Meter 1 2: Meter 2	Current value Accumulated val Current value Accumulated val	
21	3	Value unit	VUNIT	The unit of the reported value		al counter)	
24	32	Meter reading value	VAL	The reported value	0429496729	95 04294967295	5 According to VUNIT

RORG	D2	VLD Telegram
FUNC 30		Floor Heating Controls and Automated Meter Reading
TYPE	01	Type 0x01 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
ТҮРЕ	02	Type 0x02 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
ТҮРЕ	03	Type 0x03 (description: see table)
See profile: D2	-30-00	
RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
ТҮРЕ	04	Type 0x04 (description: see table)
See profile: D2	-30-00	R _M

D2-31: Automated Meter Reading Gateway

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered Communication interval: minimum 1-1000 s (configuration item), maximum 1000 s Trigger event: heartbeat 1000 s, value change in "Status/Error", "Meter Reading" while respecting the minimum reporting interval Tx delay: 500 ms (maximum response time, first telegram) Rx timeout: 0 ms (minimum time between two received messages) Teach-in method: Universal teach-in (outbound) Encryption required : no Security level format : 0

Telegram Definition The telegram definition is inherited from profile D2-30-xx and thus identical to the definition there.

EEP Family Table (Only for VLD EEP families)

Each TYPE has to support every parameter that is marked in its column!

Supported function	Type 0x00	Type 0x01
Number of supported MBUS meters	10	16
Number of supported S0 meters	2	0
Number of supported D0 meters	2	0

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

References:

M-Bus documentation: www.m-bus.com SML specification: www.vde.com/de/fnn/arbeitsgebiete/messwesen/Sym2/Seiten/default.aspx DLMS User Association: www.dlms.com

RORG	D2	VLD Telegram
FUNC	31	Automated Meter Reading Gateway
ТҮРЕ	00	Type 0x00

Submitter: MSR-Solutions

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data S	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report F measurement	RΜ	Minimum auto reporting interval	Enum: 0: No auto rep 1: Min. 1 s into 2: Min. 3 s into 3: Min. 10 s in 4: Min. 30 s in 5: Min. 100 s i 6: Min. 300 s i	No auto reporting Min. 1 s interval Min. 3 s interval Min. 10 s interval Min. 30 s interval Min. 100 s interval Min. 300 s interval Min. 1000 s interval 15: Reserved	
4	4	Command ID (CMD	Command identifier	Enum: 0x06: ID 06		
8	1	Not Used (= 0)					
9	2	Meter bus type E		The meter bus that should be configured	Enum: 0: Reserved 1: MBUS		

70,

	1		1		ı——				
					2:	S0			
					3:	D0			
11	5	Meter channel	МСН	The meter number of given bus that	030	1	030	1	
1.6		index		should be configured					
16	2	Not Used (= 0)							
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity	Enum				
				(imported value)	0: No reading (unconfigured)				
					1: Current value W, accumulated value kWh				
						2: Current value W, accumulated value Wh			
					3:	Accumulated	value kWh	only	
					4: Current value m3/h, accumulated value m3				
					5:	Current valu	e dm3/h,		
						accumulated			
					6:	Accumulated	l value m3 o	nly	
					7:	Digital count	er		
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum	:			
		72		quantity (exported value)	0: No reading (unconfigured)				
					1: Current value W, accumulated value kWh				
					2:	Current valu value Wh	e W, accumu	llated	
					3:	Accumulated	l value kWh	only	
					4:	Current valu	e m3/h,		
						accumulated	value m3		
					5: Current value dm3/h, accumulated value dm3				
					6:	Accumulated	value m3 o	nly	
					7:	Digital count			
24	8	Primary Address	ADDR	The primary MBUS address of the	125	0	1250	1	
				meter					
32	40	Not Used (= 0)							

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

24	8	Primary Address		neter	1250	1250	T
32	40	Not Used $(= 0)$					
CMD	0x6 ·	- Set meter con	figuratior	n / S0 (BUS = 2)	0		
Offset	t Size	Data	ShortCu	t Description	Valid Range	Scale	Unit
0	4	Report measurement Command ID	RM	Minimum auto reporting interval	Enum: 0: No auto re 1: Min. 1 s int 2: Min. 3 s int 3: Min. 10 s in 4: Min. 30 s in 5: Min. 100 s 6: Min. 300 s 7: Min. 1000 815: Reserved Enum:	erval terval nterval nterval interval interval	
0	1				0x06: ID 06		
8	1	Not Used (= 0)	240				
9	2	Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0		
11	5	Meter channel index	МСН	The meter number of given bus that should be configured	030	030	1
16	2	Not Used $(= 0)$					

18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:
				quantity	0: No reading (unconfigured)
				(imported value)	1: Current value W, accumulated
					value kWh
					2: Current value W, accumulated
					value Wh
					3: Accumulated value kWh only
					4: Current value m3/h,
					accumulated value m3
					 Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second	Enum:
			0.1112	measured quantity	0: No reading (unconfigured)
				(exported value)	1: Current value W, accumulated
					value kWh
					2: Current value W, accumulated
					value Wh
					3: Accumulated value kWh only
					4: Current value m3/h,
					accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
24	2	Factor of number of	FACP	The factor for the number of	Enum:
		pulses		pulses	0: 1
				per value in UNIT1	1: 0.1
					2: 0.01
					3: 0.001
26	14	Number of pulses	NOP	The number of pulses per value	Enum:
				in UNIT1* FACP	0: Do not change the current
					setting of NOP
					Number of pulses per unit
					165535:
40	32	Preset value	RST	Preset the accumulated value to	Enum:
				this value	New preset value
					04294967294:
					0xFFFFFFFF; Do not change the
					current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

CMD 0)x6 ·	- Set meter co	onfiguratio	on / D0 (BUS = 3)	0xFFFFFFFF: Do not change current value	e the
Offset	Size	Data	ShortCut	Description	Valid Range Scale	Unit
0	4	Report measurement	RM	Minimum auto reporting interval	Enum:0:No auto reporting1:Min. 1 s interval2:Min. 3 s interval3:Min. 10 s interval4:Min. 30 s interval5:Min. 100 s interval6:Min. 300 s interval7:Min. 1000 s interval815: Reserved	
4	4	Command ID	CMD	Command identifier	Enum: 0x06: ID 06	
8	1	Not Used (= 0)			1	

9	2	Meter bus type	BUS	The meter bus that should be	Enum	:		
				configured	0:	Reserved		
					1:	MBUS		
					2:	SO		
					3:	D0		
11	5	Meter channel	МСН	The meter number of given bus	030		030	1
		index		that should be configured				
16	2	Not Used (= 0)						
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum	:		
				quantity (imported value)	0:	No reading (un		
					1:	Current value V value kWh	N, accumu	ated
					2: Current value W, accumulated			
						value Wh	- .)	
					3:	Accumulated v		niy
					4:	Current value r accumulated va		
					5:	5: Current value dm3/h, accumulated value dm3		
					6:	Accumulated v		lv
					7:	Digital counter		• /
21	3	Meter 2 units	UNIT2	Physical units of second measured				
	5			quantity	0:	No reading (un	configured)
			K	(exported value)	1:	Current value V		
						value kWh	,	
					2:	Current value V value Wh	N, accumu	ated
					3:	Accumulated v	alue kWh o	nly
					4:	Current value r	m3/h,	
						accumulated va	alue m3	
					5:	Current value of		
						accumulated va		
					6: Accumulated value m3 only			
24	0	D0 Protocol	DROT	The D0 protocol that should be	7:	Digital counter		
24	8	D0 Protocol	PROT	The D0 protocol that should be used for that meter	Enum	: Auto detect		
					0: 1:	SML (Smart	Massaga	
						Language)	nessaye	
					2:	DLMS (Devic		е
						Message Spe	ecification)	
					325	Reserved		
32	40	Not Used (= 0)			525	5.		
		- Meter Status	Query				う	
	essag			ce gateway to query the status of a	meter			٢,

CMD 0x7 - Meter Status Query

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit						
0	4	Not Used (= 0)									
4	4	Command ID	0x07: ID 07								
8	1	Not Used (= 0)	Used (= 0)								
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum: 0: Reserved 1: MBUS 2: S0 3: D0						

11	5	Meter channel	MCH	The meter channel of given bus that status is	Enum:	
		index		queried		Meter channel
					030:	
					31:	All valid
						channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message "meter status query" has been received (CMD 0x7)

- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Not Used (= 0)					
1	3	Meter status / error		Meter channel status	3: Bus und 4: Bus sho 5: Commu 6: Unknow configu	l error configured connected	
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08		
8	1	Not Used $(= 0)$)				
9	2	Meter bus type	BUS	The used bus of the meter status response	Enum: 0: Reserve 1: MBUS 2: \$0 3: D0	ed	
11	5	Meter channel index	МСН	The meter number of given bus that status is reported	030	030	1
16	3	Not Used $(= 0)$)	· · ·			
19	2	Value selection	VSEL	The selection of the reported value	1: Meter 1 2: Meter 2	Current value Accumulated val Current value Accumulated val	
21	3	Value unit	VUNIT	The unit of the reported value		al counter)	
24	32	Meter reading value	VAL	The reported value	0429496729	95 04294967295	According to VUNIT

RORG	D2	VLD Telegram
FUNC	31	Automated Meter Reading Gateway
TYPE	01	Type 0x01 (description: see table)

See profile: D2-31-00

D2-A0: Standard Valve

RORG	D2	VLD Telegram
FUNC	A0	Standard Valve
ТҮРЕ	01	Valve Control (BI-DIR)

Submitter: Afriso / EnOcean

Description:

Radio operated valve control with feedback message. Valve is controlled through the air interface to be opened or closed. The valve reports the actual status after finishing the determined operation.

Data exchange

Direction: bidirectional

Addressing: addressed (inbound) and broadcast (outbound) Communication trigger: event- & time-triggered Trigger event: position of valve has changed Teach-in method: UTE

DIRECTION-1 = Outbound (water valve to the controller) Description: Valve reports its status. Report is sent after operation was executed or as a heartbeat.

DIRECTION-2 = Inbound (controller to the water valve) Description: Operational command to the valve. After this request a feedback response will be transmitted, once the operation is finished.

A "no change"-command will also be followed by a feedback response. Therefore, it can be used as a status request.

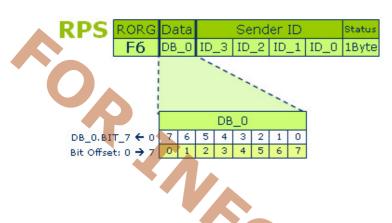
DIRECTION-1

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	6	Not Used	(= 0)					
6	2	Feedback	FDB	Return	Enum:			
					0b00: Not o	defined		
					0b01: Closed			
					0b10: Oper	ned		
					0b11: Not o	defined		

0	6	Not Used	d (= 0)							
6	2	Feedback	< FDB	Return	Enum:					
					0b00: Not de	fined				
					0b01: Closed	<u> </u>				
					0b10: Opene	d				
					0b11: Not de	efined				
DIRECT	TION-	2								
Offset	Size	Data	ShortCut	Desci	ription	Valie	d Range	Scale	Unit	
0	6	Not Used	d (= 0)							
6	2	Request	REQ	Request to op	erate the valve	Enum:				
						0b00: N	lo change (red	quest of fee	edback)	
						0b01: R	equest to clos	se valve		
						0b10: R	equest to ope	n valve		
						0b11:R	equest to clos	se valve		

3) Appendix

3.1) RPS Teach-in



The RPS telegram can only send data and has no special telegram modification to teach-in the device. Therefore, the teach-in procedure takes place manually on the actuator/controller through a normal data telegram. The EEP profile must be manually supplied to the controller per sender ID.

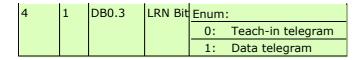
In learn mode, the receiving actuator reduces the input sensitivity in order to fade out weakly received data telegrams. This helps avoid inadvertently teaching-in sensors.

3.2) 1BS Teach-in		
1BS RORG D5	DataSender IDStatusDB_0ID_3ID_2ID_1ID_01Byte	
	DB_0	
DB_0.BIT_7 ← 0 Bit Offset: 0 → 7		

The 1BS telegram has its own teach-in telegram, which can signal the teach-in command through the DB_0.BIT_3 data bit.

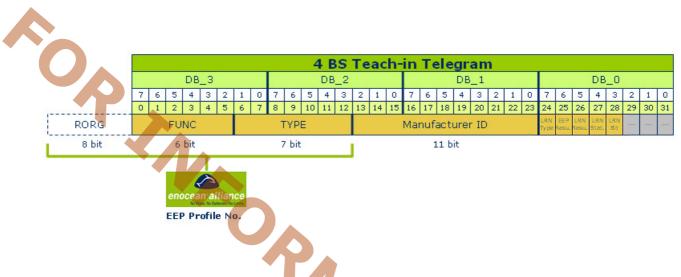
Offset Size Bitrange Data Valid Range Scale Unit

EEP 2.6 Specification



Here, an EEP profile must also be manually allocated per sender ID.

3.3) 4BS Teach-in



The 4BS telegram also has its own teach-in telegram, however with more teach-in variations:

Variation 1

The profile-less unidirectional teach-in procedure functions according to the same principle as the 1BS telegram: if the data bit is $DB_0.BIT_3 = 0$, then a teach-in telegram is sent. This includes the 'LRN TYPE' $DB_0.BIT_7 = 0$ data bit. Then no EEP profile identifier and no manufacturer ID are transferred.

Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum:			
				0:	telegram without EEP	and Manufac	turer ID
28	1	DB0.3	LRN Bit	Enum:			
				0:	Teach-in telegram		
				1:	Data telegram		



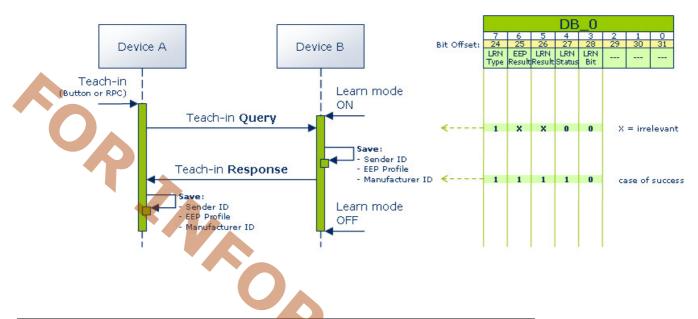
Variation 2

For the unidirectional profile teach-in procedure, it is preferred in opposite to variation 1), as the teach-in telegram contains both the complete EEP number and the manufacturer ID. The device is therefore clearly identifiable as ready-to-use and can be securely executed in a complex system environment or by foreign systems. In this case, the 'LRN TYPE' data bit is $DB_0.BIT_7 = 1$.

Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum			
				1:	telegram with EEP nu	mber and Manufa	acturer ID
28	1	DB0.3	LRN Bit	Enum	:		
				0:	Teach-in telegram		
				1:	Data telegram		

Variation 3

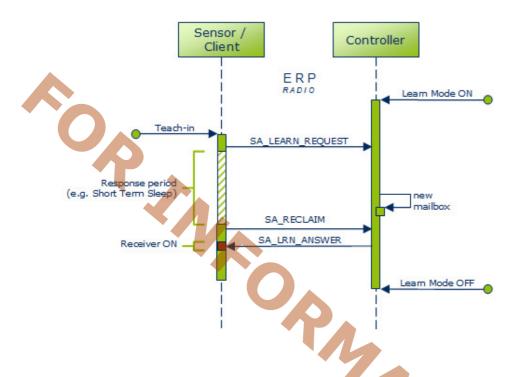
During the bidirectional teach-in procedure, further bits are required from the DB_0, in order to develop the mutual teach-in between two communication partners. For this, the procedure is made up of 2 teach-in telegrams, which are exchanged on both sides. The following UML diagram is used to illustrate this:



0: telegram without EEP and Manufacturer ID 1: telegram with EEP number and Manufacturer ID 25 1 DB0.6 EEP Result 26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 0: Sender ID stored 27 1 DB0.4 LRN Status Enum: 0: Query 1: Response	Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
25 1 DB0.6 EEP Result Enum: 0: EEP not supported 26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 27 1 DB0.4 LRN Status Enum: 0: Query 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram	24	1	DB0.7	LRN Type	Enum			
25 1 DB0.6 EEP Result Enum: 0: EEP not supported 26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 27 1 DB0.4 LRN Status Enum: 0: Query 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram					0:	telegram without EEP ar	nd Manufacture	er ID
0: EEP not supported 1: EEP supported 26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 27 1 DB0.4 LRN Status Enum: 0: Query 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram					1:	telegram with EEP numb	per and Manufa	acturer ID
26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 27 1 DB0.4 LRN Status Enum: 0: Query 1: Response 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram	25	1	DB0.6	EEP Result	Enum			
26 1 DB0.5 LRN Result Enum: 0: Sender ID deleted/not stored 27 1 DB0.4 LRN Status Enum: 0: Query 27 1 DB0.4 LRN Status Enum: 0: Query 1: Response 1: Response 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram 0: Teach-in telegram 1: Teach-in telegram					0:	EEP not supported		
0: Sender ID deleted/not stored 1: Sender ID stored 27 1 DB0.4 LRN Status Enum: 0: Query 1: Response 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram								•
27 1 DB0.4 LRN Status Enum: 0: Query 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram	26	1	DB0.5	LRN Result	Enum			
27 1 DB0.4 LRN Status Enum: 0: Query 1: Response 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram					0:	Sender ID deleted/not s	tored	
0: Query 1: Response 28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram					1:	Sender ID stored		
1: Response 28 1 DB0.3 LRN Bit Enum: 0: 0: Teach-in telegram	27	1	DB0.4	LRN Status	Enum	<u> </u>		
28 1 DB0.3 LRN Bit Enum: 0: Teach-in telegram					0:	Query		
0: Teach-in telegram					1:	Response		
	28	1	DB0.3	LRN Bit	Enum	<u> </u>		
1: Data telegram					0:	Teach-in telegram		
					1:	Data telegram		

3.4) Smart Ack Teach-in (without repeater)

Under Smart Ack (SA), the teach-in procedure is more complex as, alongside the SA client and SA controller, a Postmaster must also be established to prepare a mailbox for each taught-in SA client. The Postmaster is normally found in the controller. If a repeater is installed, then a postmaster is set up there.



After the learn mode is activated on the controller, the teach-in procedure can be started on the client. The client sends an SA_LEARN_REQUEST telegram:

															-
RORG Re	q. Manuf.ID	EEF	P (3 by	te)	RSSI		Repea	ater ID			Send	der ID		Status	СНСК
C6 5 b	oit 11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
Requi															
Data	Valu	e			Descr	iption									
lest Code	0b11111		Defau	lt valu	e – sei	nd by s	sensor								
ufacturer ID	0bnnnnn	nnnnn	Corres	spondi	ng to t	he tea	ch-in s	sensor							
No.	0xnnnnn RORG, FUNC, TYPE														
[0x00		0 = W	/ithout	repea	ter									
eater ID	0x000000	00	0 = W	/ithout	repea	ter									
ler ID	er ID 0xnnnnnnn			D of se	ensor f	for tea	ch-in								
	005		0.5				the state								

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	Obnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0x00	0 = Without repeater
Repeater ID	0x0000000	0 = Without repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
СНСК	0xnn	Checksum

During the 'response period' in the SA client, which is always 550 ms during the teach-in, the controller creates a new mailbox in its postmaster and leaves its first message there with an OK receipt. This entry is requested from the postmaster by the SA client with an SA_RECLAIM 'Learn' telegram:

Choice	RCLM_ID		Send	ler ID		Status							
A7		ID_3	ID_2	ID_1	ID_0	1Byte							
	<u> </u>	Mailbox Index (only Data Reclaim)											

Data	Value	Description
Message Index	0b0	Bit 7: 0 = Learn Reclaim
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating desired
СНСК	0xnn	Checksum

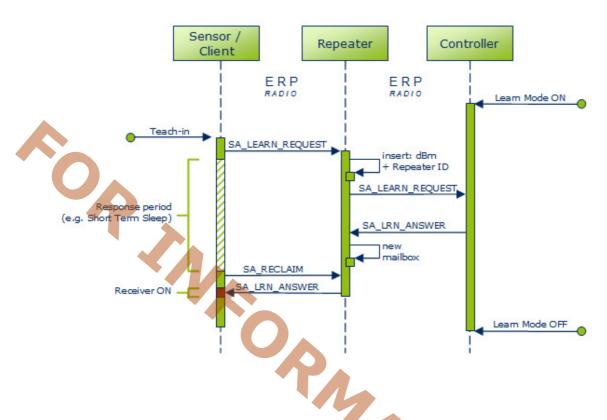
The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:



RORG	RORG-EN	Index	Res	spo	nse	tim	e.	Ack C.	Mailbox		not used	l.		Postma	ster ID			Contro	oller ID		Status	CHCK
0	1	2		3	14	4		5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
A6	C7	02								-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description
RORG 0xA	(A6	A6 = ADR Telegram
RORG-EN 0x0	c7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index 0x0	(02	Message Index; 02 = Learn Acknowledge
Response time 0xr		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value 550 ms = $0x0226$)
Acknowledge 0x0	(00	First Learn In successful
Mailbox index 0xr	nn	Index no. of the assigned mailbox
Postmaster ID 0xr	knnnnnnn	Device ID of the Post master candidate
Controller ID 0xr	knnnnnnn	Device ID of the assigned controller
Status 0x0	(0F	0F = no repeating permitted
CHCK 0xr	nn	Checksum

3.5) Smart Ack Teach-in (with repeater)



If a repeater comes into operation, the SA_LEARN_REQUEST telegram sent by the SA client (with an EEP No., Manufacturer ID, Sender ID) is completed on the repeater with the RSSI value (in dBm) and the Repeater ID, and sent to the controller.

RORG Re	q. Manuf.ID	EEP) (3 byt	te)	RSSI		Repea	ter ID			Send	der ID		Status	СНСК
C6 5 b	oit 11 bit R	ORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
Requi											<u> </u>				
Data	Value				Descr	iption									
uest Code	0b11111		Defau	lt valu	e – sei	nd by s	sensor								
ufacturer ID	0bnnnnnnn	nnnn	Corres	spondi	ng to t	he tea	ch-in s	ensor	sor						
No.	0xnnnnn RORG, FUNC, TYPE														
[0xnn Value added from repeater														
eater ID	0xnnnnnnn	nn Device ID repeater													
ler ID	0xnnnnnnn	n	Chip I	D of se	ensor f	or tea	ch-in								Ť

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	Obnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0xnn	Value added from repeater
Repeater ID	0xnnnnnnn	Device ID repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
СНСК	0xnn	Checksum

From the reception strength of the RSSI, the controller can recognise which repeater is best for the task of postmaster. In the meantime, the SA client will be in its 'response period'.

The sent addressed telegram SA_LRN_ANSWER with the message 'Learn Reply' by the controller to the repeater ensures that the postmaster is activated and a mailbox is created.

RORG	ORG Req. Manuf.ID EEP (3 b)			P (3 by	te)	RSSI	Repeater ID				Sender ID				Status	СНСК	
C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte	
Request Code																	

Data	Value	Description							
RORG	0xA6	A6 = ADR Telegram							
RORG-EN	0xC7	RG encapsulated / C7 = SA_LRN_ANSWER							
Index	0x01	Message Index; 01 = Learn Reply							
Response time	0xnnnn	ponse time for Smart Ack Client in ms in which the controller can prepare the data I send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)							
Acknowledge code	0x00	First Learn In successful							
Sender ID	0xnnnnnnn	Chip ID of sensor to be teach-in							
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate							
Controller ID	0xnnnnnnn	Device ID of the assigned controller							
Status	0x0F	0F = no repeating permitted							
СНСК	0xnn	Checksum							

Also, a mailbox is created for the SA client, where an initial entry with an OK message is left. This information is requested by the SA client from the repeater's postmaster with the SA_RECLAIM 'Learn' telegram.

Choice RCLM_ID		Sender ID	Status
A7	I)_3 ID_2 ID_1 ID_0	1Byte
			ex (only Data Reclaim) m Reclaim / 1 Data Reclaim
Data	Value	Description	
Data age Index		Description Bit 7: 0 = Learn Reclaim	
age Index	0b0		
	0b0 0xnnnnnnn	Bit 7: 0 = Learn Reclaim	
age Index er ID	0b0 0xnnnnnnn	Bit 7: 0 = Learn Reclaim Chip ID of sensor for teach-in	

Data	Value	Description					
Message Index	0b0	Bit 7: 0 = Learn Reclaim					
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in					
Status	0x0F	0F = no repeating desired					
СНСК	0xnn	Checksum					

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart	Ack Le	earn A	nswer	(Learr	n Ackn	owledg	je)														
RORG	RORG-EN	Index	Respon	ise time	Ack C.	Mailbox		not used	l)		Postma	ster ID			Contro	iller ID		Status	CHC	K	
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19		
A6	C7	02					-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0				

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	0F = no repeating permitted

CHCK 0xnn

Checksum

FOR INFORMATION ONLY

3.6) UTE – Universal Uni- and Bidirectional Teach-in

General

Up to now there are teach-in procedures available for:

- RPS communication (EnOcean ID + rocker/channel information, unidirectional)
- 1BS communication (LRN telegram, w/o EEP and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, bidirectional)
- SmartACK communication (self powered devices, bidirectional)

For uni- and bidirectional EEP communication that does not fit into SmartACK communication principles but is based on e.g. MSC and VLD messages no teach-in procedure is defined so far.

Therefore, this document proposes a universal teach-in procedure that allows handling of teach-in and teach-out requirements for EEP based communication of all different RORG. This proposal shall be understood as an alternative to SmartACK teach-in for devices where SmartACK is not applicable.

RORG to be used: **0xD4** Universal Teach-in, EEP based (UTE)

FUNC and TYPE shall be represented as 8bit parameters, both with a value range from 0x00 ... 0xFF. This aligns UTE with the EEP representation defined for SmartACK teach-in.

REMARK 1:

Even though the proposed Universal Tech-In Procedure is able to cover EEPs based on RPS, 1BS and 4BS messages as well, it is not intended to replace the existing RPS, 1BS and 4BS teach-in / teach-out procedures for unidirectional and the existing 4BS teach-in / teach-out procedures for bidirectional communication. However, it is recommended that with the acceptance of the proposed Universal Tech-In Procedure all new bidirectional 4BS applications shall use it for teach-in and teach-out as well.

REMARK 2:

The proposed Universal Tech-In Procedure is dedicated to EEP based EnOcean communication. It does neither compete with nor shall it interfere with the tech-in process of the Generic EnOcean Communication.

Communication – Principles and Definitions

BIDIRECTIONAL EEP-BASED COMMUNICATION

Bidirectional EnOcean communication means a point-to-point communication relationship between two enabled EnOcean devices. It requires all parties involved to know the unique EnOcean ID of their partners. Such point-to-point communication relationship is established with the completion of a successful teach-in process and it is deleted with the completion of a successful teach-out process.

To get a maximum reliable teach-in process with a minimum consumption of energy and resources, a simple query - response mechanism is used: the device that is intended to be taught-in broadcasts a query message and gets back an addresses response message, containing its own EnOcean ID as the transmission target address.

In case there is more than one device ready to accept teach-in query messages at the same time and within the same radio range, the device with the quickest response time will be accepted by the device to be taught-in. Second and further devices will respond as well but they will not be accepted by the device to be taught-in. This will result in a configuration situation that is common to today's EEP based unidirectional teach-in processes.

UNIDIRECTIONAL EEP-BASED COMMUNICATION

Unidirectional EnOcean communication means a point-to-multipoint communication relationship between enabled EnOcean devices. In this case of broadcasting the device to be taught-in to other devices does not know the unique EnOcean ID of those communication partners.

The proposed Universal Teach-In Procedure supports unidirectional EnOcean communication thru related configuration bits in the query message.

However, for specific applications – e.g. configuration feedback - it is also possible to combine a bidirectional teach-in process with a unidirectional EEP based communication during the regular operation of a device.

EEP Teach-In Query - UTE Message (Broadcast / CMD: 0x0)

This message is sent by the EEP based EnOcean device that is intended to be taught-in to another device (which has been set into LRN-mode before either manually or thru a ReMan command).

Response Timing:

If a response is expected it shall be received within a maximum of 700ms from the time of transmission of this message. In case no such response is received within this time frame the query action shall be treated as completed with negative result. If no response is expected, each query action has to be treated as completed with positive result.

TABLE OF 7 BYTE PAYLOAD:

Data	Value	Description						
DB_0	RORG	RORG of EEP [0x00 0xFF]						
DB_1	FUNC	FUNC of EEP [0x00 0xFF]						
DB_2	TYPE	TYPE of EEP [0x00 0xFF]						
DB_3.BIT_73	<u> </u>	Do not use						
DB_3.BIT_20	MID (3MSB)	Manufacturer-ID (3MSB)						
DB_4	MID (8LSB)	Manufacturer-ID (8LSB)						
DB_5	0x00 0xFE	Number of individual channel to be taught in						
"	0xFF	Teach-in of all channels supported by the device						
DB_6.BIT_7	0b0	Unidirectional communication (EEP operation)						
"	0b1	Bidirectional communication (EEP operation)						
DB_6.BIT_6	0b0	EEP Teach-In-Response message expected						
п	0b1	No EEP Teach-In-Response message expected						
DB_6.BIT_54	0b00	Teach-in r <mark>equest</mark>						
"	0b01	Teach-in deletion request						
"	0b10	Teach-in or deletion of teach-in, not specified						
"	0b11	Not used						
DB_6.BIT_30	0x0	Command identifier (CMD): EEP Teach-In Query						

EEP Teach-In Response - UTE Message (Addressed / CMD: 0x1)

This message is the reply to an EEP Teach-In Query message. It is sent by the EEP based EnOcean device that has been set into LRN-mode before (either manually by HMI or thru a ReMan command).

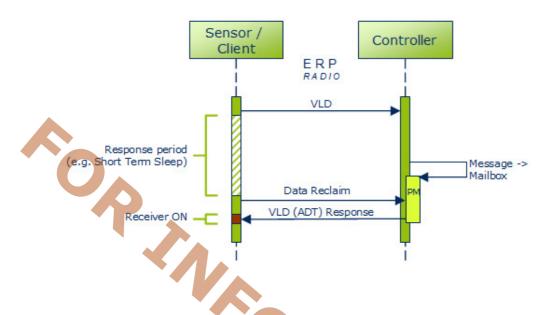
Response Timing:

If a response is requested this message shall be sent within a maximum of 500ms from the time of reception of the EEP Teach-In Query message. This limit shall give sufficient time to decide on the teach-in request and answer accordingly (e.g. when requests need to be processes by data base systems connected asynchronously).

TABLE OF 7 BYTE PAYLOAD:

Data	Value	Description							
DB_0DB_5		Same structure as Teach-In Query message (EEP, MID and channel of requesting device is echoed back)							
DB_6.BIT_7	0b0	Unidirectional communication (EEP operation)							
" Ob1		directional communication (EEP operation)							
DB_6.BIT_6	-	Not used							
DB_6.BIT_54	0b00	Request not accepted, general reason							
11	0b01	Request accepted, teach-in successful							
	0b10	Request accepted, deletion of teach-in successful							
"	0b11	Request not accepted, EEP not supported							
DB_6.BIT_30	0x1	Command identifier (CMD): EEP Teach-In Response							

3.7) Smart Ack: functional principle (without repeater)



Smart Ack is a bidirectional communication protocol between a self-powered device and a line-powered controller. Data transmission in both directions is controlled by the sensor/client, as the limited energy budget requires an exact synchronization of the sent and the received messages. This pre-defined time interval allows a very short activation of the energy-intensive receiver electronics on the client.

If the teach-in procedure has already taken place as in Chapter 'Smart Ack Teach-in procedure' and the two devices already 'know each other', communication always takes place as following under Smart Ack:

The client sends its message over a VLD telegram to the controller (Manufacturer ID = optional).

VLD									
RORG	Manufacturer ID	Variable data			Send	ler ID		Status	CRC8
D2	1,5 byte	1 12,5 bytes	- 1	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

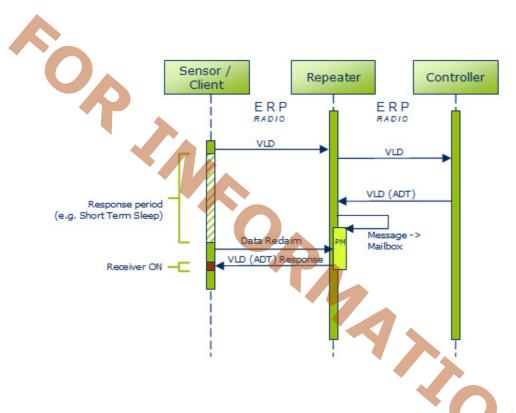
Finally, the message is processed in the controller, or forwarded to an external micro-controller over the serial interface for each use case. During the intervening period, the client is in the 'response period', which is frequently connected to an energy saving measure (like 'Short Term Sleep'). The length of this time period is agreed during the teach-in procedure between the devices as 'response time'. The feedback defined for the client is deposited in the mailbox of the postmaster (PM). When the client is active again, it requests this message containing the Smart Ack telegram DATA_RECLAIM from the responsible postmaster.

RORG		Send	ler ID		Status	СНСК				
A7	ID_3	ID_2	ID_1	ID_0	1Byte	1 Byte				
				ID_1 ID_0 1Byte 1 Byte bit 0 6: Mailbox Index bit 7: 1 = Message index 'Dat						

Finally, the receiver part of the client is activated and the message sent by the postmaster is accepted. In this case the VLD telegram is sent encapsulated as ADT telegram (= addressed).

ADT /	VLD												
RORG	RORG-EN	Manufacturer ID	Variable data	Destination ID		Sender ID			Status	CRC8			
A6	D2	1,5 byte	1 7,5 bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

3.8) Smart Ack: functional principle (with repeater)



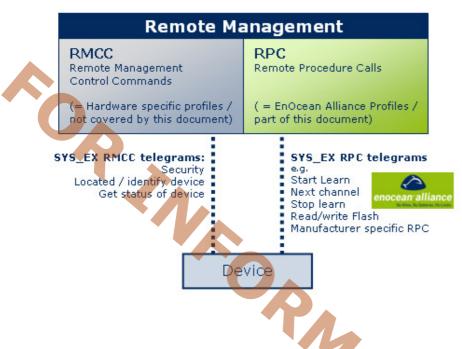
If a repeater is used, it takes over the task of the postmaster after the teach-in procedure. Hence, the client cannot view under operating conditions whether it is communicating directly with a controller or with a repeater.

The VLD telegram of the client is forwarded by the repeater 1:1 in the direction of the controller. The feedback is transferred in the form of an addressed telegram (containing Repeater ID) to the postmaster of the repeater and stored in the mailbox.

The client then turns to the repeater with its 'Data Reclaim', instead of turning to the controller, and requests the response message from the postmaster.

3.9) Remote Management / RPC

Remote Management allows EnOcean devices to be configured and maintained over the air or via a serial interface. For instance sensor or switch IDs can be stored or deleted from already installed actuators or gateways that are hard to access. There is a remote management library available for Dolphin based products.



Remote management is divided into two function groups:

RMCCs are mandatory features; they are permanently defined and they have overlapping tasks. They cannot be modified devicespecifically and are therefore, not an integral part of this description.

RPCs cover optional and manufacturer-specific features, and they have a flexible number of functionalities that can be used for numerous devices. If new device properties are mapped, RPCs can be extended correspondingly. To keep the RPCs interoperable, it is in the interest of the EnOcean Alliance to standardize these procedures.

The RPCs available today with their SYS_EX structures do not have any data-technical commonalities with EEP, but are to be handled the same way in future within the framework of coordination measures.

Structure of SYS_EX for RPC

SYS_EX telegrams for RPCs are generally encapsulated in an ADT telegram (RORG = A6) and are sent addressed as such.

ADT / S	SYS_EX	/ RPC										
RORG	RORG-EN	SYS-EX data		Destina	ation ID		Sender ID		Status	CRC8		
A6	C5	x bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

In the following section the SYS_EX data is described in detail. Note that Remote Management RPC commands are composed of several telegrams. That means SYS_EX data is than merged in one data block. The next section describes this datablock in detail.

For further details refer to the specification Remote Management, V1.7, Dec 16, 2010, released by EnOcean GmbH www.enocean.com/fileadmin/redaktion/pdf/tec_docs/RemoteManagement.pdf , please.

Title RPC - Remote learn

Function code	0x201
Manufacturerid	0x7FF
Datalength	0x04
Broadcast	YES
Addressable	YES
Answer	NO

Offset	Size	Data	Description	Valid	Range	Scale	Unit
0	24	(ORG-FUNC-TYPE)	Determines the device type to learn in, all other devices learn telegrams are ignored. To ignore EEP controll the mask bits has to be set to 0)				
24	8	Flag	learn flag, determines different behaviour of the learn procedure	0x00:	RESER\ Start le		
			0x01: 0x02: 0x03:	Next ch Stop lea			
				0x04:		CK - Sta learn mo	
				0x05:		CK - Sta ed learn	rt
				0x06:		CK - Sto	p

Title	RPC - Remote flash write
Function code	0x203
Manufacturerid	0x7FF
Datalength	0x04 + N
Broadcast	YES
Addressable	YES
Answer	NO

				mode	
				SmartACK - Stop	
				0x06: learn	
	Title		RPC - Remote fla	ish write	
Fund	ction c	ode	0x203		
Manu	Ifactu	rerid	0x7FF		
	taleng		0x04 + N		
Br	oadca	st	YES		
Add	lressa	ble	YES		
	this co		NO	device can be written.	
Jsing	this co	omma	nd the flash of a	device can be written.	
Jsing Offse	this co	omma	nd the flash of a Data	Description	
Jsing <mark>Offse</mark> D	this co et Size	omma Flash	nd the flash of a Data Memory Address	Description Destination where the data should be stored	
Jsing <mark>Offse</mark> 0 16	this co t Size 16 16	omma Flash	nd the flash of a Data	Description	
Using	this co t Size 16 16	omma Flash Numt	nd the flash of a Data Memory Address	Description Destination where the data should be stored Number of bytes to be transfered and written to the flash	
Using Offse 0 16	this co t Size 16 16	omma Flash Numt	nd the flash of a Data Memory Address	Description Destination where the data should be stored Number of bytes to be transfered and written to the flash	
Jsing <mark>Offse</mark> 0 16	this co test test test test test test test tes	Flash Numb Data	nd the flash of a Data Memory Address ber of Bytes	Description S Destination where the data should be stored Number of bytes to be transfered and written to the flash data to be transfered and written to the flash	
Jsing Offse 0 16 32	this cc 16 16 N*8	omma Flash Numt Data	nd the flash of a Data Memory Address ber of Bytes RPC - Remote fla	Description S Destination where the data should be stored Number of bytes to be transfered and written to the flash data to be transfered and written to the flash	
Using Offse 0 16 32 Fund	this co test test test test test test test tes	omma Flash Numt Data	nd the flash of a Data Memory Address ber of Bytes RPC - Remote fla 0x204	Description S Destination where the data should be stored Number of bytes to be transfered and written to the flash data to be transfered and written to the flash	

Title	RPC - Remote flash read
Inte	RPC - Remote Hash Teau
Function code	0x204
Manufacturerid	0x7FF
Datalength	0x04
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the flash can be read from the application. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash

Title	RPC - Remote flash read answer
Function code	0x804
Manufacturerid	0x7FF
Datalength	N
Broadcast	NO
Addressable	YES
Answer	NO

Offset	Size	Data	Description	
0	N*8	Data	data read from flash	
	itle		RPC - SmartACK read	l setting
Funct	ion c	ode	0x205	
Manuf	actu	r er id	0x7FF	
Data	aleng	th 📉	1	
Bro	adca	st	NO	
Addr	essa	ble	YES	
An	swe	r	YES	
	0 Funct Manuf Data Bro Addr	0 N*8 Title Function c Manufactur Dataleng Broadca Addressa	0 N*8 Data	0 N*8 Data data read from flash Title RPC - SmartACK read Function code 0x205 Manufacturerid 0x7FF Datalength 1 Broadcast NO Addressable YES

Using this command the SmartACK settings and learn tables can be read from the device. The Setting type filled determines what type of data is requested. The data requested data area transmitted in RPC telegrams.

0 8 >Setting type type of settings to read Enum: RESERVED 0x00: Mailbox settings 0x01: Learned sensor - read the ID table of sensors in the 0x02: Controller Title RPC - SmartACK read settings - Mailbox settings answer 0x805 Title RPC - SmartACK read settings - Mailbox settings answer Output Title RPC - SmartACK read settings - Mailbox settings answer Output Answer NO	Offset Size	Data	Description		Valid Range	Scale	Unit
Title RPC - SmartACK read settings - Mailbox settings answer Function code 0x805) 8	>Setting	type of settings to	Enum:			
Mailbox settings 0x01: Learned sensor - read the ID table of sensors in the 0x02: Controller Title RPC - SmartACK read settings - Mailbox settings answer Function code 0x805		type	read		RESERVED		
Ox01: Learned sensor - read the ID table of sensors in the 0x02: Controller Title RPC - SmartACK read settings - Mailbox settings answer Function code 0x805				0x00:			
Learned sensor - read the ID table of sensors in the 0x02: Controller Title RPC - SmartACK read settings - Mailbox settings answer Function code 0x805					Mailbox settings		
Title RPC - SmartACK read settings - Mailbox settings answer Function code 0x805				0x01:			
Title RPC - SmartACK read settings - Mailbox settings answer Function code 0x805						ID table of sensors	in the
Function code 0x805				0x02:	Controller		
Function code 0x805							
Function code 0x805							
Function code 0x805	Title		SmartACK road cottings	Mailbo	w cottings answer		
Punction code 0x805 Manufacturerid 0x7FF Datalength 4 Broadcast NO Addressable YES Answer NO					ox settings answer		
Datalength 4 Broadcast NO Addressable YES Answer NO							
Datalength4BroadcastNOAddressableYESAnswerNO							
BroadcastNOAddressableYESAnswerNO	Dataleng	yth	4				
AddressableYESAnswerNO	Broadca	st	NO				
Answer NO		ble	YES				
		DIE					
	Addressa		NO				
	Addressa		NO				×,
	Addressa		NO				
Offset Size Data Description	Addressa Answe	r	NO				Υ.

Title	RPC - SmartACK read settings - Mailbox settings answer
Function code	0x805
Manufacturerid	0x7FF
Datalength	4
Broadcast	NO
Addressable	YES
Answer	NO

Offset	Size	Data	Description
0	16	SmartACK flash address	Address where the SmartACK settings are stored
16	16	SmartACK mailbox count	number of mailboxes stored in flash

Title	RPC - SmartACK read settings - Learned sensor answer
Function code	0x806
Manufacturerid	0x7FF
Datalength	N*9
Broadcast	NO
Addressable	YES
Answer	NO

N - is the number of entries: SensorID, ControllerID, LearnCount

Offset	Size	Data
N*0	32	SensorID
N*32	32	ControllerID
N*64	8	Learned Count

RPC - SmartACK write settings
0x206
0x7FF
10
NO
YES
YES

Using this command different type of data can be transmitted to the SmartACK devices. This command is useful when the SmartACK device has to be configured remotely. The structure of the data transmitted is depends on the Operation Type field.

Operation Type = 0x01: Add mailbox (only controller)

	_				
Offset	Size	Data	Value	Descri	ption
0	8	Operatian Type	0x01	Add mailbox (or	nly controller)
8	8	Mailbox Index			
16	32	SensorID			107
48	32	PostmasterID			
Opera	ation	Type = 0x02	2: Dele	ete mailbox	
Offset	Size	Data	Value	Description	
0		Operation Type	0x02	Delete mailbox	
8		Mailbox Index			
16	64	Not Used $(= 0)$			
Opera	ation	Type = 0x03	8: Lea	rnIn - only co	ontroller
Offset	Size	Data	Value	Descripti	ion
	-	Operation Type		•	

Operation Type = 0x02: Delete mailbox

Offset	Size	Data	Value	Description
0	8	Operation Type	0x02	Delete mailbox
8	8	Mailbox Index		
16	64	Not Used $(= 0)$		

Operation Type = 0x03: LearnIn - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x03	LearnIn - only controller
8	8	Learn Count		
16	32	SensorID		
48	32	ControllerID		

Operation Type = 0x04: LearnOut - only controller

(Offset	Size	Data	Value	Description
(C	8	Operation Type	0x04	LearnOut - only controller

8	8	Learn Count	
16	32	SensorID	
48	32	ControllerID	

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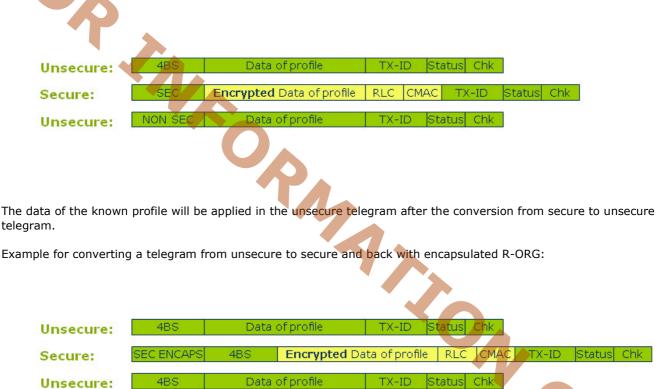
3.10) Interoperability with Security of EnOcean Networks

The Specification "Security of EnOcean Networks" defines two new telegram types for secure EnOcean telegrams in operational mode:

- R-ORG = 0x30 = SEC <u>Secure telegram</u>
- R-ORG = 0x31 = SEC_ENCAPS Secure telegram with R-ORG encapsulation

To make sure that interoperability is warranted, both telegrams may used for telegram transmission with existing EEP's. Because the profile of the device is known, the data of the SEC or SEC_ENCAPS telegram contains the same information as described in the profile, but it may be encrypted defined by the SLF (Security level format) of the device. When the device uses more than one R-ORG's in operational mode, the SEC_ENCAPS telegram has to be applied to ensure the correct original R-ORG after converting from secure to unsecure telegram. At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

Example for converting a telegram from unsecure to secure and back:



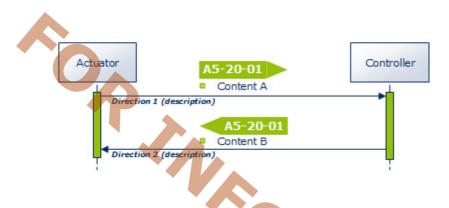
After conversion from secure to unsecure telegram, the encapsulated R-ORG will be applied in the telegram. The data of the profile of the encapsulated R-ORG will be applied.

3.11) Existing 'bidirectional' profile structures

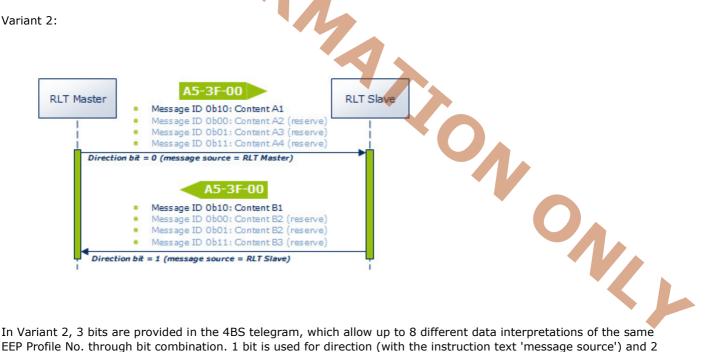
At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

The original terminology 'transmit mode / receive mode' was not taken over, as no unique assignment to device type and hence to transmission direction can be derived there from. A neutral number (Direction 1 / 2) or the state of a bit should allow the required free space to the individual application.

Variant 1:

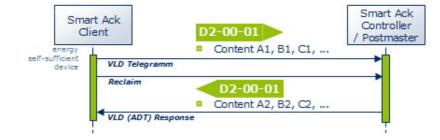


In Variant 1, there is no data-technical differentiation option in the 4BS telegram between Direction 1 and Direction 2, but only a documentation-related direction specification. No transmission direction can be detected if the telegrams are monitored on the radio stretch.



In Variant 2, 3 bits are provided in the 4BS telegram, which allow up to 8 different data interpretations of the same EEP Profile No. through bit combination. 1 bit is used for direction (with the instruction text 'message source') and 2 bits for the Message ID.

Variant 3:



In Variant 3, the Smart Ack technology normally offers multiple use options of bidirectional data transmission. Smart , can as with b. Ack clients can therefore be energy self-sufficient devices. The used VLD telegrams allow a payload of up to 14 bytes (12.5 bytes with Manufacturer ID). Contents can thus be structured more individually.

3.12) MSC telegram - Manufacturer Specific Communication

Communication over MSC telegrams can always be used when bigger data volumes are to be transmitted, and at the same time, a closed system structure is to be created. This can be the case if e.g., the controller system backbone is expanded to include radio components, or if safety-related controls require proprietary data structures.

Such communication must not affect any interoperable EEP-based communication and should be identifiable as MSC by any Dolphin-based hardware.

Interoperability Conditions:

A device using MSC in addition to other EEPs may be marked with the EnOcean ingredient logo, as long as it complies with the rules defined by the EnOcean alliance for such markings. A device using MSC may be marked with the EnOcean ingredient logo even though the manufacturer does not disclose any or all information regarding the MSC payload. However, all other functionality of such a device shall comply with the latest EEP specification and such a device shall support at least one additional EEP. The manufacturer must clearly state which EEP(s) the device complies with. To safeguard interoperability, if there is sufficient justified doubt within the EnOcean Alliance TWG, a specific unit using MSC can be assessed by the TWG and if found to breach the interoperability intentions, the TWG may then decide (majority vote) to adapt the rules for the usage of the interoperability logo.

The MSC telegram has the same structure as a VLD telegram. The only difference is that the RORG Number is different and the payload specification is missing.

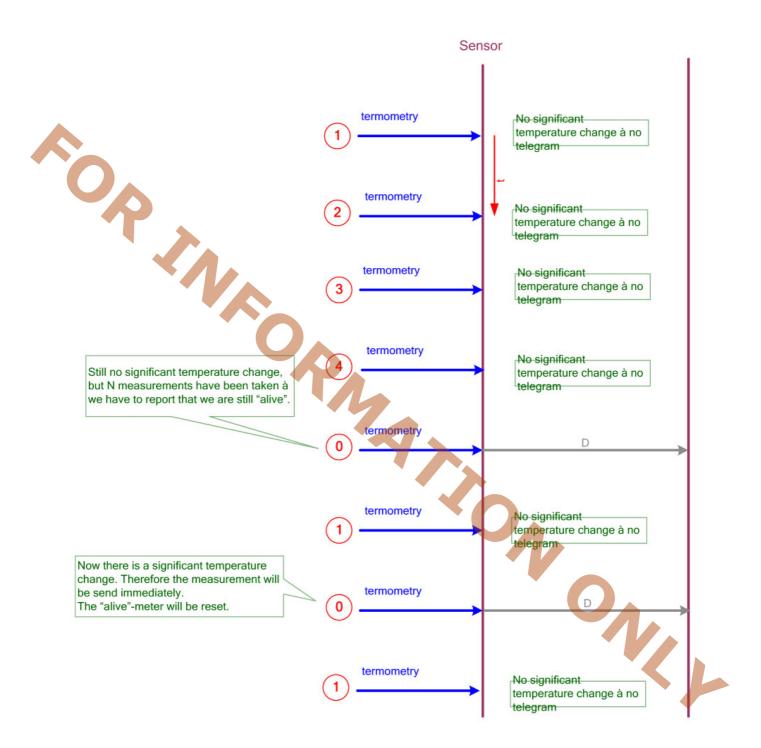
MSC									
RORG	Manufacturer ID		Variable data		Send	ler ID		Status	CRC8
D1	1,5 byte		1 12,5 bytes	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte
			ρ ,						

The following points are to be noted:

- 1. The usage of the Multi User Manufacturer ID (0x7FF) shall not be allowed.
- The dsage of the Multi oser Manufacturer ID (over 1 journated and international and inter

3.13) Use Cases for profile 2D-00-01 (self powered RCP for 2way operation)

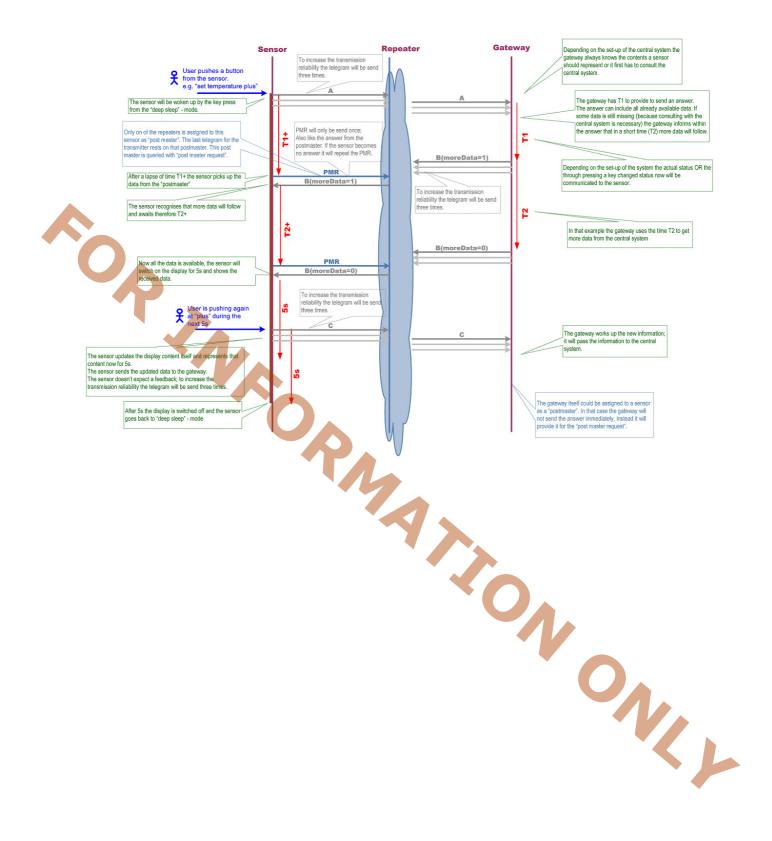
Use Case: Temperature Measurement



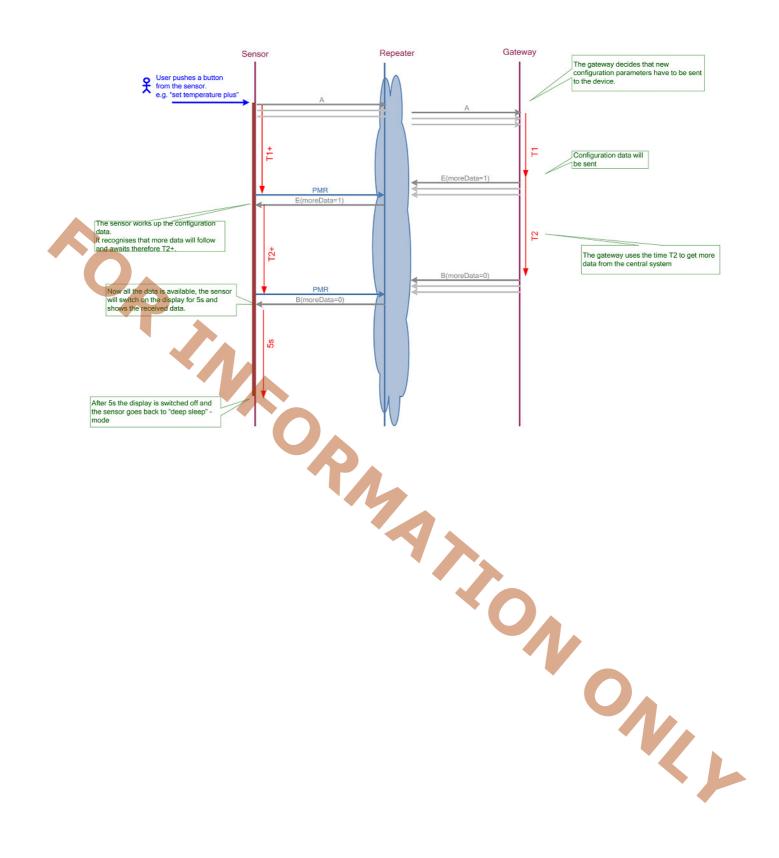
REMARK:

Temperature measurement may be configured by the Gateway, see chapter "Message Type E – RCP Configuration".

Use Case: User Interaction



Use Case: User Interaction including transfer of configuration data



3.14) Manufacturer ID's

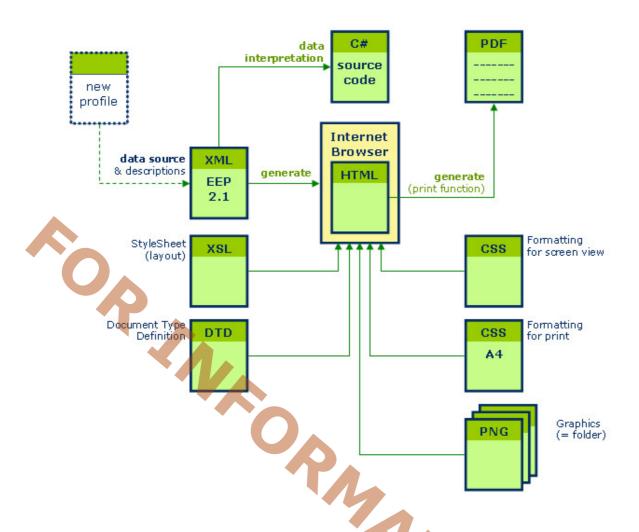
This chapter was transferred into a separate document entitled **EnOcean Manufacturer Identification (ManID)**. This document will be updated as soon as a new ManID will be allocated to a member of the EnOcean Alliance. The document **EnOcean Manufacturer Identification (ManID)** is stored in the webspace of the TWG on http://portal.enocean-alliance.org/MyWorkGroups/Documents.aspx (access only for registered members of the TWG).

3.15) XML + DOC Maintenance process



With EEP 2.1, a new type of documentation is introduced, which can also display logical structures next to the described contents. These can be adapted by developers into their programming environment.

XML is fully compatible with applications like C# or JAVA, and it can be combined with any application which is capable of processing XML irrespective of the platform it is being used on. If the application can work alongside XML, then XML can work on any platform and has no boundaries. It is also vendor independent and system independent.



Only the XML data is edited and released in defined time intervals as a total release under a new version. A styles sheet file (XSL) and formatting specifications (CSS) ensure that an attractive HTML representation is possible in an internet browser. The author of the new version also creates a final PDF file.

This method ensures that the document view, as well as the software environment, remain synchronized. Errors are strongly reduced and data maintenance is optimized.

3.16) Revision

Rev.	Date	Editor	Major Changes
0.10		GT	Initial EnOcean Alliance Version created, based on the EnOcean GmbH document "Standardization EnOcean Communication Profiles_v1.04"
0.90		TR	EEP for ORG = 0x05 added EEP for ORG = 0x06 added Headlines and Text formatted
0.91		TR	FUNC = 11 "Controller Status" added Proposals added: EEP 07-11-01 "Lightning Controller" (EchoFlex) EEP 07-02-0C "Temp.Sensor, Window Contact" (EchoFlex) EEP 07-10-0A "Temp. Sensor, Set-Point Adj., Window Contact" (EchoFlex) EEP 07-30-02 "Window Contact, Single Input" (EchoFlex)
0.92		TR	Manufacturer ID: Guidelines added. Definitions updated Revision History moved to a separate document chapter INPUT document for Berlin Meeting April 2009
2.0R		TR	EEP 07-02-0C shifted to Room Operating Panels -> EEP 07-10-0B EEP 06-00-00 renamed to 06-00-01 EEP 05-xx-xx (PRS telegram / PTM200) updated with results of latest discussions EEP 05-04-01 (Key Card Activated Switch) updated Proposals Added: EEP 07-10-0C "Temp. Sensor, Occupancy Control" (Termokon) EEP 07-10-0D "Temp. Sensor, Day/Night Control" (Termokon) Ratification info and period added
2.0	July 2009		Creation of final Version V2.0 EEP 05-03-02 added EEP 05-04-01 corrected EEP 06-00-01 renamed Single Input Contact EEP 07-10-0A and EEP 07-10-0B updated Single Input Contact EEP 07-30-01 and EEP 07-30-02 updated Single Input Contact 4BS teach in Telegram updated FUNC /TYPE Editorial corrections
	Nov 12, 2010	Ор	The EEP 2.0 document as well as all 2.1 single documents were transferred to an XML data structure and standardized. The following chapters were re-written: Introduction, Teach-in, Bi-directional profiles, Smart Ack, RPC and MSC. Profiles that are still being coordinated were also accepted. These are characterized as 'Not approved' in the document. Bidirectional profiles are labeled with 'BI-DIR'. RPS ORG 05 = RORG F6; 1BS ORG 06 = RORG D5; 4BS ORG 07 = RORG A5
	Dec 31, 2010	Ор	2th review
	Jan 20, 2011	Ор	Final Version V2.1
2.5		Ор	Review version 1 Added profiles: - 1 RPS: F6-02-03 - 16 4BS: A5-07-02, A5-09-02, A5-09-05, A5-09-06, A5-09-07, A5-10-1F, A5-11-03, A5-11-04, A5-14-01, A5-14-02, A5-14-03, A5-14-04, A5-14-05, A5-14-06, A5-38-08 CMD 0x07, A5-38-09 - 15 VLD: D2-01-0011, D2-01-0002 Updated profiles: A5-07-01, A5-09-01, A5-09-04 Further: - Description: UTE – Universal Uni- and Bidirectional Teach-in - RPC function no. added - Manufacturer ID's added
	Nov 08, 2012	Ор	Review version 2 Significant changes: - Chapter 1.3 - Add new profiles: A5-06-03, A5-07-03, A5-13-07 - Update of profiles: A5-10-15, A5-10-16, A5-10-17, A5-13-01, A5-13-05
	Feb 03, 2013	Ор	Significant changes: - Add new profiles: D2-03-00, D2-20-00, D2-20-01, D2-20-02 - Update of profiles: A5-07-02, A5-13-02, D2-01-00 - Deleted Chapter ´Manufacturer ID's´

2.5	March 04, 2013	Ор	 Final Version V2.5 Add chapter 3.14 "Manufacturer ID's" with a cross reference only Add chapter 3.10 "Interoperability with Security" Update profiles: A5-13-02 (name), A5-20-01 (first phrase), A5-38-08 / 0x02 Dimming (remark / ramp time), A5-38-09 (remark 7 / ramp time)
2.6 R1	Nov 26, 2013	Ор	Review version - Add 15 new profiles
2.6	Dec 17, 2013	Ор	Final Version V2.6

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